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Monterey, California



THESIS

COMPUTER PROGRAMS FOR HELICOPTER DATA DISPLAY
AND CONCEPTUAL DESIGN

by

Gary M. Bishop

December 1983

Thesis Advisor:

Donald M. Layton

Approved for public release, distribution unlimited

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Computer Programs for Helicopter Data Display
and Conceptual Design

by

Gary M. Bishop
Captain, United States Army
B.S., United States Military Academy, 1975

Submitted in partial fulfillment of the
requirements for the degree of

MASTER OF SCIENCE IN AERONAUTICAL ENGINEERING

from the

NAVAL POSTGRADUATE SCHOOL

December 1983

ABSTRACT

This thesis allows a person with access to a computer that uses the FORTRAN language and that is equipped with the DISSPLA software system the ability to select and graphically portray for analysis the critical design parameters of actual helicopters. It also allows a person with access to any computer that uses the FORTRAN language the ability to do a complete conceptual design of a helicopter at one sitting in accordance with the procedures in the Helicopter Design Manual published as course notes for the AE 4306 Helicopter Design course at the Naval Postgraduate School.

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I. INTRODUCTION

A. BACKGRCUND

The helicopter industry, as in most industries, incorporates many of the attributes of its previous designs into its new products. New aircraft are generally built upon the successes of previous designs with minor changes due to technological advances. These technological advances usually relate to new materials and new methods of control but hardly ever result in drastic changes to the aerodynamic surfaces. These proven designs of the integral parts which have specific aerodynamic characteristics are well documented and extremely useful in the design process. It is essential for the designer to have this corporate knowledge of design trends for the design process as well as for the validation of his design. This knowledge of design trends is necessary for both the designer in industry and the student in a learning environment.

Outside of specific helicopter companies, little has been done to analyze the interrelationships that exist between design parameters. These interrelationships provide a bases for the simplification of assumptions and validation of design results. This knowledge needs to be available to

the design student just as it is to the design engineer so that the information can be used for an analysis or verification during the design process. Therefore, it is important that this information be readily available and that the student have quick, easy and well defined access to this information.

The retrieval and analysis of historical data is but one part of the design process. The critical part is the actual process whereby a conceptual design is accomplished through many iterations. This process is long and involved but provides the design student with a basic understanding of the design process. For a more indepth study of the design process it is necessary for the student to vary as many of the design parameters as possible in order to see the interrelationships that exist. This process also allows the student to become intimately familiar with the problems and needs of the designer.

To date, no known programs for the IBM 3033 have been prepared that will take the design student through the entire process from historical analyses to conceptual design completion.

B. GOALS

The objective of this study was to develop an interactive capability for the design student using the IBM 3033 computer. The program, if used at the Naval Postgraduate School, should be capable of providing graphical representations of the critical data necessary for a proper analysis in the data analysis phase. During the conceptual design phase the program should allow for design student/computer interaction so that the design student can readily see the effects of varying critical parameters. To maximize the assets available at the Naval Postgraduate School, the Tektronix 618 dual screen system and the DISSPLA [Ref. 1] software system should be incorporated in the structuring of the computer programs.

The programs should be designed primarily for the use of Aeronautical Engineering students at the Naval Postgraduate School enrolled in the Helicopter Performance, Helicopter Design, and Advanced Helicopter Design courses.

II. APPROACH TO THE PROBLEM

A. INTRODUCTION

The basic approach was to write two computer programs utilizing the DISSPLA software system for use on the IBM 3033 using FORTRAN IV. The programs are completely interactive, prompting the user for all necessary information and then graphically depicting the information in the form of tables on the IBM 3278 screen or as a graph on either the Tektronix 618 screen or by use of the VERSATEC plotter. If the Tektronix machine is used, the displayed graph can be copied directly using electrostatic copiers attached to each machine.

B. ANALYSIS OF HELICOPTER DESIGN DATA

The first program consists of a historical data display system that takes thirty critical design parameters and allows the user to select the parameters for analysis. The user can then specify the page format as well as the number of graphs per page of the finished graph. Subroutines within the program are as follows:

1. Block data
2. Data point identification
3. Graphical display formatting

C. CONCEPTUAL HELICOPTER DESIGN

The second program is written to correspond procedurally WITH THE Helicopter Design Manual [Ref. 2] used in the AE 4306 Helicopter Design course at the Naval Postgraduate School. The formulae necessary for the computation of each section is provided in lieu of subroutine use. This allows for quick and easy updating of the program as it becomes necessary. Also, if the student desires, it can be seen how the data that is received is computed. This program is completely interactive and requires only that the student have the information listed on the design specification sheet and the accompanying charts and references necessary for the required decisions during the design process. All tables and graphs are generated and displayed either on the IBM 3278 screen or the Tektronix 618 screen. Output for the tabular data is provided on a separate file and the single graph needed for design decisions can be obtained using the electrostatic printers.

Detailed knowledge of the IBM 3033 computer is not necessary. A familiarity of helicopter aerodynamics and performance is, however, necessary for proper utilization of the program in order to obtain meaningful design information.

III. SOLUTIONS TO THE PROBLEMS

A. DATA DISPLAY PROGRAM

Table I lists the thirty critical design parameters used most often in any analysis of an aircrafts performance as found in the Helicopter Performance Manual [Ref. 3].

TABLE I

Design Parameters

Main rotor radius
Tail rotor radius
Number of main rotor blades
Number of tail rotor blades
Height of the main rotor system
Speed of the main rotor
Speed of the tail rotor
Chord of the main rotor
Chord of the tail rotor
Span of the main rotor
Span of the tail rotor
Twist of the main rotor blade
Twist of the tail rotor blade
Profile drag of the main rotor blade
Profile drag of the tail rotor blade
Disc loading of the main rotor system
Width of the fuselage
Length of the fuselage
Frontal equivalent flat plate area
Vertical equivalent flat plate area
Maximum forward velocity
Maximum range
Rate of climb
Hover ceiling (IGE)
Hover ceiling (OGE)
Length of the tail
Operating weight
Load weight
Fuel weight
Maximum gross weight

The above parameters have been deemed those most critical to the design process. The airfoil data has been extrapolated from NACA data and the specific helicopter

performance parameters have been extrapolated from the various manuals for the specific helicopters. Tables III through X, Appendix C, list the specific data utilized for the study.

Table II lists the helicopters used for the analysis portion of the graphing.

TABLE II
Representative Helicopters

<u>Military Designator</u>	<u>Weight Classification</u>	<u>Branch of Service</u>
AH-64	Medium	USA
OH-6A	Light	USA
SH-3H	Medium	USN
S-76	Medium	USN
UH-60A	Medium	USA/USN
CH-54B	Heavy	USA
CH-53D	Heavy	USN
CH-53E	Heavy	USN

All the helicopters selected for study were single main rotor helicopters that are still in the active inventories of the agencies listed. The selections were made with deference to aircraft of the U.S. Army and U.S. Navy and then to a representative sampling of the three major weight classifications.

The data from Tables III through X can now be graphed in the following combinations using the Data Display program:

1. Simple X-Y plot

- a. Horizontal page format (11 X 8.5 inches)
- b. Vertical page format (8.5 X 11 inches)
2. Two parameters versus a third
 - a. Horizontal page format (11 X 8.5 inches)
 - (1) Two axes on the abscissa scale
 - (2) Two axes on the ordinate scale
 - b. Vertical page format (8.5 X 11 inches)
 - (1) Two axes on the abscissa scale
 - (2) Two axes on the ordinate scale
3. Two X-Y plots on the same page with a horizontal page format
4. Three parameters versus one common parameter with a vertical page format
5. Four separate X-Y plots on the same page with a horizontal page format

Figures 3.1. through 3.9., Appendix C, illustrate the capability of the program. The program was devised so as to allow the greatest flexibility for the analyst as to the graphical presentation.

B. CONCEPTUAL DESIGN PROGRAM

The design process is in accordance with the procedural steps as outlined in the Helicopter Design Manual. The

program is devised so as to allow the design student the ability to do a complete conceptual design at one sitting if he is properly prepared. The program lists all critical tables and information necessary for doing an analysis of the design and also provides the necessary information to prepare a written report. If the Tektronix dual screen combination is used, the student has a graphical representation of the total power curve at altitude presented to him which must be used to extrapolate critical design performance parameters. Figure 3.10. is a sample of the graphical representation provided. Sample output is provided in Appendix B to illustrate the capabilities of the program and the possible usefulness to the design student.

IV. RESULTS AND CONCLUSIONS

A. DATA DISPLAY PROGRAM

This program provided good results in use for the analyses of the design parameters considered, particularly in the correlation between commonly used 'rules of thumb' and graphical analyses of the same parameters.

The capability of the program could be enhanced in several ways. First, additional single main rotor helicopters could be added to enable a more complete analysis to be accomplished. Second, the use of different scales, such as the logarithmic scale, for the graphical analysis could prove to be more suitable for some of the parameters. Third, additional parameters that other companies have compiled in their technical manuals could be added for analysis.

B. CONCEPTUAL DESIGN PROGRAM

This program provided information consistent with existing aircraft. The interactive characteristic of the program allows the student to actively participate in the design process and, most importantly, the program allows the student to vary parameters and see the effects of changing a

single parameter on the entire design process. If the student was prepared and had all the appropriate references, this process need only take an hour to complete one iteration of the entire process. This allows for multiple iterations, optimization, and parameter variation.

One problem with the program is that it is only as good as the assumptions that have been made for the model to simplify the formulae used as given in Reference 3. A crude approximation to existing aircraft can be made with the understanding that the aircraft designed during this process is merely a conceptual design and the beginning step in the process for the final product. This model has been developed so that changes made to the course can be incorporated easily and that any corrections can be made quickly. This program also can be run on any FORTRAN capable computer using the coding listed in Appendix B.

APPENDIX A

A. USERS GUIDE TO THE DATA DISPLAY PROGRAM

The program has been written with the user in mind. It is completely interactive once the program has been loaded into the DISSPLA mode so that the user need only read the instructions presented on the screen carefully.

Use the following procedure to invoke the Data Display program once the Fortran program resides on the users disk.

1. Logon as normal at either a regular IBM 3278 terminal or at a Tektronix 618 dual screen terminal
2. Obtain the use of temporary storage space by entering the following:

DEFINE STORAGE 1M (enter)

3. When the PSW '00020000 00000000' appears on the screen type in:

I CMS (enter)

4. If the program has not been previously compiled on your disk type in:

FORTGI HELODATA (enter)

5. When the program has been compiled you are ready to enter into DISSPLA by typing in:

DISSPLA HELODATA (enter)

6. Follow the instructions given on the screen. If you desire a hard copy of the graphs do the following:

IBM terminal--Exit the program and
enter DISSPOP and then
follow the instructions

TEK terminal--Press the hard copy button
on the large monitor

B. PROGRAM NOMENCLATURE

<u>MNEMONIC</u>	<u>DEFINITION</u>
ANS	General variable for reading keyboard answers
B	Number of main rotor blades
BTR	Number of tail rotor blades
C	Chord of a main rotor blade in feet
CDO	Profile drag of a main rotor blade section
CDOTR	Profile drag of a tail rotor blade section
CTR	Chord of a tail rotor blade in feet
DL	Disc loading of the main rotor system
FH	Frontal effective flat plate area in square feet
FV	Vertical effective flat plate area in square feet
FWT	Fuel weight in pounds
HOVIGE	Hover ceiling (in ground effect) in feet
HOVOGE	Hover ceiling (out of ground effect) in feet
HT	Height of the main rotor system above the ground in feet
I	Do loop variable
IPAK	Array for packing legend information
KINDS	Array for packing legend information
LGH	Length of the fuselage in feet
LT	Length of the tail in feet

LWT	Load weight in pounds
MGW	Maximum gross weight in pounds
OPTION	Term used in Switch subroutine for page formatting
OWT	Operating weight in pounds
PANS	References page format selection
R	Main rotor radius in feet
RC	Maximum rate of climb in feet per minute
RNG	Maximum range in nautical miles
RPM	Speed of the main rotor system in RPM
RPMTR	Speed of the tail rotor system in RPM
RS	Span of a main rotor blade in feet
RSTR	Span of a tail rotor blade in feet
RTR	Tail rotor radius in feet
TEMP1	Dummy parameter returned from subroutine
TEMP2	Dummy parameter returned from subroutine
TEMP3	Dummy parameter returned from subroutine
TITALT	Program trip used in multiple axes plotting
TWOAX	References which axis has two axes plotted
TWST	Twist of a main rotor blade in degrees
TWSTR	Twist of a tail rotor blade in degrees
VM	Maximum velocity in knots
WDT	Width of the fuselage in feet
X	Array returned from Switch subroutine containing abscissas for plotting

XANS	Answer referenced to X axis selection
XANS1	Answer referenced to multiple X axes selection
XANS2	Answer referenced to multiple X axes selection
XMAX	Maximum value of abscissa desired for plotting
XORIG	Minimum value of abscissa desired for plotting
XPOS	Array of values referencing subplot locations of abscissas
XSTP	Increment size between minimum and maximum of the abscissa axis
XTWO	Array returned from Switch subroutine containing abscissas for plotting
X2ANS	Array for X axis answers for two graph option
X4ANS	Array for X axis answers for four graph option
Y	Array returned from Switch subroutine containing ordinates for plotting
YANS	Answer referenced to Y axis selection
YANS1	Answer referenced to multiple Y axes selection
YANS2	Answer referenced to multiple Y axes selection
YMAX	Maximum value of abscissa desired for plotting
YORIG	Minimum value of ordinate desired for plotting
YPOS	Array of values referencing subplot locations of ordinates
YSTP	Increment size between minimum and maximum of the abscissa axis
YTWO	Array returned from Switch subroutine containing ordinates for plotting
Y2ANS	Array for Y axis answers for two graph option
Y3ANS	Array for Y axis answers for three graph option

Y4ANS Array for Y axis answers for four graph option
Z Array in subroutine switch for parameters

C. PROGRAM LISTING

```

REAL R(8), RTR(8), B(8), BTR(8), HT(8), RPM(8), RPMTR(8), C(8), CTR(8)
REAL RS(8), RSTR(8), TWST(8), TWSTTR(8), CDO(8), CDOTR(8), DL(8)
REAL HVOGE(8), LGH(8), FH(8), FV(8), VM(8), RNG(8), RC(8), HOVI GE(8)
REAL YORIG(8), LT(8), OWT(8), LWT(8), FWT(8), MGW(8)
REAL YANS2, YANS2, TITALT, TWOAX, ANS, PANS, XTWO
2(8), YTW(8), TEMP1, TEMP2, TEMP3, XPOS(9), YPOS(9), Y3ANS(3), X4ANS(4), Y4
3ANS(4), X2ANS(2), Y2ANS(2), X(8), Y(8)
INTEGER I, KINDS(200), IPAK(200)
DATA XPOS/1.5, 6.5, 1.1, 1.1, 1.1, 6.5, 1.1, 6.5, 1.1, 6.5/
DATA YPCS/1.1, 1.1, 3.75, 6.5, 1.1, 1.1, 4.4, 1.1, 4.4, 1.1/
COMMON /C1/ R, RTR, B, BTR, HT, RPM, RC, CTR, RS, RSTR, TWST, TWSTTR, CDO
1, CDOTR, CL, WCT, LGH, FH, FV, VM, RNG, RC, HOVI GE, HVOGE, LT, OWT, LWT, FWT, MGW
C THIS SECTION DETERMINES WHICH TYPE OF TEKTRONIX EQUIPMENT THAT YOU
C ARE USING AND MAKES THE APPROPRIATE CALLS TO BRING THE SYSTEM ON
C LINE
C ***** CLRS CRN 6 *****
CALL FRTCMS (' CLRS CRN 6')
WRITE (6, 37C)
WRITE (6, 38C)
READ (5, *) ANS
IF (ANS.NE.1.) GO TO 360
CALL FRTCMS (' CLRS CRN 6')
WRITE (6, 39C)
READ (5, *) ANS
CALL FRTCMS (' CLRS CRN 6')
IF (ANS.NE.1.) GO TO 10
CALL TEK618
GO TO 30
IF (ANS.NE.2.) GO TO 20
CALL TEKALL (4662, 30, 31, 1, 0)
GO TO 30
IF (ANS.NE.3.) GO TO 340
CALL CCMPRS
CONTINUE
CALL SWISSL ('BLACK')
CALL SEICLR (1)
CALL HEIGHT
C THIS PORTION PACKS THE INFORMATION INTO AN ARRAY SO THAT A STORY
C CAN BE PRINTED CNTO EACH GRAPH WITH THE MEANING OF THE NUMBERS THAT
C LABELS GIVE FOR EACH PLOT
C ***** CLRS CRN 6 *****
CALL LINES (1. AH-64 5. UH-60A$, KINDS, 1)

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CALL LINES (2, OH-6A, 6, CH-54B$, KINCS, 2)
CALL LINES (3, SH-3H, 7, CH-53D$, KINCS, 3)
CALL LINES (4, S-76, 8, CH-54E$, KINCS, 4)
CALL MARKER (15, HEIGHT)
CALL SHCCHR (90, 1, 0.002, 1)
CALL HWSCL (SCREEN)
C** THIS SECTION ALLOWS THE USER TO SELECT IF THEY WANT 1 GRAPH, 2 SAME
C** GRAPHS HORIZONTALLY SIDE BY SIDE, 3 GRAPHS VERTICALLY WITH THE SAME
C** X AXIS OR FCUR GRAPHS ON THE SAME PAGE.
C** WRITE (6, 40C)
READ (5, 1C)
CALL FRICMS (CLRCRN 6)
IF (ANS.NE.1) GO TO 280
C** THIS SECTION PRESENTS THE 30 DIFFERENT PARAMTERS THAT CAN BE USED IN
C** COMPARISONS AND ALLOWS THE USER TO SELECT UP TO 3 FOR COMPARISON
C** TOTAL=C.O
WRITE (6, 41C)
READ (5, 1C)
CALL FRICMS (CLRCRN 6)
C** ONLY 2 PARAMETERS ARE SELECTED, A CHOICE OF PAGE FORMAT IS GIVEN
C** IF AND A CHOICE OF WHICH PARAMTER IS TO BE ON WHICH AXIS IS GIVEN
C** SUBROUTINES ARE CALLED WHICH CHANGE THE PARAMTER SELECTED VALUES INTO
C** VALUES TO BE PLOTTED ALONG WITH THEIR RESPECTIVE PLOTTING INFORMATION
C** IF (ANS.NE.2) GO TO 60
WRITE (6, 43C)
READ (5, 1C)
CALL FRICMS (CLRCRN 6)
IF (ANS.NE.1) GO TO 40
WRITE (6, 54C)
READ (5, 1C)
IF (ANS.NE.1) GO TO 340
CALL FRICMS (CLRCRN 6)
CALL AREA2D (11, 8.5)
CALL HEIGHT (9, 6)
CALL HEIGHT (3)
CALL MEASHT (HEIGHT)
CALL MEASHT (AE 4306/4900$, 100, 1.2, 6.25)
CALL MEASHT (1)
CALL HEIGHT (KINCS, 4, 7.25, 6.25)

```



```

CALL TO RESET ('HEIGHT')
GO TO 50
IF (ANS.NE.2.) GO TO 340
WRITE (6,55C)
WRREAD (5,*) ANS
IF (ANS.NE.1.) GO TO 340
CALL PAGECT ('CLRSCRN 6')
CALL PAGECT ('E.5,11.')
CALL HWRROT ('AUTO')
CALL AREAD2D ('6.,8.')
CALL AREAD2D ('3')
CALL HEIGHT ('HELI COPTER DESIGN$', -100,0.,8.5)
CALL MEESAG ('HEIGHT')
CALL MEESAG ('AE 4306/4900$', 100,1.2,8.25)
CALL LSTORY (KINDS,4,4.25,8.25)
CONTINUE
WRITE (6,41C)
WRITE (6,44C)
READ (5,*) XANS,YANS
CALL FRAME ('CLRSCRN 6')
CALL FRAME ('NCENDS')
CALL XAXEND ('NCENDS')
CALL YAXEND ('NCENDS')
CALL SWITCH (XANS,1.,X,XORIG,XSTP,XMAX)
CALL SWITCH (YANS,2.,Y,YORIG,YSTP,YMAX)
CALL SWATCH (XORIG,XSTP,XMAX,YORIG,YSTP,YMAX)
CALL GRESET ('XTICKS')
CALL GRESET ('YTTICKS')
CALL RESEVE (X,Y,8,-1)
CALL CURVEL (X,Y)
CALL LABEL (X,Y)
TITLE=0.0
GO TO 180

```

```

CC** SINCE 3 PARAMETERS WERE CHOSEN, THE USER IS GIVEN A CHOICE OF PAGE
CC** SCALES LOCATED IN SUBROUTINE OR VERTICALS ARE USED WHICH PROVIDE A SELECTION
CC** OF DESIRED PARAMETERS AND CALL THEIR SET OF DATA FOR ONE AXIS MUST BE
CC** VALUES TO BE PLCTED. A SECOND LEVEL REQUIREMENTS, A VARIABLE
CC** HAS BEEN DESIGNATED TO TRIP A LATER SUBROUTINE WHERE THE ADDITIONAL
CC** CALL TO A SUBROUTINE FOR ADDITIONAL AXES CAN BE MADE
CC** CONTINUE
CC** CALL HMYLGHT (,1,1)
CC** CALL HMYEGLR (,RED,1)
CC** CALL LINES (,PRIMARY,1)
CC** CALL SETCLR (,GREEN,1)

```



```

CALL LINES ('SECONDARY AXES$', IPAK, 2)
CALL LSETCLR ('BLACK')
CALL RESET ('HEIGHT')
IF (ANS.NE.3) GO TO 340
WRITE (6, 430)
READ (5, #) PANS
CALL FRTCMS ('CLRSCRN 6')
WRITE (6, 450)
READ (5, #) TWOAX
CALL FRTCMS ('CLRSCRN 6')
IF (PANS.NE.1) GO TO 70
IF (TWOAX.NE.1) GO TO 110
GO TO 90
IF (PANS.NE.2) GO TO 340
IF (TWOAX.NE.1) GO TO 80
GO TO 130
IF (TWOAX.NE.2) GO TO 340
GO TO 150
CONTINUE
WRITE (6, 560)
READ (5, #) ANS
IF (ANS.NE.1) GO TO 340
CALL FRTCMS ('CLRSCRN 6')
WRITE (6, 410)
WRITE (6, 460)
READ (5, #) XANS1, XANS2, YANS
CALL FRTCMS ('CLRSCRN 6')
CALL PAGE (11, 8.5)
CALL PHYSOR (1.5, 2)
CALL AREA2D (9, 5)
CALL HEIGHT (.3)
CALL MESSAGE ('HEIGHT')
CALL MESSAGE ('AE 4306/4900$', 100, 1.2, 5.25)
CALL MESSAGE ('KINDS, 4, 7.25, 5.25')
CALL LSTCRY (XANS1, 1, X, XORIG, XSTP, XMAX)
CALL SWITCH (YANS, 2, Y, YORIG, YSTP, YMAX)
DO 100 I=1, 5
YTWO(I)=Y(I)
CONTINUE
TTT=1.0
GO TO 170
CONTINUE
WRITE (6, 570)
READ (5, #) ANS
IF (ANS.NE.1) GO TO 340
CALL FRTCMS ('CLRSCRN 6')
WRITE (6, 410)

```

70

80

90

100

110


```

WRITE (6,47C)
READ (5,*) XANS,YANS1,YANS2
CALL FRICMS (.CLRSCRN 6,)
CALL PAGE (11,.8.5)
CALL PHYSOR (2.5,1.0)
CALL AREA2D (7.5,6.)
CALL HEIGHT (.3)
CALL MESSAG (.HELICOPTER DESIGN$, -100,0.,6.5)
CALL MESSAG (.HEIGHT,)
CALL MESSAG (.AE 4306/4900$, 100,1.2,6.25)
CALL LSTORY (KINDS,4,5.75,6.25)
CALL SWITCH (XANS,1.,X,XORIG,XSTP,XMAX)
CALL SWITCH (YANS1,2.,Y,YORIG,YSTP,YMAX)
DO 120 I=1,E
XTWO(I)=X(I)
CONTINUE
TITALT=2.0
GO TO 170
120 CONTINUE
WRITE (6,58C)
READ (5,*) ANS
IF (ANS.NE.1.) GO TO 340
CALL FRICMS (.CLRSCRN 6,)
WRITE (6,410)
WRITE (6,46C)
READ (5,*) XANS1,XANS2,YANS
CALL FRICMS (.CLRSCRN 6,)
CALL PAGE (8.5,11.)
CALL HWFUT (.AUTO,)
CALL PHYSOR (1.5,2.)
CALL AREA2D (6.5,7.5)
CALL HEIGHT (.3)
CALL MESSAG (.HELICOPTER DESIGN$, -100,0.,8.)
CALL MESSAG (.HEIGHT,)
CALL MESSAG (.AE 4306/4900$, 100,1.2,7.75)
CALL LSTORY (KINDS,4,4.75,7.75)
CALL SWITCH (XANS1,1.,X,XORIG,XSTP,XMAX)
CALL SWITCH (YANS,2.,Y,YORIG,YSTP,YMAX)
DO 140 I=1,E
YTWO(I)=Y(I)
CONTINUE
TITALT=3.0
GO TO 170
140 CONTINUE
WRITE (6,59C)
READ (5,*) ANS
IF (ANS.NE.1.) GO TO 340
CALL FRICMS (.CLRSCRN 6,)

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160 WR ITE (6,41C)
    WR ITE (6,47C) >ANS,YANS1,YANS2
    READ (5,CMS) (<CLRSCRN 6<)
    CALL PAGE (8,5,11<)
    CALL HWRROT (<AUTO<)
    CALL PHYSOR (2.25,1.0)
    CALL AREA2D (5.75,8.0)
    CALL HEIGHT (<3)
    CALL MESSAG (<HEIGHT>)
    CALL MESSAG (<AE 4306/4900$>,100,1.2,8.25)
    CALL MESSAG (KINDS 4,4.8.25)
    CALL LSTCRY (XANS,1.0,X,XORIG,XSTP,XMAX)
    CALL SWITCH (YANS1,2.0,Y,YORIG,YSTP,YMAX)
    DO 160 I=1,8
    XTWO(I)=X(I)
    CONTINUE
    TITALT=4.0
    GO TO 170
170 CONTINUE
C *****
C NORMAL DISPLA ***** CALLS TO ESTABLISH THE STYLE OF WRITING, PUTTING A
C BORDER AROUND THE SUBPLOT AREA, MAKING A GENERIC HEADING, SUPPRESSING
C PRINTED VALUES AT THE ENDS OF THE AXES OF THE GRAPH, CALLING THE CURVE
C AXES, THEIR INCREMENT AND THEIR VALUES TO BE DRAWN, CALLING THE LABELS THE
C THAT PLOTS ONLY A MARKER AND THEN CALLING A ROUTINE *****
C MARKERS BY THE TYPE OF AIRCRAFT *****
C *****
    CALL SETCLR (<RED>)
    CALL FRAME
    CALL XAXEND (<NCENDS>)
    CALL YAXEND (<NOENDS>)
    CALL GRAF (XORIG,XSTP,XMAX,YORIG,YSTP,YMAX)
    CALL RESET (<XTICKS>)
    CALL RESET (<YTIKS>)
    CALL CURVE (X,Y,8,-1)
    CALL LABEL (X,Y)
    CALL RESET (<HEIGHT>)
C *****
C SECONDARY AXIS IS DRAWN WITH APPROPRIATE TITLE AND VALUES AND THEN A
C PLOT OF THE NEW POINTS IS MADE AND THEIR POINTS LABELLED *****
C *****
180 CONTINUE
    IF (TITALT.NE.0.0) GO TO 190
    GO TO 350
190 IF (TITALT.NE.1.0) GO TO 200
    CALL SWITCH (XANS2,3.0,XTWO,TEMP1,TEMP2,TEMP3)

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200 GO TO 230
    IF (TITALT.NE.2.0) GO TO 210
    CALL SWITCH (YANS2,4.,YTWO,TEMP1,TEMP2,TEMP3)
    GO TO 230
210 IF (TITALT.NE.3.0) GO TO 220
    CALL SWITCH (XANS2,5.,XTWO,TEMP1,TEMP2,TEMP3)
    GO TO 230
220 CONTINUE
    CALL SWITCH (YANS2,6.,YTWO,TEMP1,TEMP2,TEMP3)
    GO TO 230
230 CONTINUE
    CALL SETCLR ('GREEN')
    CALL MARKE (16)
    CALL CURVE (XTWO,YTWO,8,-1)
    CALL LABEL (XTWO,YTWO)
    CALL RESET ('HEIGHT')
    IF (TITALT.NE.1.) GO TO 240
    CALL LEGEND (IPAK,2.0,2,4.5)
    GO TO 270
240 IF (TITALT.NE.2.) GO TO 250
    CALL LEGEND (IPAK,2.0,2,5.5)
    GO TO 270
250 IF (TITALT.NE.3.) GO TO 260
    CALL LEGEND (IPAK,2.0,2,7.)
    GO TO 270
260 IF (TITALT.NE.4.) GO TO 340
    CALL LEGEND (IPAK,2.0,2,7.5)
    GO TO 270
270 CONTINUE
    CALL RESET ('MARKER')
    GO TO 350
C*****
C THIS SECTION ALLOWS THE USER TO SELECT 2 SEPARATE GRAPHS ON THE
C SAME PAGE CN A HORIZONTAL PAGE FORMAT.
C*****
280 IF (ANS.NE.2.) GO TO 340
    WRITE (6,48C)
    READ (5,*) ANS
    CALL FRTCMS ('CLRSCRN 6')
    IF (ANS.NE.2.0) GO TO 300
    WRITE (6,60C)
    READ (5,*) ANS
    IF (ANS.NE.1.) GO TO 340
    CALL FRTCMS ('CLRSCRN 6')

C
    WRITE (6,41C)
    WRITE (6,49C)
    READ (5,*) X2ANS(1),Y2ANS(1),X2ANS(2),Y2ANS(2)

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CALL FRTCMS ('CLRSCRN 6')
CALL PAGEA2D (11.,8.5)
CALL HEIGHT (9.,6.)
CALL MESSAG ('HELICOPTER DESIGN$',-100,0.25,6.5)
CALL RESET ('HEIGHT')
CALL MESSAG ('AE 4306/4900$',100,1.45,6.25)
CALL MESSAG ('KINDS,4,7.5,6.25')
CALL LENDGR (0)
DO 290 I=1,2
CALL SETCLR ('RED')
CALL PHYSOR (XPOS(1),YPOS(1))
CALL AREA2D (3.85,6.)
CALL FRAME (14)
CALL HEIGHT (X2ANS(1),1.,X,XORIG,XSTP,XMAX)
CALL SWITCH (X2ANS(1),2.,Y,YORIG,YSTP,YMAX)
CALL XAXEND ('NCENDS')
CALL YAXEND ('NOENDS')
CALL GRAF ('XORIG,XSTP,XMAX,YORIG,YSTP,YMAX')
CALL RESET ('XTICKS')
CALL RESET ('YTTICKS')
CALL CURVE (X,Y,8,-1)
CALL LABEL (X,Y)
CALL LENDGR (0)
CONTINUE
290 CALL SETCLR ('BLACK')
GO TO 350
C***** THIS SECTION ALLOWS THE USER TO PUT 3 GRAPHS WITH A COMMON X AXIS *****
C ON ONE VERTICAL PAGE PLACED ONE ON TOP OF THE OTHER. *****
C***** IF (ANS.NE.3.0) GO TO 320 *****
300 WRITE (6,61C)
READ (5,#) ANS
IF (ANS.NE.1.) GO TO 340
CALL FRTCMS ('CLRSCRN 6')
WRITE (6,41C)
WRITE (6,50C)
READ (5,#) Y3ANS(1),Y3ANS(2),Y3ANS(3)
CALL FRTCMS ('CLRSCRN 6')
CALL HWRGT ('AUTO')
CALL PAGEA2D (8.5,11.)
CALL AREA2D (7.,7.)
CALL HEIGHT (3)
CALL MESSAG ('HELICOPTER DESIGN$',-100,0.,8.)
CALL RESET ('HEIGHT')
CALL MESSAG ('AE 4306/4900$',100,1.2,7.75)

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CALL LSTCRY (KINDS,4,5.25,7.75).
CALL LENDGR (0)
CALL SETCLR ('GREEN')
CALL PHYSOR (XPOS(3),YPOS(3))
CALL AREA2D (7.,2.5)
CALL FRAME
CALL SWITCH (XANS,1.,X,XORIG,XSTP,XMAX)
CALL HEIGHT (.10)
CALL SWITCH (Y3ANS(1),2.,Y,YORIG,YSTP,YMAX)
CALL XAXEND ('NOENDS.')
CALL YAXEND ('NOENDS.')
CALL GRAF (XORIG,XSTP,XMAX,YORIG,YSTP,YMAX)
CALL CURVE (X,Y,8,-1)
CALL RESET ('HEIGHT')
CALL LABEL (X,Y)
CALL LENDGR (0)
DO 310 I=1,2
CALL PHYSOR (XPOS(I+3),YPOS(I+3))
CALL AREA2D (7.,2.5)
CALL FRAME
CALL SWITCH (XANS,7.,X,XORIG,XSTP,XMAX)
CALL HEIGHT (.10)
CALL SWITCH (Y3ANS(I+1),2.,Y,YORIG,YSTP,YMAX)
CALL XAXEND ('NOENDS.')
CALL YAXEND ('NOENDS.')
CALL XNCNUM
CALL GRAF (XORIG,XSTP,XMAX,YORIG,YSTP,YMAX)
CALL RESET ('XTICKS')
CALL RESET ('YTIKCS')
CALL CURVE (X,Y,8,-1)
CALL LABEL (X,Y)
CALL RESET ('HEIGHT')
CALL LENDGR (0)
CONTINUE
310 CALL SETCLR ('BLACK')
GO TO 350
C*****
C THIS SECTION ALLOWS THE USER TO PUT 4 GRAPHS ON A HORIZONTAL PAGE, *
C BASICALLY DIVIDE THE PAGE IN QUARTERS, WITH WHATEVER AXES WANTED. *
C*****
320 CONTINUE
IF (ANS.NE.4.0) GO TO 340
WRITE (6,62C)
READ (5,*) ANS
IF (ANS.NE.1.) GO TO 340
CALL FRICMS ('CLRSCRN 6')
WRITE (6,410)
WRITE (6,51C)

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READ (5,*) X4ANS(1),Y4ANS(1),X4ANS(2),Y4ANS(2),X4ANS(3),Y4ANS(3),X
14ANS(4),Y4ANS(4)
CALL FRICMS ('CLRSCRN 6')
CALL PAGE (11,8.5)
CALL AREA2D (9,5)
CALL HEIGHT (.3)
CALL MESSAG ('HELICOPTER DESIGN$',-100,-.25,5.5)
CALL RESET ('HEIGHT')
CALL MESSAG ('AE 4306/4900$',100,.95,5.25)
CALL LSTORY (KINDS,4,7.5,5.25)
CALL ENDGR (0)
DO 330 I=1,4
  CALL PHYSOR (XPOS(I+5),YPOS(I+5))
  CALL SETCLR ('RED')
  CALL AREA2D (4,.2.5)
  CALL FRAME (.10)
  CALL HEIGHT (X4ANS(1),1.,X,XORIG,XSTP,XMAX)
  CALL SWITCH (Y4ANS(1),2.,Y,YORIG,YSTP,YMAX)
  CALL XAXEND ('NCENDS')
  CALL YAXEND ('NOENDS')
  CALL GRAF (XORIG,XSTP,XMAX,YORIG,YSTP,YMAX)
  CALL RESET ('XTICKS')
  CALL RECURVE (X,Y,8,-1)
  CALL LABEL (X,Y)
  CALL RESET ('HEIGHT')
  CALL ENDGR (0)
CONTINUE
330 CALL SETCLR ('BLACK')
GO TO 350
C *****
C THIS SECTION ALLOWS THE USER TO REMAIN WITHIN THE PROGRAM IF HE
C MAKES A MISTAKE IN ENTERING DATA.
C *****
340 CONTINUE
WRITE (6,52)
READ (5,*) ANS
CALL FRICMS ('CLRSCRN 6')
IF (ANS.NE.1.) GO TO 360
GO TO 30
CONTINUE
350 CALL ENDPL (0)
C *****
C THIS SECTION IS USED TO ALLOW THE USER TO MAKE ADDITIONAL GRAPHS
C WITHOUT LEAVING THE PROGRAM AND HAVING TO REINITIATE DISPLA
C *****
WRITE (6,53)

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REAL RS(8), RSTR(8), TWST(8), TWSTTR(8), CDO(8), CDOTR(8), DL(8)
REAL WDT(8), LGH(8), FH(8), FV(8), VM(8), RNG(8), RC(8), HOVIGE(8)
REAL HOVIGE(8), LT(8), OWT(8), LWT(8), FWT(8), MGW(8), X(8)
INTEGER XORIG, XSTP, XMAX, Z, OPTION
COMMON /C1/ R, RTR, B, BTR, HT, RPM, RPMTR, C, CTR, RS, RSTR, TWST, TWSTTR, CDO
1, CDOTR, CL, WCT, LGH, FH, FV, VM, RNG, RC, HOVIGE, HOVIGE, LT, OWT, LWT, FWT, MGW
CALL XAXEND ('NOENDS')
CALL YAXEND ('NOENDS')
IF (Z.NE.1.) GO TO 90
DO 10 I=1,8
X(I)=R(1)
CONTINUE
XORIG=15.
XSTP=5.
XMAX=45.
IF (OPTICN.NE.1.) GO TO 20
CALL XTICKS(5)
CALL XNAME ('MAIN ROTOR RADIUS (FT)$', 100)
GO TO 2710
IF (OPTICN.NE.2.) GO TO 30
CALL Y TICKS(5)
CALL YNAME ('MAIN ROTOR RADIUS (FT)$', 100)
GO TO 2710
IF (OPTICN.NE.3.) GO TO 40
CALL XTICKS(5)
CALL XREVTK
CALL XGRAXS (XORIG, XSTP, XMAX, 9., 'MAIN ROTOR RADIUS (FT)$',
100, 0., -.75)
1 CALL RESET ('XTICKS')
GO TO 2710
IF (OPTICN.NE.4.) GO TO 50
CALL Y TICKS(5)
CALL YREVTK
CALL YGRAXS (XORIG, XSTP, XMAX, 6., 'MAIN ROTOR RADIUS (FT)$',
100, -1., 0.)
1 CALL RESET ('Y TICKS')
GO TO 2710
IF (OPTICN.NE.5.) GO TO 60
CALL XTICKS(5)
CALL XREVTK
CALL XGRAXS (XORIG, XSTP, XMAX, 6.5, 'MAIN ROTOR RADIUS (FT)$',
100, 0., -.75)
1 CALL RESET ('XTICKS')
GO TO 2710
IF (OPTICN.NE.6.) GO TO 70
CALL Y TICKS(5)

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CALL YREVTK (XORIG,XSTP,XMAX,8.,,MAIN ROTOR RADIUS (FT))$,
CALL YGRAXS (100,-1.,15,0.,
1 CALL RESET (YTIKCS;)
GO TO 2710
IF (OPTION,NE,7.) GO TO 80
CALL XTICKS (5)
CALL XNAME (.,,1)
GO TO 2710
CONTINUE
80 GO TO 2700
IF (Z,NE,2.) GO TO 180
90 DO 100 I=1,E
X(I)=RTR(I)
CONTINUE
100 XORIG=0.
XSTP=2.
XMAX=12.
IF (OPTION,NE,1.) GO TO 110
CALL XTICKS (5)
CALL XNAME (,TAIL ROTOR RADIUS (FT))$,100)
GO TO 2710
110 IF (OPTION,NE,2.) GO TO 120
CALL YTIKCS (2)
CALL YNAME (,TAIL ROTOR RADIUS (FT))$,100)
GO TO 2710
120 IF (OPTION,NE,3.) GO TO 130
CALL XTICKS (2)
CALL XREVTK
CALL XGRAXS (XORIG,XSTP,XMAX,9.,,TAIL ROTOR RADIUS (FT))$,
1 GO TO 2710
IF (OPTION,NE,4.) GO TO 140
CALL YTIKCS (2)
CALL YREVTK
CALL YGRAXS (XORIG,XSTP,XMAX,6.,,TAIL RCTOR RADIUS (FT))$,
1 GO TO 2710
IF (OPTION,NE,5.) GO TO 150
CALL XTICKS (2)
CALL XREVTK
CALL XGRAXS (XORIG,XSTP,XMAX,6.5,,TAIL ROTOR RADIUS (FT))$,
1 GO TO 2710
IF (OPTION,NE,6.) GO TO 160
CALL YTIKCS (2)
CALL YREVTK
CALL YGRAXS (XORIG,XSTP,XMAX,8.,,TAIL ROTOR RADIUS (FT))$,
180

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100,-1.15,0.)
1 GO TO 2710
IF (OPTION.NE.7.) GO TC 170
CALL XTICKS(2)
CALL XNAME(' ',1)
GO TO 2710
CONTINUE
GO TO 2700
IF (Z.NE.3.) GO TO 270
DO 190 I=1,E
X(I)=8(I)
CONTINUE
XORIG=0.
XSTP=1.
XMAX=9.
IF (OPTION.NE.1.) GO TO 200
CALL XNAME('NUMBER MAIN ROTOR BLADES$',100)
CALL XINTAX
GO TO 2710
200 IF (OPTION.NE.2.) GO TO 210
CALL YNAME('NUMBER MAIN ROTOR BLADES$',100)
CALL YINTAX
GO TO 2710
210 IF (OPTION.NE.3.) GO TO 220
CALL XREVTK
CALL XGRAXS
(XORIG,XSTP,XMAX,9.,BLADES$,100,0.,-.75)
1 CALL XINTAX
GO TO 2710
220 IF (OPTION.NE.4.) GO TO 230
CALL YREVTK
CALL YGRAXS
(XORIG,XSTP,XMAX,6.,BLADES$,100,-1.,0.)
1 CALL YINTAX
GO TO 2710
230 IF (OPTION.NE.5.) GO TO 240
CALL XREVTK
CALL XGRAXS
(XORIG,XSTP,XMAX,6.5,
,NUMBER MAIN ROTOR BLADES$,100,0.,-.75)
1 CALL XINTAX
GO TO 2710
240 IF (OPTION.NE.6.) GO TO 250
CALL YREVTK
CALL YGRAXS
(XORIG,XSTP,XMAX,8.,BLADES$,100,-1.15,0.)
1 CALL YINTAX
GO TO 2710
250 IF (OPTION.NE.7.) GO TO 260

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260 CALL XNAME (' ',1)
GO TO 2710
CONTINUE
270 GO TO 2700
IF (Z.NE.4.) GO TO 360
DO 280 I=1,E
X(I)=BTR(I)
CONTINUE
280 XORIG=0.
XSTP=1.
XMAX=6.
IF (OPTION.NE.1.) GO TO 290
CALL XNAME ('NUMBER TAIL ROTOR BLADES$',100)
CALL XINTAX
GO TO 2710
290 IF (OPTION.NE.2.) GO TO 300
CALL YNAME ('NUMBER TAIL ROTOR BLADES$',100)
CALL YINTAX
GO TO 2710
300 IF (OPTION.NE.3.) GO TO 310
CALL XREVTK (XORIG,XSTP,XMAX,9.,
CALL XGRAXS ('NUMBER TAIL ROTOR BLADES$',100,0.,-.75)
1 CALL XINTAX
GO TO 2710
310 IF (OPTION.NE.4.) GO TO 320
CALL YREVTK (XORIG,XSTP,XMAX,6.,
CALL YGRAXS ('NUMBER TAIL ROTOR BLADES$',100,-1.,0.)
1 CALL YINTAX
GO TO 2710
320 IF (OPTION.NE.5.) GO TO 330
CALL XREVTK (XORIG,XSTP,XMAX,6.5,
CALL XGRAXS ('NUMBER TAIL ROTOR BLADES$',100,0.,-.75)
1 CALL XINTAX
GO TO 2710
330 IF (OPTION.NE.6.) GO TO 340
CALL YREVTK (XORIG,XSTP,XMAX,8.,
CALL YGRAXS ('NUMBER TAIL ROTOR BLADES$',100,-1.15,0.)
1 CALL YINTAX
GO TO 2710
340 IF (OPTION.NE.7.) GO TO 350
CALL XNAME (' ',1)
GO TO 2710
CONTINUE
350 GO TO 2730

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360 IF (Z.NE.5.) GO TO 450
DO 370 I=1,8
X(I)=HT(I)
CONTINUE
XORIG=0.
XSTP=5.
XMAX=20.
IF (OPTION.NE.1.) GO TO 380
CALL XTICKS (5)
CALL XNAME ('HEIGHT OF ROTOR SYSTEM (FT)$',100)
GO TO 2710
380 IF (OPTION.NE.2.) GO TO 390
CALL YTICKS (5)
CALL YNAME ('HEIGHT OF ROTOR SYSTEM (FT)$',100)
GO TO 2710
390 IF (OPTION.NE.3.) GO TO 400
CALL XTICKS (5)
CALL XREVTK
CALL XGRAXS
1 GO TO 2710
400 IF (OPTION.NE.4.) GO TO 410
CALL YTICKS (5)
CALL YREVTK
CALL YGRAXS
1 GO TO 2710
410 IF (OPTION.NE.5.) GO TO 420
CALL XTICKS (5)
CALL XREVTK
CALL XGRAXS
1 GO TO 2710
420 IF (OPTION.NE.6.) GO TO 430
CALL YTICKS (5)
CALL YREVTK
CALL YGRAXS
1 GO TO 2710
430 IF (OPTION.NE.7.) GO TO 440
CALL XTICKS (5)
CALL XNAME ('',1)
GO TO 2710
440 CONTINUE
GO TO 2700
450 IF (Z.NE.6.) GO TO 540
DO 460 I=1,8
X(I)=RPM(I)

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460 CONTINUE
XORIG=0.
XSIP=50.
XMAX=600.
CALL XINTAX
CALL YINTAX
IF (OPTION. NE. 1.) GO TO 470
CALL XTICKS (5)
CALL XNAME ('MAIN ROTOR SPEED (RPM)$', 100)
CALL XINTAX
GO TO 2710
IF (OPTION. NE. 2.) GO TO 480
CALL YTICKS (5)
CALL YNAME ('MAIN ROTOR SPEED (RPM)$', 100)
CALL YINTAX
GO TO 2710
IF (OPTION. NE. 3.) GO TO 490
CALL XTICKS (5)
CALL XREVTK
CALL XGRAXS
1 XORIG, XSIP, XMAX, 9., (RPM)$, 100, 0., -.75)
CALL XINTAX
GO TO 2710
IF (OPTION. NE. 4.) GO TO 500
CALL YTICKS (5)
CALL YREVTK
CALL YGRAXS
1 XORIG, XSIP, XMAX, 6., (RPM)$, 100, -1., 0.)
CALL YINTAX
GO TO 2710
IF (OPTION. NE. 5.) GO TO 510
CALL XTICKS (5)
CALL XREVTK
CALL XGRAXS
1 XORIG, XSIP, XMAX, 6.5, (RPM)$, 100, 0., -.75)
CALL XINTAX
GO TO 2710
IF (OPTION. NE. 6.) GO TO 520
CALL YTICKS (5)
CALL YREVTK
CALL YGRAXS
1 XORIG, XSIP, XMAX, 8., (RPM)$, 100, -1.15, 0.)
CALL YINTAX
GO TO 2710
IF (OPTION. NE. 7.) GO TO 530
CALL XTICKS (5)
CALL XNAME ('', 1)
GO TO 2710

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530 CONTINUE
530 GO TO 2700
540 IF (Z.NE.7.) GO TO 630
540 DO 550 I=1,8
550 X(I)=RPMTR(I)
CONTINUE
XORIG=500.
XSTP=500.
XMAX=3500.
IF (OPTION.NE.1.) GO TO 560
CALL XTICKS (5)
CALL XNAME ('TAIL ROTOR SPEED (RPM)$',100)
CALL XINTAX
GO TO 2710
560 IF (OPTION.NE.2.) GO TO 570
CALL YTICKS (5)
CALL YNAME ('TAIL ROTOR SPEED (RPM)$',100)
CALL YINTAX
GO TO 2710
570 IF (OPTION.NE.3.) GO TO 580
CALL XTICKS (5)
CALL XREVTK
CALL XGRAXS (XORIG,XSTP,XMAX,9.,(RPM)$',100,0.,-.75)
1
CALL XINTAX
GO TO 2710
580 IF (OPTION.NE.4.) GO TO 590
CALL YTICKS (5)
CALL YREVTK
CALL YGRAXS (XORIG,XSTP,XMAX,6.,(RPM)$',100,-1.,0.)
1
CALL YINTAX
GO TO 2710
590 IF (OPTION.NE.5.) GO TO 600
CALL XTICKS (5)
CALL XREVTK
CALL XGRAXS (XORIG,XSTP,XMAX,6.5,(RPM)$',100,0.,-.75)
1
CALL XINTAX
GO TO 2710
600 IF (OPTION.NE.6.) GO TO 610
CALL YTICKS (5)
CALL YREVTK
CALL YGRAXS (XORIG,XSTP,XMAX,8.,(RPM)$',100,-1.15,0.)
1
CALL YINTAX
GO TO 2710
610 IF (OPTION.NE.7.) GO TO 620

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620 CALL XTICKS (5)
    CALL XNAME ('',1)
    GO TO 2710
CONTINUE
630 GO TO 2700
    IF (Z.NE.8.) GO TO 720
DO 640 I=1,8
    X(I)=C(I)
CONTINUE
640 XORIG=0.0
    XSTP=0.5
    XMAX=3.0
    IF (OPTION.NE.1.) GO TO 650
    CALL XTICKS (5)
    CALL XNAME ('MAIN ROTOR BLADE CHORD(FT)$',100)
    GO TO 2710
650 IF (OPTION.NE.2.) GO TC 660
    CALL YTICKS (5)
    CALL YNAME ('MAIN ROTOR BLADE CHORD(FT)$',100)
    GO TO 2710
660 IF (OPTION.NE.3.) GO TO 670
    CALL XTICKS (5)
    CALL XREVTK
    CALL XGRAXS (XORIG,XSTP,XMAX,9.,CHORD(FT)$',100,0.,-.75)
1
670 GO TO 2710
    IF (OPTION.NE.4.) GO TO 680
    CALL YTICKS (5)
    CALL YREVTK
    CALL YGRAXS (XORIG,XSTP,XMAX,6.,CHORD(FT)$',100,-1.,0.)
1
680 GO TO 2710
    IF (OPTION.NE.5.) GO TC 690
    CALL XTICKS (5)
    CALL XREVTK
    CALL XGRAXS (XORIG,XSTP,XMAX,6.5,CHORD(FT)$',100,0.,-.75)
1
690 GO TO 2710
    IF (OPTION.NE.6.) GO TC 700
    CALL YTICKS (5)
    CALL YREVTK
    CALL YGRAXS (XORIG,XSTP,XMAX,8.,CHORD(FT)$',100,-1.15,0.)
1
700 GO TO 2710
    IF (OPTION.NE.7.) GO TO 710
    CALL XTICKS (5)
    CALL XNAME ('',1)
    GO TO 2710

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710 CONTINUE
720 GO TO 2700
    IF (Z.NE.9.) GO TO 810
    DO 730 I=1,8
    X(I)=CTR(I)
730 CONTINUE
    XORIG=0.3
    XSTP=0.1
    XMAX=1.5
    IF (OPTION.NE.1.) GO TO 740
    CALL XTICKS (5)
    CALL XNAME ('TAIL ROTOR BLADE CHORD(FT)',100)
    GO TO 2710
740 IF (OPTION.NE.2.) GO TO 750
    CALL YTICKS (5)
    CALL YNAME ('TAIL ROTOR BLADE CHORD(FT)',100)
    GO TO 2710
750 IF (OPTION.NE.3.) GO TO 760
    CALL XTICKS (5)
    CALL XREVTK
    CALL XGRAXS (XORIG,XSTP,XMAX,9.,CHORD(FT)$,100,0.,-.75)
    1 GO TO 2710
760 IF (OPTION.NE.4.) GO TO 770
    CALL YTICKS (5)
    CALL YREVTK
    CALL YGRAXS (XORIG,XSTP,XMAX,6.,CHORD(FT)$,100,-1.,0.)
    1 GO TO 2710
770 IF (OPTION.NE.5.) GO TO 780
    CALL XTICKS (5)
    CALL XREVTK
    CALL XGRAXS (XORIG,XSTP,XMAX,6.5,CHORD(FT)$,100,0.,-.75)
    1 GO TO 2710
780 IF (OPTION.NE.6.) GO TO 790
    CALL YTICKS (5)
    CALL YREVTK
    CALL YGRAXS (XORIG,XSTP,XMAX,8.,CHORD(FT)$,100,-1.15,0.)
    1 GO TO 2710
790 IF (OPTION.NE.7.) GO TO 800
    CALL XTICKS (5)
    CALL XNAME ('',1)
    GO TO 2710
800 CONTINUE
    GO TO 2700
810 IF (Z.NE.10.) GO TO 900

```



```

820 DO 820 I=1,E
      X(I)=RS(I)
      CONTINUE
      XORIG=10.
      XSTP=5.
      XMAX=40.
      IF (OPTION,NE,1.) GO TO 830
      CALL XTICKS (5)
      CALL XNAME ('MAIN ROTOR BLADE SPAN(FT)',100)
      GO TO 2710
830 IF (OPTION,NE,2.) GC TC 840
      CALL YTICKS (5)
      CALL YNAME ('MAIN ROTOR BLADE SPAN(FT)',100)
      GO TO 2710
840 IF (OPTION,NE,3.) GO TO 850
      CALL XTICKS (5)
      CALL XREVTK
      CALL XGRAXS
      1 GO TO 2710
      IF (OPTION,NE,4.) GO TO 860
      CALL YTICKS (5)
      CALL YREVTK
      CALL YGRAXS
      1 GO TO 2710
      IF (OPTION,NE,5.) GC TC 870
      CALL XTICKS (5)
      CALL XREVTK
      CALL XGRAXS
      1 GO TO 2710
      IF (OPTION,NE,6.) GO TC 880
      CALL YTICKS (5)
      CALL YREVTK
      CALL YGRAXS
      1 GO TO 2710
      IF (OPTION,NE,7.) GO TO 890
      CALL XTICKS (5)
      CALL XNAME ('',1)
      CONTINUE
      GO TO 2700
890 IF (Z,NE,1.) GO TO 990
900 DO 910 I=1,E
      X(I)=RSTR(I)
      CONTINUE
910

```



```

XORIG=0.
XSTP=1.
XMAX=10.
IF (OPTION.NE.1.) GO TO 920
CALL XTICKS (5)
CALL XNAME ('TAIL ROTOR BLADE SPAN(FT) $',100)
GO TO 2710
920 IF (OPTION.NE.2.) GO TC 930
CALL YTICKS (5)
CALL YNAME ('TAIL ROTOR BLADE SPAN(FT) $',100)
GO TO 2710
930 IF (OPTION.NE.3.) GO TO 940
CALL XTICKS (5)
CALL XREVTK
CALL XGRAXS (XORIG,XSTP,XMAX,9.,SPAN(FT) $,100,0.,-.75)
1 GO TO 2710
IF (OPTION.NE.4.) GO TO 950
940 CALL YTICKS (5)
CALL YREVTK
CALL YGRAXS (XORIG,XSTP,XMAX,6.,SPAN(FT) $,100,-1.,0.)
1 GO TO 2710
950 IF (OPTION.NE.5.) GO TC 960
CALL XTICKS (5)
CALL XREVTK
CALL XGRAXS (XORIG,XSTP,XMAX,6.5,SPAN(FT) $,100,0.,-.75)
1 GO TO 2710
960 IF (OPTION.NE.6.) GO TC 970
CALL YTICKS (5)
CALL YREVTK
CALL YGRAXS (XORIG,XSTP,XMAX,8.,SPAN(FT) $,100,-1.15,0.)
1 GO TO 2710
970 IF (OPTION.NE.7.) GO TO 980
CALL XTICKS (5)
CALL XNAME ('',1)
GO TO 2710
980 CONTINUE
GO TO 2700
990 IF (Z.NE.12.) GO TO 1080
DO 1000 I=1,8
X(I)=TWST(I)
1000 CONTINUE
XORIG=-5.
XSTP=-5.
XMAX=-20.

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1010 IF (OPTION.NE.1.) GO TO 1010
      CALL XTICKS (5)
      CALL XNAME ('MAIN ROTOR BLADE TWIST(DEG)$',100)
      GO TO 2710
      IF (OPTION.NE.2.) GO TC 1020
      CALL YTICKS (5)
      CALL YNAME ('MAIN ROTOR BLADE TWIST(DEG)$',100)
      GO TO 2710
1020 IF (OPTION.NE.3.) GO TO 1030
      CALL XTICKS (5)
      CALL XREVTK
      CALL XGRAXS (XORIG,XSTP,XMAX,9.,TWIST(DEG)$',100,0.,-.75)
      1 GO TO 2710
1030 IF (OPTION.NE.4.) GO TC 1040
      CALL YTICKS (5)
      CALL YREVTK
      CALL YGRAXS (XORIG,XSTP,XMAX,6.,TWIST(DEG)$',100,-1.,0.)
      1 GO TO 2710
1040 IF (OPTION.NE.5.) GO TC 1050
      CALL XTICKS (5)
      CALL XREVTK
      CALL XGRAXS (XORIG,XSTP,XMAX,6.5,TWIST(DEG)$',100,0.,-.75)
      1 GO TO 2710
1050 IF (OPTION.NE.6.) GO TO 1060
      CALL YTICKS (5)
      CALL YREVTK
      CALL YGRAXS (XORIG,XSTP,XMAX,8.,TWIST(DEG)$',100,-1.15,0.)
      1 GO TO 2710
1060 IF (OPTION.NE.7.) GO TO 1070
      CALL XTICKS (5)
      CALL XNAME ('',1)
      GO TO 2710
1070 CONTINUE
      GO TO 2700
1080 IF (Z.NE.13.) GO TO 1170
      DO 1090 I=1,8
      X(I)=TWSTTR(I)
      CONTINUE
      XORIG=5.
      XSTP=-5.
      XMAX=-20.
      IF (OPTION.NE.1.) GO TO 1100
      CALL XTICKS (5)
      CALL XNAME ('TAIL ROTOR BLADE TWIST(DEG)$',100)

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1100      GO TO 2710
          IF (OPTION,NE,2.) GO TO 1110
          CALL YTICKS (5)
          CALL YNAME ('TAIL ROTOR BLADE TWIST(DEG)$',100)
          GO TO 2710
1110      IF (OPTION,NE,3.) GO TO 1120
          CALL XTICKS (5)
          CALL XREVTK
          CALL XGRAXS
          1      (XORIG,XSTP,XMAX,9.,
                  'TAIL ROTOR BLADE TWIST(DEG)$',100,0.,-.75)
1120      GO TO 2710
          IF (OPTION,NE,4.) GO TO 1130
          CALL YTICKS (5)
          CALL YREVTK
          CALL YGRAXS
          1      (XORIG,XSTP,XMAX,6.,
                  'TAIL ROTOR BLADE TWIST(DEG)$',100,-1.,0.)
1130      GO TO 2710
          IF (OPTION,NE,5.) GO TO 1140
          CALL XTICKS (5)
          CALL XREVTK
          CALL XGRAXS
          1      (XORIG,XSTP,XMAX,6.5,
                  'TAIL ROTOR BLADE TWIST(DEG)$',100,0.,-.75)
1140      GO TO 2710
          IF (OPTION,NE,6.) GO TO 1150
          CALL YTICKS (5)
          CALL YREVTK
          CALL YGRAXS
          1      (XORIG,XSTP,XMAX,8.,
                  'TAIL ROTOR BLADE TWIST(DEG)$',100,-1.15,0.)
1150      GO TO 2710
          IF (OPTION,NE,7.) GO TO 1160
          CALL XTICKS (5)
          CALL XNAME ('',1)
          GO TO 2710
1160      CONTINUE
          GO TO 2700
1170      IF (Z,NE,14.) GO TO 1260
          DO 1180 I=1,8
          X(I)=CCC(I)
          CONTINUE
          XORIG=.007
          XSTP=.001
          XMAX=.011
          IF (OPTION,NE,1.) GO TO 1190
          CALL XTICKS (5)
          CALL XNAME ('PROFILE DRAG MAIN ROTOR$',100)
          GO TO 2710
1190      IF (OPTION,NE,2.) GO TO 1200
          CALL YTICKS (5)

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1200      CALL YNAME ('PROFILE DRAG MAIN ROTCR$',100)
        GO TO 2710
        IF (OPTION.NE.3.) GO TC 1210
        CALL XTICKS (5)
        CALL XREVTK
        CALL XGRAXS (XORIG,XSTP,XMAX,9.,
1          'PROFILE DRAG MAIN ROTOR$',100,0.,-.75)
1210      GO TO 2710
        IF (OPTION.NE.4.) GO TO 1220
        CALL YTICKS (5)
        CALL YREVTK
        CALL YGRAXS (XORIG,XSTP,XMAX,6.,
1          'PROFILE DRAG MAIN ROTOR$',100,-1.,0.)
1220      GO TO 2710
        IF (OPTION.NE.5.) GO TO 1230
        CALL XTICKS (5)
        CALL XREVTK
        CALL XGRAXS (XORIG,XSTP,XMAX,6.5,
1          'PROFILE DRAG MAIN ROTOR$',100,0.,-.75)
1230      GO TO 2710
        IF (OPTION.NE.6.) GO TO 1240
        CALL YTICKS (5)
        CALL YREVTK
        CALL YGRAXS (XORIG,XSTP,XMAX,8.,
1          'PROFILE DRAG MAIN ROTCR$',100,-1.15,0.)
1240      GO TO 2710
        IF (OPTION.NE.7.) GO TC 1250
        CALL XTICKS (5)
        CALL XAAME ('',1)
        GO TO 2710
        CONTINUE
1250      GO TO 2700
1260      IF (Z.NE.15.) GO TO 1350
        DO 1270 I=1,8
        X(I)=CCCTR(I)
        CONTINUE
1270      XORIG=.007
        XSTP=.002
        XMAX=.017
        IF (OPTION.NE.1.) GO TO 1280
        CALL XTICKS (2)
        CALL XNAME ('PROFILE DRAG TAIL ROTOR$',100)
        GO TO 2710
1280      IF (OPTION.NE.2.) GO TO 1290
        CALL YTICKS (2)
        CALL YNAME ('PRGFILE DRAG TAIL ROTCR$',100)
        GO TO 2710
1290      IF (OPTION.NE.3.) GO TO 1300

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CALL XTICKS (2)
CALL XREVTK
CALL XGRAXS (XORIG,XSTP,XMAX,9.,
'PROFILE DRAG TAIL ROTOR$',100,0.,-,.75)
1 GO TO 2710
IF (OPTION,NE.4.) GO TO 1310
CALL XTICKS (2)
CALL YREVTK
CALL YGRAXS (XORIG,XSTP,XMAX,6.,
'PROFILE DRAG TAIL ROTOR$',100,-1.,0.)
1 GO TO 2710
IF (OPTION,NE.5.) GO TO 1320
CALL XTICKS (2)
CALL XREVTK
CALL XGRAXS (XORIG,XSTP,XMAX,6.5,
'PROFILE DRAG TAIL ROTOR$',100,0.,-,.75)
1 GO TO 2710
IF (OPTION,NE.6.) GO TO 1330
CALL XTICKS (2)
CALL YREVTK
CALL YGRAXS (XORIG,XSTP,XMAX,8.,
'PROFILE DRAG TAIL ROTOR$',100,-1.15,0.)
1 GO TO 2710
IF (OPTION,NE.7.) GO TO 1340
CALL XTICKS (2)
CALL XNAME (',',1)
GO TO 2710
CONTINUE
GO TO 2700
IF (Z,NE.16.) GO TO 1440
DO 1360 I=1,8
X(I)=DL(I)
CONTINUE
XORIG=4.
XSTP=1.
XMAX=16.
IF (OPTION,NE.1.) GO TO 1370
CALL XTICKS (2)
CALL XNAME ('DISC LOADING$',100)
GO TO 2710
IF (OPTION,NE.2.) GO TO 1380
CALL YTICKS (2)
CALL YNAME ('DISC LOADING$',100)
GO TO 2710
IF (OPTION,NE.3.) GO TO 1390
CALL XTICKS (2)
CALL XREVTK
CALL XGRAXS (XORIG,XSTP,XMAX,9.,

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CALL YTICKS (2)
CALL YREVTK
CALL YGRAXS (XORIG,XSTP,XMAX,6.,,
,FUSELAGE WIDTH (FT)$',100,-1.,0.)
1 GO TO 2710
IF (OPTION,NE.5.) GO TO 1500
CALL XTICKS (2)
CALL XREVTK
CALL XGRAXS (XORIG,XSTP,XMAX,6.5,
,FUSELAGE WIDTH (FT)$',100,0.,-.75)
1 GO TO 2710
IF (OPTION,NE.6.) GO TO 1510
CALL YTICKS (2)
CALL YREVTK
CALL YGRAXS (XORIG,XSTP,XMAX,8.,,
,FUSELAGE WIDTH (FT)$',100,-1.15,0.)
1 GO TO 2710
IF (OPTION,NE.7.) GO TO 1520
CALL XTICKS (2)
CALL XNAME (',',1)
GO TO 2710
CONTINUE
GO TO 2700
IF (Z,NE.18.) GO TO 1620
DO 1540 I=1,8
X(I)=LGH(I)
CONTINUE
XORIG=20.
XSTP=20.
XMAX=120.
IF (OPTION,NE.1.) GO TO 1550
CALL XTICKS (2)
CALL XNAME (,FUSELAGE LENGTH (FT)$',100)
GO TO 2710
IF (OPTION,NE.2.) GO TO 1560
CALL YTICKS (2)
CALL YNAME (,FUSELAGE LENGTH (FT)$',100)
GO TO 2710
IF (OPTION,NE.3.) GO TO 1570
CALL XTICKS (2)
CALL XREVTK
CALL XGRAXS (XORIG,XSTP,XMAX,9.,,
,FUSELAGE LENGTH (FT)$',100,0.,-.75)
1 GO TO 2710
IF (OPTION,NE.4.) GO TO 1580
CALL YTICKS (2)
CALL YREVTK
CALL YGRAXS (XORIG,XSTP,XMAX,6.,,

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1 GO TO 2710
1580 IF (OPTION,NE.5.) GO TO 1590
CALL XTICKS(2)
CALL XREVTK
CALL XGRAXS
1 GO TO 2710
1590 IF (OPTION,NE.6.) GO TO 1600
CALL YTICKS(2)
CALL YREVTK
CALL YGRAXS
1 GO TO 2710
1600 IF (OPTION,NE.7.) GO TO 1610
CALL XTICKS(2)
CALL XNAME(' ',1)
GO TO 2710
1610 CONTINUE
GO TO 2700
1620 IF (Z,NE.19.) GO TO 1710
DO 1630 I=1,8
X(I)=FH(I)
CONTINUE
XORIG=0.
XSTP=10.
XMAX=70.
IF (OPTION,NE.1.) GO TC 1640
CALL XTICKS(2)
CALL XNAME('FRONT FLAT PLATE AREA(SF)$',100)
GO TO 2710
1640 IF (OPTION,NE.2.) GO TO 1650
CALL YTICKS(2)
CALL YNAME('FRONT FLAT PLATE AREA(SF)$',100)
GO TO 2710
1650 IF (OPTION,NE.3.) GO TO 1660
CALL XTICKS(2)
CALL XREVTK
CALL XGRAXS
1 GO TO 2710
1660 IF (OPTION,NE.4.) GO TO 1670
CALL YTICKS(2)
CALL YREVTK
CALL YGRAXS
1 GO TO 2710
1670 IF (OPTION,NE.5.) GO TO 1680

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CALL XTICKS (2)
CALL XREVTK
CALL XGRAXS
1  GO TO 2710
   IF (OPTION, NE, 6.) GO TO 1690
   CALL YTICKS (2)
   CALL YREVTK
   CALL YGRAXS
1  GO TO 2710
   IF (OPTION, NE, 7.) GO TO 1700
   CALL XTICKS (2)
   CALL XNAME ('', 1)
   GO TO 2710
   CONTINUE
   GO TO 2700
1710 IF (Z, NE, 20.) GO TO 1800
   DO 1720 I=1,8
   X(I)=FV(I)
   CONTINUE
   XORIG=0.
   XSTP=30.
   XMAX=150.
   IF (OPTION, NE, 1.) GO TO 1730
   CALL XTICKS (3)
   CALL XNAME ('VERT. FLAT PLATE AREA(SF)', 100)
   GO TO 2710
1730 IF (OPTION, NE, 2.) GO TO 1740
   CALL YTICKS (3)
   CALL YNAME ('VERT. FLAT PLATE AREA(SF)', 100)
   GO TO 2710
1740 IF (OPTION, NE, 3.) GO TO 1750
   CALL XTICKS (3)
   CALL XREVTK
   CALL XGRAXS
1  GO TO 2710
   IF (OPTION, NE, 4.) GO TO 1760
   CALL YTICKS (3)
   CALL YREVTK
   CALL YGRAXS
1  GO TO 2710
   IF (OPTION, NE, 5.) GO TO 1770
   CALL XTICKS (3)
   CALL XREVTK
   CALL XGRAXS (XORIG, XSTP, XMAX, 6.5,
                'VERT. FLAT PLATE AREA(SF)', 100, 0., -.75)
1750
1760
1770

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1      'VERT. FLAT PLATE AREA(SF)$',100,0.,-.75)
1770  GO TO 2710
      IF (OPTICN,NE,6.) GO TO 1780
      CALL YTICKS (3)
      CALL YREVTK
      CALL YGRAXS (XORIG,XSTP,XMAX,8.,
1      'VERT. FLAT PLATE AREA(SF)$',100,-1.15,0.)
1780  GO TO 2710
      IF (OPTICN,NE,7.) GO TO 1790
      CALL XTICKS (3)
      CALL XNAME ('',1)
      GO TO 2710
1790  CONTINUE
      GO TO 2700
1800  IF (Z,NE,21.) GO TO 1890
      DO 1810 I=1,8
1810  X(I)=VM(I)
      CONTINUE
      XORIG=100.
      XSTP=100.
      XMAX=180.
      IF (OPTICN,NE,1.) GO TO 1820
      CALL XTICKS (2)
      CALL XNAME ('MAXIMUM VELOCITY (KNT)$',100)
      CALL XINTAX
      GO TO 2710
1820  IF (OPTICN,NE,2.) GO TO 1830
      CALL YTICKS (2)
      CALL YNAME ('MAXIMUM VELOCITY (KNT)$',100)
      CALL YINTAX
      GO TO 2710
1830  IF (OPTICN,NE,3.) GO TO 1840
      CALL XTICKS (2)
      CALL XREVTK
      CALL XGRAXS (XORIG,XSTP,XMAX,9.,
1      'MAXIMUM VELOCITY (KNT)$',100,0.,-.75)
1840  GO TO 2710
      IF (OPTICN,NE,4.) GO TO 1850
      CALL YTICKS (2)
      CALL YREVTK
      CALL YGRAXS (XORIG,XSTP,XMAX,6.,
1      'MAXIMUM VELOCITY (KNT)$',100,-1.,0.)
1850  GO TO 2710
      IF (OPTICN,NE,5.) GO TO 1860
      CALL XTICKS (2)
      CALL XREVTK

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1 CALL XGRAXS (XORIG,XSTP,XMAX,6.5,
  'MAXIMUM VELOCITY (KNT)$',100,0.,-.75)
1860 CALL XINTAX
      GO TO 2710
      IF (OPTION,NE.6.) GO TO 1870
      CALL YTICKS (2)
      CALL YREVTK
      CALL YGRAXS (XORIG,XSTP,XMAX,8.,
        'MAXIMUM VELOCITY (KNT)$',100,-1.15,0.)
1 CALL YINTAX
      GO TO 2710
      IF (OPTION,NE.7.) GO TO 1880
      CALL XTICKS (2)
      CALL XNAME ('',1)
      GO TO 2710
      CONTINUE
      GO TO 450
      IF (Z,NE.22.) GO TO 1980
      DO 1900 I=1,8
      X(I)=RNG(I)
      CONTINUE
      XORIG=150.
      XSTP=50.
      XMAX=550.
      IF (OPTION,NE.1.) GO TO 1910
      CALL XTICKS (2)
      CALL XNAME ('MAXIMUM RANGES (NM)$',100)
      CALL XINTAX
      GO TO 2710
      IF (OPTION,NE.2.) GO TO 1920
      CALL YTICKS (2)
      CALL YNAME ('MAXIMUM RANGES (NM)$',100)
      CALL YINTAX
      GO TO 2710
      IF (OPTION,NE.3.) GO TO 1930
      CALL XTICKS (2)
      CALL XREVTK
      CALL XGRAXS (XORIG,XSTP,XMAX,9.,
        'MAXIMUM RANGE (NM)')
1 CALL XINTAX
      GO TO 2710
      IF (OPTION,NE.4.) GO TO 1940
      CALL YTICKS (2)
      CALL YREVTK
      CALL YGRAXS (XORIG,XSTP,XMAX,6.,
        'MAXIMUM RANGE (NM)')
1 CALL YINTAX
      GO TO 2710

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1940	IF (OPTION, NE.5.) GO TO 1950 CALL XTICKS (2) CALL XREVTK CALL XGRAXS (XORIG, XSTP, XMAX, 6.5, , MAXIMUM RANGE (NM))
1950	1 CALL XINTAX GO TO 2710 IF (OPTION, NE.6.) GO TO 1960 CALL YTICKS (2) CALL YREVTK CALL YGRAXS (XORIG, XSTP, XMAX, 8., , MAXIMUM RANGE (NM))
1960	1 CALL YINTAX GO TO 2710 IF (OPTION, NE.7.) GO TO 1970 CALL XTICKS (2) CALL XNAME (, , 1)
1970	GO TO 2710 CONTINUE GO TO 2700
1980	IF (2, NE.23.) GO TO 2070 DO 1990 I=1,8 X(I)=RC(I)
1990	CONTINUE XORIG=C. XSTP=500. XMAX=3000. IF (OPTION, NE.1.) GO TO 2000 CALL XTICKS (2) CALL XNAME (, RATE OF CLIMB (FT/MIN)\$, 100) CALL XINTAX GO TO 2710
2000	IF (OPTION, NE.2.) GO TO 2010 CALL YTICKS (2) CALL YNAME (, RATE OF CLIMB (FT/MIN)\$, 100) CALL YINTAX GO TO 2710
2010	IF (OPTION, NE.3.) GO TO 2020 CALL XTICKS (2) CALL XREVTK CALL XGRAXS (XORIG, XSTP, XMAX, 9., , RATE OF CLIMB (FT/MIN)\$, 100, 0., -.75)
2020	1 CALL XINTAX GO TO 2710 IF (OPTION, NE.4.) GO TO 2030 CALL YTICKS (2) CALL YREVTK CALL YGRAXS (XORIG, XSTP, XMAX, 6.,


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1 CALL YINTAX
  GO TO 2710
  IF (OPTION.NE.5.) GO TO 2040
  CALL XTICKS (2)
  CALL XREVTK
  CALL XGRAXS
  (XORIG,XSTP,XMAX,6.5,
  'RATE OF CLIMB (FT/MIN)$',100,0.,-.75)
1 CALL XINTAX
  GO TO 2710
  IF (OPTION.NE.6.) GO TO 2050
  CALL YTICKS (2)
  CALL YREVTK
  CALL YGRAXS
  (XORIG,XSTP,XMAX,8.,
  'RATE OF CLIMB (FT/MIN)$',100,-1.15,0.)
1 CALL YINTAX
  GO TO 2710
  IF (OPTION.NE.7.) GO TO 2060
  CALL XTICKS (2)
  CALL XNAME ('',1)
  GO TO 2710
  CONTINUE
  GO TO 2700
  IF (Z.NE.24.) GO TO 2160
  DO 2080 I=1,8
  X(I)=HCVIGE(I)
  CONTINUE
  XORIG=3000.
  XSTP=3000.
  XMAX=15000.
  IF (OPTION.NE.1.) GO TO 2090
  CALL XTICKS (3)
  CALL XNAME ('HOVER CEILING (FT) IGE$',100)
  CALL XINTAX
  GO TO 2710
  IF (OPTION.NE.2.) GO TO 2100
  CALL YTICKS (3)
  CALL YNAME ('HOVER CEILING (FT) IGE$',100)
  CALL YINTAX
  GO TO 2710
  IF (OPTION.NE.3.) GO TO 2110
  CALL YTICKS (3)
  CALL XREVTK
  CALL XGRAXS
  (XORIG,XSTP,XMAX,9.,
  'HOVER CEILING (FT) IGE$',100,0.,-.75)
1 CALL XINTAX
  GO TO 2710
  IF (OPTION.NE.4.) GO TO 2120

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CALL YTICKS (3)
CALL YREVTK
CALL YGRAXS
1  (XORIG,XSTP,XMAX,6; IGE$,100,-1.,0.)
   HOVER CEILING (FT)
CALL YINTAX
GO TO 2710
IF (OPTION,NE,5.) GO TO 2130
CALL XTICKS (3)
CALL XREVTK
CALL XGRAXS
1  (XORIG,XSTP,XMAX,6.5, IGE$,100,0.,-.75)
   HOVER CEILING (FT)
CALL XINTAX
GO TO 2710
IF (OPTION,NE,6.) GO TO 2140
CALL YTICKS (3)
CALL YREVTK
CALL YGRAXS
1  (XORIG,XSTP,XMAX,8; IGE$,100,-1.15,0.)
   HOVER CEILING (FT)
CALL YINTAX
GO TO 2710
IF (OPTION,NE,7.) GO TO 2150
CALL XTICKS (3)
CALL XNAME (.,.,1)
GO TO 2710
CONTINUE
GO TO 2700
IF (Z,NE,25.) GO TO 2250
DO 2170 I=1,8
X(I)=HCVGGE(I)
CONTINUE
XORIG=0.
XSTP=3CC0.
XMAX=18000.
IF (OPTION,NE,1.) GO TO 2180
CALL XTICKS (3)
CALL XNAME (HOVER CEILING (FT) OGE$,100)
CALL XINTAX
GO TO 2710
IF (OPTION,NE,2.) GO TO 2190
CALL YTICKS (3)
CALL YNAME (HOVER CEILING (FT) OGE$,100)
CALL YINTAX
GO TO 2710
IF (OPTION,NE,3.) GO TO 2200
CALL XTICKS (3)
CALL XREVTK
CALL XGRAXS
1  (XORIG,XSTP,XMAX,9; OGE$,100,0.,-.75)
   HOVER CEILING (FT)

```



```

2200      CALL XINTAX
        GO TO 2710
        IF (OPTION.NE.4.) GO TO 2210
        CALL YTICKS (3)
        CALL YREVTK
        CALL YGRAXS (XORIG,XSTP,XMAX,6.;
                     ,HOVER CEILING (FT) OGE$,100,-1.,0.)
1
        CALL YINTAX
        GO TO 2710
        IF (OPTION.NE.5.) GO TO 2220
        CALL XTICKS (3)
        CALL XREVTK
        CALL XGRAXS (XORIG,XSTP,XMAX,6.5,
                     ,HOVER CEILING (FT) OGE$,100,0.,-.75)
1
        CALL XINTAX
        GO TO 2710
        IF (OPTION.NE.6.) GO TO 2230
        CALL YTICKS (3)
        CALL YREVTK
        CALL YGRAXS (XORIG,XSTP,XMAX,8.;
                     ,HOVER CEILING (FT) OGE$,100,-1.15,0.)
1
        CALL YINTAX
        GO TO 2710
        IF (OPTION.NE.7.) GO TO 2240
        CALL XTICKS (3)
        CALL XNAME (.,1)
        GO TO 2710
        CONTINUE
        GO TO 2700
2240      IF (Z.NE.26.) GO TO 2340
2250      DO 2260 I=1,8
        X(I)=LT(I)
        CONTINUE
        XORIG=10.
        XSTP=10.
        XMAX=60.
        IF (OPTION.NE.1.) GO TO 2270
        CALL XTICKS (5)
        CALL XNAME (,LENGTH OF TAIL (FT)$,100)
        GO TO 2710
        IF (OPTION.NE.2.) GO TO 2280
        CALL YTICKS (5)
        CALL YNAME (,LENGTH OF TAIL (FT)$,100)
        GO TO 2710
        IF (OPTION.NE.3.) GO TO 2290
        CALL XTICKS (5)
        CALL XREVTK
        CALL XGRAXS (XORIG,XSTP,XMAX,9.,

```



```

1      GO TO 2710
2290  IF (OPTION,NE,4.) GO TO 2300
      CALL YTICKS (5)
      CALL YREVTK
      CALL YGRAXS
      (XORIG,XSTP,XMAX,6.,
1      'LENGTH OF TAIL (FT)',100,0.,-1.,0.)

2300  GO TO 2710
      IF (OPTION,NE,5.) GO TO 2310
      CALL XTICKS (5)
      CALL XREVTK
      CALL XGRAXS
      (XORIG,XSTP,XMAX,6.5,
1      'LENGTH OF TAIL (FT)',100,0.,-.75)

2310  GO TO 2710
      IF (OPTION,NE,6.) GO TO 2320
      CALL YTICKS (5)
      CALL YREVTK
      CALL YGRAXS
      (XORIG,XSTP,XMAX,8.,
1      'LENGTH OF TAIL (FT)',100,-1.15,0.)

2320  GO TO 2710
      IF (OPTION,NE,7.) GO TO 2330
      CALL XTICKS (5)
      CALL XNAME ('',1)
      GO TO 2710
2330  CONTINUE
      GO TO 2700
2340  IF (Z,NE,27.) GO TO 2430
      DO 2350 I=1,8
      X(I)=0*(1)
      CONTINUE
2350  XORIG=0.
      XSTP=5000.
      XMAX=40000.
      IF (OPTION,NE,1.) GO TO 2360
      CALL XTICKS (2)
      CALL XNAME ('OPERATING WEIGHT (LB)',100)
      CALL XINTAX
      GO TO 2710
2360  IF (OPTION,NE,2.) GO TO 2370
      CALL YTICKS (2)
      CALL YNAME ('OPERATING WEIGHT (LB)',100)
      CALL YINTAX
      GO TO 2710
2370  IF (OPTION,NE,3.) GO TO 2380
      CALL XTICKS (2)
      CALL XREVTK
      CALL XGRAXS
      (XORIG,XSTP,XMAX,9.,
1      'OPERATING WEIGHT (LB)',100,0.,-.75)

```


2380	CALL XINTAX GO TO 2710 IF (OPTION.NE.4.) GO TO 2390 CALL YTTICKS (2) CALL YREVTK CALL YGRAXS 1 (XORIG,XSTP,XMAX,6.,(LB)\$,100,-1.,0.) OPERATING WEIGHT (LB)\$,100,0.,-.75)
2390	CALL YINTAX GO TO 2710 IF (OPTION.NE.5.) GO TO 2400 CALL XTTICKS (2) CALL XREVTK CALL XGRAXS 1 (XORIG,XSTP,XMAX,6.5, OPERATING WEIGHT (LB)\$,100,0.,-.75)
2400	CALL XINTAX GO TO 2710 IF (OPTION.NE.6.) GO TO 2410 CALL YTTICKS (2) CALL YREVTK CALL YGRAXS 1 (XORIG,XSTP,XMAX,8., OPERATING WEIGHT (LB)\$,100,-1.15,0.)
2410	CALL YINTAX GO TO 2710 IF (OPTION.NE.7.) GO TO 2420 CALL XTTICKS (2) CALL XNAME ('',1) GO TO 2710 CONTINUE
2420	GO TO 2700
2430	IF (2.NE.28.) GO TO 2520 DO 2440 I=1,8 X(I)=LWT(I) CONTINUE XORIG=0. XSTP=5000. XMAX=30000. IF (OPTION.NE.1.) GO TO 2450 CALL XTTICKS (2) CALL XNAME (LOAD WEIGHT (LB)\$,100) CALL XINTAX GO TO 2710 IF (OPTION.NE.2.) GO TO 2460 CALL YTTICKS (2) CALL YNAME (LOAD WEIGHT (LB)\$,100) CALL YINTAX GO TO 2710 IF (OPTION.NE.3.) GO TO 2470 CALL XTTICKS (2)
2440	
2450	
2460	


```

CALL XREVTK
CALL XGRAXS (XORIG,XSTP,XMAX,9,1,100,0,0,-.75)
1 CALL XINTAX
GO TO 2710
IF (OPTION,NE,4.) GO TO 2480
CALL YTTICKS (2)
CALL YREVTK
CALL YGRAXS (XORIG,XSTP,XMAX,6,1,100,-1,0,0.)
1 CALL YINTAX
GO TO 2710
IF (OPTION,NE,5.) GO TO 2490
CALL XTTICKS (2)
CALL XREVTK
CALL XGRAXS (XORIG,XSTP,XMAX,6,5,100,0,0,-.75)
1 CALL XINTAX
GO TO 2710
IF (OPTION,NE,6.) GO TO 2500
CALL YTTICKS (2)
CALL YREVTK
CALL YGRAXS (XORIG,XSTP,XMAX,8,1,100,-1,15,0.)
1 CALL YINTAX
GO TO 2710
IF (OPTION,NE,7.) GO TO 2510
CALL XTTICKS (2)
CALL XNAME ('',1)
GO TO 2710
CONTINUE
GO TO 2700
IF (Z,NE,29.) GO TO 2610
DO 2530 I=1,8
X(I)=FWT(I)
CONTINUE
XORIG=C.
XSTP=3000.
XMAX=21000.
IF (OPTION,NE,1.) GO TO 2540
CALL XTTICKS (3)
CALL XNAME ('FUEL WEIGHT (LB)$',100)
CALL XINTAX
GO TO 2710
IF (OPTION,NE,2.) GO TO 2550
CALL YTTICKS (3)
CALL YNAME ('FUEL WEIGHT (LB)$',100)
CALL YINTAX

```

2470

2480

2490

2500

2510

2520

2530

2540

2550	GO TO 2710 IF (OPTION.NE.3.) GO TO 2560 CALL XTICKS (3) CALL XREVTK CALL XGRAXS (XORIG,XSTP,XMAX,9.,100,0.,-.75)
2560	1 CALL XINTAX GO TO 2710 IF (OPTION.NE.4.) GO TO 2570 CALL YTICKS (3) CALL YREVTK CALL YGRAXS (XORIG,XSTP,XMAX,6.,100,-1.,0.)
2570	1 CALL YINTAX GO TO 2710 IF (OPTION.NE.5.) GO TO 2580 CALL XTICKS (3) CALL XREVTK CALL XGRAXS (XORIG,XSTP,XMAX,6.5,100,0.,-.75)
2580	1 CALL XINTAX GO TO 2710 IF (OPTION.NE.6.) GO TO 2590 CALL YTICKS (3) CALL YREVTK CALL YGRAXS (XORIG,XSTP,XMAX,8.,100,-1.15,0.)
2590	1 CALL YINTAX GO TO 2710 IF (OPTION.NE.7.) GO TO 2600 CALL XTICKS (3) CALL XNAME (.,1)
2600	GO TO 2710 CONTINUE
2610	GO TO 2700 IF (2.NE.30.) GO TO 2700 DO 2620 I=1,8 X(I)=MGW(I)
2620	CONTINUE XORIG=0. XSTP=30000. XMAX=90000. IF (OPTION.NE.1.) GO TO 2630 CALL XTICKS (3) CALL XNAME (MAXIMUM GROSS WEIGHT (LB)\$,100)
2630	CALL XINTAX GO TO 2710 IF (OPTION.NE.2.) GO TO 2640


```

2640      CALL YTICKS (3)
          CALL YNAME ('MAXIMUM GROSS WEIGHT (LB)$',100)
          CALL YINTAX
          GO TO 2710
          IF (OPTION,NE,3.) GO TO 2650
          CALL XTICKS (3)
          CALL XREVTK
          CALL XGRAXS
          1 CALL XINTAX
            GO TO 2710
            IF (OPTION,NE,4.) GO TO 2660
            CALL YTICKS (3)
            CALL YREVTK
            CALL YGRAXS
            1 CALL YINTAX
              GO TO 2710
              IF (OPTION,NE,5.) GO TO 2670
              CALL XTICKS (3)
              CALL XREVTK
              CALL XGRAXS
              1 CALL XINTAX
                GO TO 2710
                IF (OPTION,NE,6.) GO TO 2680
                CALL YTICKS (3)
                CALL YREVTK
                CALL YGRAXS
                1 CALL YINTAX
                  GO TO 2710
                  IF (OPTION,NE,7.) GO TO 2690
                  CALL XTICKS (3)
                  CALL XNAME ('',1)
                  GO TO 2710
                  CONTINUE
                  GO TO 2700
                  CONTINUE
                  WRITE (6,2720)
                  CONTINUE
                  CALL RESET ('XREVTK')
                  CALL RESET ('YREVTK')
                  RETURN
2720      FORMAT (54H YOU HAVE MADE A MISTAKE AND ENTERED AN INVALID NUMBER)
          END
          (XORIG,XSTP,XMAX,9, (LB)$,100,0.,-.75)
          (XORIG,XSTP,XMAX,6, (LB)$,100,-1.,0.)
          (XORIG,XSTP,XMAX,6.5, (LB)$,100,0.,-.75)
          (XORIG,XSTP,XMAX,8, (LB)$,100,-1.15,0.)

```


APPENDIX B

A. USERS GUIDE TO THE CONCEPTUAL DESIGN PROGRAM

The design program has been developed with the user in mind. The program is completely interactive in that it prompts the user for any inputs needed. The following steps should be taken to invoke the program and to get an output file useable for analysis.

1. Logon as normal on either the IBM 3278 or the Tektronix 618 dual screen system
2. Obtain temporary storage space by typing in:

DEFINE STORAGE 1M (enter)
3. When PSW '00020000 00000 000' appears on the screen type in:

I CMS (enter)
4. If the program has not been compiled on your disk yet type in the following:

FORTGI DESIGN (enter)
5. After the program has been compiled you are ready to run the program by typing in:

DISSPLA (enter)
6. You will be asked to enter library functions or to press enter. Press the enter key.
7. You will then be asked if you want additional temporary space for shading, etc.. Again, press the enter key.
8. Next you will be asked to enter any defined files that you want. Here you should enter the following:

FILEDEF 08 DISK DESIGN (file name)

9. After entering the above line the screen will flash and your FILEDEF should be listed on the bottom line of the existing FILEDEFS. If your filedef is listed press the enter key to start the program execution.
10. Follow the instructions given on the screen. You will need the Helicopter Design Manual and the appropriate handouts/references to complete the process.
11. If you are on the IBM 3278 terminal you will not get a graph, therefore, you must plot the total power data by hand and extrapolate the needed data
12. If you are using the TEK 618 dual screen system a graph will be drawn of the total power curve and its components at altitude which can immediately be used to extrapolate the necessary data to complete the entire design process.
13. Note that the output file of all the information that you have computed is in the file that you have defined. To get your data type in:

PRINT DESIGN (filename) (CC

B. PROGRAM NOMENCLATURE

<u>MNEMONIC</u>	<u>DEFINITION</u>
A	Sonic speed at standard sea level
AALT	Sonic speed at specification density altitude
AASLY	Average aircraft serviceable life in years
AFHPF	Average flight hours per flight
AFHPY	Average flight hours per year per airframe
ALPHA	Ordinate intercept of fuel flow-horsepower curve
ALT	Maximum rate of climb calculation altitude
ALTSC	Service ceiling altitude
AMAX	Steady flow stall angle of the airfoil

ANS	General variable for keyboard answer
AR	Aspect ratio of the main rotor system
AREAMR	Area of the main rotor disc
AREATR	Area of the tail rotor disc
ARTR	Aspect ratio of the tail rotor
ARVS	Vertical stabilizer aspect ratio
AVAIL	Availability of an engine
AVAILM	Availability (multiple engine)
A11	Term in definition of THETA2
A12	Term in definition of THETA2
A13	Term in definition of THETA2
A14	Term in definition of THETA2
A80	Vertical stabilizer angle of attack at 80 knots
A90	Angle of attack of the advancing blade (radians)
A160	Vertical stabilizer angle of attack at 160 knots
A90D	Angle of attack of the advancing blade (degrees)
A270	Angle of attack of retreating blade (radians)
A270D	Angle of attack of retreating blade (degrees)
B	Main rotor tip loss factor
BETA	Slope of the fuel flow horsepower curve
BH	Main rotor tip loss factor at a hover
BL	Blade loading of the main rotor system
BLADES	Number of main rotor blades

BLADTR	Number of tail rotor blades
BS	Term used in inboard stall analysis
BTA	Tail rotor tip loss factor at altitude
BTR	Tail rotor tip loss factor
BVS	Span of the vertical stabilizer
CDO	Coefficient of drag of a main rotor blade
CDOTR	Coefficient of drag of a tail rotor blade
CHORD	Chord of a main rotor blade
CHORDT	Chord of a tail rotor blade
CL	Coefficient of lift of a main rotor blade section
CLA	Lift curve slope of a main rotor blade section
CLMAX	Maximum coefficient of lift for a blade section
CL80	Section coefficient of lift at 80 knots
CL160	Section coefficient of lift at 160 knots
COLL	Collective position (radians)
COLLD	Collective position (degrees)
COMPAR	Weight variance parameter
CONST	Constant value in ICAO formulae
COUNT	Counter variable
CPC	Correction to power coefficient
CPS	Correction to power coefficient due to stall
CREW	Number of specified crew
CS	Term used in stall analysis

CT	Main rotor coefficient of thrust
CTH	Main rotor coefficient of thrust at a hover
CTTA	Tail rotor coefficient of thrust at altitude
CTTR	Tail rotor coefficient of thrust at sea level
CYCD	Cyclic position (degrees)
CYCLIC	Cyclic position (radians)
C1	Cost of main rotor
C2A	Cost of tail rotor
C2B	Cost of tail rotor structure
C3	Cost of body
C4	Cost of landing gear
C5	Cost of nacelle
C6A	Cost of engine
C6B	Cost of drive system
C6C	Cost of fuel tanks
C7	Cost of flight controls
C8	Cost of auxillary power
C9	Cost of instruments
C10	Cost of hydraulics
C11	Cost of electrical system
C12	Cost of avionics
C13	Cost of furnishings
C14	Cost of air and ice

C15	Cost of load and handling
D	Diameter of the rotor system
DA270	Blade angle of advancing blade (degrees)
DELTA	Fuel flow ratio
DERR	Error function
DL	Disc loading of the main rotor system
DLAMB	Term used in blade stall analysis
DP	Parasite drag
DREF	Acceptable error function
DW	Powerplant dry weight of an engine
DWG	Design gross weight
DWM	Powerplant dry weight (multiple engine)
D1	Stall analysis parameter
D2	Stall analysis parameter
EFPAFF	Effective flat plate area (horizontal)
EFPAVF	Effective flat plate area (vertical)
EIW	Engine installed weight
EIWM	Engine installed weight (multiple engine)
ENGSEL	Engine selected
ESHPR	Estimated shaft horsepower required to hover
EW	Estimated engine weight from weight estimations
EWNEW	New engine weight using powerplant data
EXCESS	Excess weight

E1	Stall analysis parameter
E2	Stall analysis parameter
E3	Stall analysis parameter
FL	Factor for landing gear weight approximation
FSLT	Length of the fuselage
FSLTS	Specification maximum length of the fuselage
FUEL	Amount of fuel in pounds
FW	Fuel weight in pounds
FWNEW	Change in original fuel weight for printout
GALIN	Internal fuel weight in gallons
GALOUT	External fuel weight in gallons
GAM	Stall analysis parameter
GWSPEC	Specification maximum gross weight
HL	Life of the aircraft
HOVIGE	Specification hover ceiling (in ground effect)
HP	Hover power of the main rotor system (out of ground effect)
ht	Rotor system height above the ground
I	Do loop parameter
IC	Initial cost of an engine
ICM	Initial costs (multiple engine)
IER	Library function error code
IF	Installation fraction
IHP	Array for plotting

IR	Inflation rate in 1977 dollars
K	Dc loop parameter
KNOTS	Increment for forward speed
KNT	Increment for forward speed
KNTS	Knots increment for table
KS	Stall analysis parameter
LAMBDA	Stall analysis parameter
LAMB1	Stall analysis parameter
LAMFR	Used for reliability calculation
LCC	Life cycle cost of an engine
LCCM	Life cycle cost (multiple engine)
LERR	Acceptable error function
LG	Type of landing gear
LOAD	Loading used to find effective flat plate area
LREF	Acceptable error function
LTR	Length of the tail rotor
M	Figure of merit
MACH	Maximum allowable Mach number at sea level
MACHT	Main rotor system tip Mach number
MAINT	Maintainability of an engine
MAINTM	Maintainability (multiple engine)
MAXRC	Specification rate of climb
MAXV	Maximum forward velocity in feet per second

MCRIT	Critical Mach number
MCRO	Zero angle of attack critical Mach number
MD	Drag divergence Mach number
MDT	Mean down time of an engine
MTBF	Mean time between engine failures
MTBMA	Mean time between maintenance actions per engine
MTBR	Mean time between repairs for an engine
MTBRM	Mean time between repair (multiple engine)
MTIP	Tip Mach number of the main rotor system
MTTR	TIP MACH NUMBER OF THE TAIL ROTOR SYSTEM
MU	Advance ratio of the main rotor system
MUTR	Advance ratio of the tail rotor system
N	Do loop parameter
NDEG	Order of differential equation
NENG	Number of engines
NEWUSE	New useful load
NN	Do loop parameter
NRPL	Number of engine replacements (real or integer)
NRPLM	Number of engine replacements (multiple engine)
NW	Number of landing gear
NXRPL	Number of engine replacements (integer)
NXRPLM	Number of engine replacements (multiple engine)
OC	Operating cost of an engine

OLD	Previous gross weight used for comparison
OMEGA	Main rotor rotational velocity (radians)
OMEGTR	Tail rotor rotational velocity (radians)
PA	Specification pressure altitude
PADJA	Adjusted power at altitude
PADJS	Adjusted power at sea level
PALT	Rate of climb pressure
PAVAIL	Power available
PC	Power to climb
PCMPA	Array for compressible power at altitude
PCMPs	Array for compressible power at sea level
PEOPLE	Number of people
PI	Induced power of the main rotor system
PIE	Constant for value of π
PIHP	Induced power of the main rotor system in HP
PITLF	Induced power (IGE) at a forward speed
PITLFA	Induced power at altitude at forward speed
PITLFS	Induced power at sea level at forward speed
PITLGE	Induced power in ground effect
PITLGH	Induced power at a hover
PITLH	Induced power at a hover
PITLTF	Induced power of the tail rotor in forward flight
PITLTR	Induced power for the tail rotor

PITRFA	Induced power of the tail rotor at altitude in forward flight
PITRFS	Induced power of the tail rotor at sea level in forward flight
PIVERT	Induced power vertically
PIX	Array used for plotting of total induced power at sea level
PIY	Array used for plotting total induced power at altitude
PM	Preventative maintenance cost of an engine
PMBS	Blade stall power factor
PO	Profile power of the main rotor system
POC	Profile power to climb
POF	Profile power at a forward speed
POFA	Profile power at altitude at forward speed
POFS	Profile power at sea level at forward speed
POH	Profile power at a hover
POHP	Profile power of the main rotor system in HP
POTA	Profile power of tail rotor at altitude
POTR	Profile power for the tail rotor
POTRF	Profile power of the tail rotor in forward flight
POTRFA	Profile power of the tail rotor at altitude in forward flight
POTRFS	Profile power of the tail rotor at sea level in forward flight
POX	Array used for plotting of total profile power at sea level
POY	Array used for plotting total profile power at altitude

PP	Parasite power
PPC	Parasite power to climb
PPF	Parasite power at a forward speed
PPFA	Parasite power at altitude at forward speed
PPFS	Parasite power at sea level at forward speed
PPOGE	In ground effect distance parameter
PPOGEH	Ground effect factor at a hover
PPX	Array used for plotting total parasite power at sea level
PPY	Array used for plotting total parasite power at altitude
PRESS	Specification pressure altitude
PS	Stall power
PSHP	Phantom shaft horsepower
PT	Total power of the main rotor system
PTACH	Total power for the aircraft to hover
PTAH	Total power of the aircraft to hover
PTAVAL	Total power available
PTF	Total power at a forward velocity
PTFA	Total power at altitude at forward speed
PTFS	Total power at sea level at forward speed
PTH	Total power at a hover
PTHOVS	Total power to hover
PTHP	Total power of the main rotor system in HP
PTTAHP	Total power of the aircraft to hover in HP

PTTRF	Total power of the tail rotor in forward flight
PTTRFA	Total power of the tail rotor at altitude in forward flight
PTTRFS	Total power of the tail rotor at sea level in forward flight
PTTRH	Total power for the tail rotor at a hover
PTTRHP	Total power for the tail rotor at a hover in HP
PTVERT	Total power vertically
PTX	Array used for plotting total power at sea level
PTY	Array used for plotting total power at altitude
Q	Production run quantity
R	Rotor radius
RBS	Retreating blade stall velocity
RC	Recovery cost of an engine
RCLIMB	Rate of climb
RCM	Recovery cost (multiple engine)
RDC	Research and development cost of an engine
RDCM	Research and development costs (multiple engine)
RELY	Reliability of an engine
RELYM	Reliability (multiple engine)
REVWE	Revised empty weight
REVWG	Revised gross weight
RHOALT	Density at specification density altitude
RHOMH	Density at hover in ground effect ceiling
RHOS	Density at service ceiling

RHOSC	Service ceiling density
RHOSL	Sea level density
RNGMAX	Maximum range as per specification
RNGNMX	New maximum range
RSHPC	Required shaft horsepower for cruise
RSHPME	Required shaft horsepower for max endurance speed
RSHRME	Total required shaft horsepower for max endurance
RSHPRC	Total required shaft horsepower for cruise
RRSHP	Required shaft horsepower
RSHPM	Required shaft horsepower (military)
RSPEC	Specification maximum rotor radius
RT	Stall analysis parameter
RTR	Tail rotor radius
S	Main rotor planform area for weight estimation
SB	Body surface area for weight estimation
SC	Specification service ceiling
SFCC	Cruise specific fuel consumption
SFCM	Military specific fuel consumption
SFCN	Normal specific fuel consumption
SHPC	Cruise shaft horsepower
SHPM	Military shaft horsepower
SHPMN	Military shaft horsepower (multiple engine)
SHPN	Normal shaft horsepower

SIG	Pressure ratio
SIGMA	Solidity of the main rotor system
SIGTR	Solidity of the tail rotor system
SIM	Weight variance parameter
SPCLOD	Specification useful load
STEP	Variance parameter for iterations
STT	Total tail surface area for weight estimation
SV	Salvage value
SVM	Salvage value (multiple engine)
TALT	Rate of climb temperature
TEMP	Specification temperature
THETA	Temperature ratio
THETA0	Collective angle in radians
THETA2	Cyclic angle in radians
TOTALC	Total cost of an aircraft in a production run
TRIP1	Trips the program so that repetitive questions are repeated
TRIP2	Trips the program so that repetitive questions are repeated
TRIP3	Trips the program so that repetitive questions are repeated
TRIP4	Trips the program so that repetitive questions are repeated
TRIP5	Trips the program so that repetitive questions are repeated
TSHP	Total shaft horsepower
TTR	Thrust of the tail rotor

TTR80	Tail rotor thrust at 80 knots
TTR160	Tail rotor thrust at 160 knots
TWIST	Twist of main rotor blade
TYPE	Type of helicopter (light,medium,heavy)
TYPEM	Type of aircraft (light,medium,heavy)
T1	Term used in defining THETA0
T2	Term used in defining THETA0
T3	Term used in defining THETA0
T4	Term used in defining THETA0
USELOD	Useful load desired
VCR	Cruise velocity as per specification
VELMAX	Maximum forward velocity
VF	Forward velocity
VFWD	Forward velocity
VF80	Forward velocity at 80 knots in ft/sec
VF160	Forward velocity at 160 knots in ft/sce
VI	Induced velocity in a hover
VINEW	Induced velocity at hover
VIT	Vertical induced velocity at a hover
VITNEW	Induced vertical velocity at a hover
VITR	Induced velocity of the tail rotor
VITTR	Induced vertical velocity of the tail rotor
VL	stall parameter

VMAX	Specification maximum forward velocity
VMAXE	Maximum endurance velocity
VMAXF	Maximum forward velocity in knots
VMAXK	Initial forward velocity for stall analysis
VMAXR	Maximum range velocity
VOPT	Optimum velocity for aircraft in ft/sec
VOPTK	Optimum velocity for aircraft in knots
VS	Forward speed in ft/sec
VSK	Forward speed in knots
VTIP	Tip velocity of the main rotor system
VTIPTR	Tail rotor tip velocity
VTNEW	Solution to fourth order differential equation
VVERT	Vertical velocity
WE	Manufacturers empty weight
WFC	Cruise fuel flow rate
WFCR	Fuel flow rate for cruise flight
WFM	Military fuel flow rate
WFME	Fuel flow rate for max endurance velocity
WFN	Normal fuel flow rate
WG	Gross weight
WGNEW	New gross weight
WXO	Transmission and oil weight
WXOM	Transmission and oil weight (multiple engine)

W1	Rotor weight
W2A	Tail rotor weight
W2B	Tail rotor structure weight
W3	Body weight
W4	Landing gear weight
W5	Nacelle weight
W6A	Engine weight
W6B	Drive weight
W6C	Fuel tank weight
W7	Flight control weight
W8	Auxillary power weight
W9	Instrument weight
W10	Hydraulic weight
W11	Electrical weight
W12	Avionics weight
W13	Furnishings weight
W14	Air and ice weight
W15	Load and handling weight
XO	Radius used for stall analysis (inboard)
XRLG	Fixed or retractable landing gear
XS	Radius outboard analysis
YMC	Yearly maintenance cost of an engine
YMCM	Yearly maintenance costs (multiple engine)

YOC	Yearly operating cost of an engine
YOCM	Yearly operating costs (multiple engine)
ZCMPLX	Array for library function
ZHI	Zero horsepower intercept

C. PROGRAM LISTING

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REAL TRI1, TRI2, TRI3, TRI4, SC, HOVIGE, RSPEC, FSLTS, MAXRC, SPCLOD, TR
1IP5, COUNT/O., IR
REAL WG, GWSPEC
REAL WE
REAL A, MACH, VMAX, PIE, RHOSL
REAL DL, R, AREAMR
REAL OMEGA
REAL VTIP, CT
REAL VMAXF, MAXV, MU, BL, SIGMA
REAL CHORD, AR
REAL CLA, CDC
REAL CL, PI, PC, PT, PIHP, PQHP, PTHP, HP
REAL B, FUEL, USELOD, STT, SB, S, W1, W2A, W2B, W3, W4, W5, W6A, W6B, W6C, W7, W8, W9
1, W10, W11, W12, W13, W14, W15, REVWE, REVWG, TYPE
REAL MANS, CLD/O.,
REAL STEP, FL, LG, XRLG, NW
REAL H, D, PPCGE, PITLGE, PTHOVS
REAL LCAC, EFPAFF, KNTS
REAL VF, PPF, POF, VI, VIT, PITLF, PTF, MACHT, PPFS(55), PQFS(55), PITLFS(55
1), PTFS(55), AALT, RHOALT, PPFA(55), POFA(55), PITLFA(55), PITFA(55), TEMP,
2THETA, PRESS, SIG, PA, CONST
REAL RTR, OMEGTR, CDOTR, LTR, ART, CHORDI, SIGTR
REAL AREATR, TTR, VTIPTR, CTIR, BTR, PITLTR, POTR, PTTRH, PTTRHP, CTTA, BTA,
1PITLTA, FCTA, PTTAH, PTTAHP
REAL MUTR, PCTRF, POTRFS(55), PITRFS(55), MTTR, POTRFA(55), P
1ITRFA(55), PTTRFA(55), VITR, VITTR, PITTRF, PITLTF
REAL TTR160, TTR80, VS, BVS, CL80, CL160, VF80, VF160, CLARVS, A80, A160, ARV
1S
REAL LAMBDA, KS, MCRIT, MTIP, LERR, MCRO, LAMBD1, CLMAX, VL, VMAXK, PCMPA(55
1), PCMPS(55), C1, C2, T1, T2, T3, T4, A11, A12, A13, A14, DP, DLAMB, LREF, E1, E2,
2E3, D1, C2, CYCLIC, COLL, TWIST, GAM, AMAX, BS, RT, XS, XO, CS, CPS, KS, PS, A90, A
3270, A90D, A270D, MD, CPC, TSHP, VOPF, VOPIK, VSK, T+ETA0, THETA2, DA270, DREF
4, DERR, PMBS, CYCD, COLLD
REAL PTAH, PCX(55), PIX(55), PPX(55), PTX(55), POY(55), PIY(55), PPY(55),
1PTY(55), KNOTS(55)
REAL PACJS, FADJA, RRSHP
REAL RHCS, CTH, BH, PITLH, PPOGEH, POH, PTH, RSHPM, PTACH, PITLGH
REAL ESHPR
REAL AFHPY, AFHPF, AASLY, HL, PM(6), OC(6), YMC(6), YOC(6), MTBR(6), NRPL(6
1), NXRPL(6), EIWL(6), RC(6), DW(6), IF(6), IC(6), SV(6), WXD(6), SHPM(6), LAM
2FR(6), MTBF(6), RELY(6), AVAIL(6), MTBMA(6), MDT(6), LCC(6), RDC(6), MAINT
3(6), DW(6), ICM(6), SHPM(6), RDCM(6), MTBRM(6), YDCM(6), YOCM(6), NRPLM(
46), NXRPLM(6), EIWM(6), RCM(6), SVM(6), WXOM(6), RELYM(6), AVAILM(6), LCCM
5(6), MAINTM(6), SHPC(6), SHPN(6), ENGSEL

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REAL EWNEW,WGNEW,W,COMPAR
REAL WFM,WFC,WFN,SFCN(6),SFCM(6),SFCC(6)
REAL BETA,ALPHA
REAL DELTA,ZHI
REAL PSFP,TYPEM,FSLT
REAL VMAXR
REAL VMAXE,RSHPM,RSHRME,WFME
REAL RSHPC,RSHPRC,WFCR,RNGMAX,VCR
REAL FW,GALIN,GALOUT,EXCESS
REAL DWG,RNGNMX,NEWUSE,SIM
REAL VVERT,EFPAVF,PC,VFWD,PPC,POC,PIVERT,VINEW,PAVAL,PTVER
1,REAL VNEW(5),VTNEW,RCLIMB
REAL ALT,PALT,TALT,RHOMH
REAL ALTSC,RHOSC
REAL TOTALC,Q,C1,C2A,C2B,C3,C4,C5,C6A,C6B,C6C,C7,C8,C9,C10,C11,C12
1,REAL CP,KNT,RBS,FWNEW,VELMAX
INTEG I,BLADES,NENG,PEOPLE,BLADTR,IHP(600),CREW,N,N,N,NDeg,IER/O/
1,K
COMPLX ZCMFLX(4)
DATA DW/158.,288.,423.,709.,580.,750./
DATA SHFM/420.,708.,1561.,1800.,2500.,3400./
DATA SHPN/370.,659.,1318.,1530.,2200.,3000./
DATA SHPC/278.,494.,989.,1148.,1650.,2250./
DATA SFCEM/.650.,.573.,.460.,.595.,.615.,.543/
DATA SFCN/.651.,.573.,.470.,.606.,.622.,.562/
DATA SFCC/.709.,.599.,.510.,.661.,.678.,.610/
DATA IC/93.,100.,580.,360.,640.,700./
DATA OC/.008.,.016.,.020.,.035.,.040.,.060/
DATA PM/.025.,.050.,.100.,.125.,.160.,.220/
DATA MTBMA/3.5,3.0,2.0,3.0,4.0,3.5/
DATA MDT/.7,6.,.5,1.3,2.,2.6/
DATA MTBF/185.,210.,205.,285.,280.,320./
DATA MTBR/60.,750.,800.,800.,1000.,750./
DATA RCC/0.,0.,.29.,.27.,.24.,.27./
DATA IF/.29.,.29.,.27.,.24.,.27.,.24/
DATA DERR/.001/,LEERR/.0001/
C*****
WRITE (6,1560)
READ (5,*) ANS
CALL FRICMS ('CLRS CRN 6')
IF (ANS.NE.1.) GO TO 10
CALL TEK618
GO TO 20
CONTINUE
TRIP5=5.
CONTINUE
TRIP1=0.
10
20

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```

TRIP2=0.
TRIP3=0.
TRIP4=0.
WRITE (6,2660) CREW
CALL FRICMS (6,2750) CLRS CRN 6")
WRITE (6,2750) SPC LOD
CALL FRICMS (6,2660) CLRS CRN 6")
WRITE (6,2660) FOV IGE
CALL FRICMS (6,2670) CLRS CRN 6")
WRITE (6,2670) SC
CALL FRICMS (6,1620) CLRS CRN 6")
WRITE (6,1620) VMAX F
CALL FRICMS (6,2370) CLRS CRN 6")
WRITE (6,2370) VCR
CALL FRICMS (6,2360) CLRS CRN 6")
WRITE (6,2360) RNG MAX
CALL FRICMS (6,2720) CLRS CRN 6")
WRITE (6,2720) MAX RC
CALL FRICMS (6,1570) CLRS CRN 6")
WRITE (6,1570) GWS PEC
CALL FRICMS (6,2650) CLRS CRN 6")
WRITE (6,2650) FSP EC
CALL FRICMS (6,2700) CLRS CRN 6")
WRITE (6,2700) FSL TS
CALL FRICMS (6,2050) CLRS CRN 6")
WRITE (6,2050) AFHPY
CALL FRICMS (6,2060) CLRS CRN 6")
WRITE (6,2060) AFHPF
CALL FRICMS (6,2070) CLRS CRN 6")
WRITE (6,2070) AASLY
CALL FRICMS (6,2640) CLRS CRN 6")
WRITE (6,2640) PA
CALL FRICMS (6,2640) CLRS CRN 6")

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WRITE (6,2650)
READ (5,*) TEMP
CALL FRICMS ('CLRSCRN 6')
WRITE (6,2820)
READ (5,*) IR
CALL FRICMS ('CLRSCRN 6')
C*****
C*****
C*****
2.1 MAKE A ROUGH ESTIMATE OF GROSS WEIGHT
C*****
C*****
WRITE (6,1550)
READ (5,*) WG
CALL FRICMS ('CLRSCRN 6')
WG=0.8*WG
WRITE (6,1600) WG
C*****
C*****
2.2 MAKE A ROUGH ESTIMATE OF THE MANUFACTURER'S EMPTY
C*****
C*****
C*****
WRITE (6,1580)
READ (5,*) WE
CALL FRICMS ('CLRSCRN 6')
C*****
C*****
C*****
2.3 CALCULATE THE MAXIMUM TIP VELOCITY
C*****
C*****
A=1116.89
MACH=0.65
VMAX=MACH*A
PIE=3.1415927
RHOSL=0.0023769
C*****
C*****
2.4 DETERMINE THE ROTOR RADIUS
C*****
C*****
WRITE (6,1610) WG
READ (5,*) CL
CALL FRICMS ('CLRSCRN 6')
R=SQR(T(WG/(PIE*CL)))
AREAMR=PIE*R**2
C*****
C*****
2.5 DETERMINE A FIRST-CUT ROTATIONAL VELOCITY
C*****
C*****
OMEGA=VMAX/R
C*****
C*****
2.6 MAKE A FIRST-CUT DETERMINATION OF THRUST
C*****
C*****
C*****
CONTINUE
VTIP=OMEGA*R
CT=WG/(AREAMR*RHOSL*VTIP**2)
40

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```

130 READ (5,*) TYPE
    CALL FRICMS ('CLRSCRN 6')
    CONTINUE
    IF (TYPE.NE.1.) GO TO 160
    IF (TRIP2.EC.2.) GO TO 140
    WG=173.701*WE*.378
140 CONTINUE
    STT=.264*EXF(.0135*HP)
    SB=194.274*ALOG(WG)-1306.779
    S=CHORD*(FLCAT(BLADES))*R
    W1=408.562*ALOG(S)-1142.917
    W2A=2.215*EXP(.0005*WG)
    W2B=19.131*ALOG(STT)-32.414
    W3=.00901*SE*.917
    IF (COUNT.NE.0.) GO TO 150
    W4=-.0539*WG+200.912
    CONTINUE
150 W5=34.
    W6A=-.0896*HP+221.338*FLOAT(NENG)
    W6B=17.190*EXP(.0008*WG)
    W6C=.384*(FUEL/6.5)**1.0717
    W7=(1.28E-10)*WG**3.469
    W8=0.
    W9=24.571*EXP(.0004*HP)
    W10=0.
    W11=-.51.0661*ALOG(SB)+367.947
    W12=1062.00451-122.282*ALOG(1120.354*EXP(.003*HP))
    W13=19.800*(EXP(.372*FLCAT(PEOPLE))+EXP(-.033*SB))
    W14=-22.371*ALOG(SB)+143.396
    W15=0.
    GO TO 270
160 IF (TYPE.NE.2.) GO TO 240
    IF (TRIP2.EC.2.) GO TO 170
    WG=16239.43*ALOG(WE)-130252.76
170 CONTINUE
    STT=.0376*HF-8.106
    SB=636.081*EXP(.000011*WG)
    S=CHORD*(FLCAT(BLADES))*R
    W1=11.0702*WG+12.470
    W2A=.00438*WG+12.470
    W2B=2.411*STT-19.531
    W3=.282*SB*.1.272
    IF (COUNT.NE.0.) GO TO 190
    IF (WG.GT.600.) GO TO 180
    W4=.025*EXP(.0000062*WG+8.020)
    GO TO 190
    W4=301.577*ALOG(WG)-2319.890
180 CONTINUE
190

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200 W5=.02*EXP(.000062*WG+8.02)
210 IF (NENG.NE.1.) GO TO 200
W6A=130.0+.451*HP
GO TO 210
W6A=(295.0+.188*HP)*FLOAT(NENG)
W6B=(741.460*ALCG(HP)-4542.0420)
W6C=(363.24*ALOG(FUEL/6.5)-1656.521)
W7=210.858*EXP(.000059*WG)
IF (NENG.NE.1.) GO TO 220
W8=0.0
GO TO 230
W8=190.0
W9=56.0975*ALOG(HP)-312.237
W10=0.00362*WG+11.553
W11=481.735*ALOG(SB)-2794.53
W12=.135*HP+77.823
W13=.175*SB+22.*FLOAT(PEOPLE)-10.
W14=122.468*ALOG(SB)-730.252
W15=84.5
GO TO 270
CONTINUE
240 IF (TRIP2.EC.2.) GO TO 250
WG=4.975*WE*.887
CONTINUE
250 STT=60.127*EXP(.000145*HP)
SB=426.378*EXP(.000045*WG)
S=CHORC*(FLCAT(BLADES))*R
W1=707.174*EXP(.00539*S)
W2A=324.550*ALOG(WG)-3021.510
W2B=-18.42.83*STT
W3=2.9818*SB-1321.921
IF (COUNT.NE.0.) GO TO 260
W4=258.358*EXP(.000041*WG)
CONTINUE
260 W5=.014*(.2041*WG)*.1.136
W6A=(348.+.510*HP)*FLOAT(NENG)
W6B=(.959*HF*.959)
W6C=(454.619*(FUEL/6.5))*(-.0566)
W7=.00334*WG*.1.224
W8=139.0
W9=68.266*ALOG(HP)-387.598
W10=(6.63E-7)*WG*.1.863
W11=.9.780*SE*.539
W12=(16744.567*ALOG(HP)-108666.)*.536*.1.90
W13=.159*SB+18.11*FLOAT(PEOPLE)
W14=117.771*ALOG(SB)-710.594
W15=-72.+.111*SB+3.49*FLOAT(PEOPLE)
CONTINUE
270

```



```

RE VWE = W1+W2A+W2B+W3+W4+W5+W6A+W6B+W6C+W7+W8+W9+W10+W11+W12+W13+W14
1+W15
RE VWG = REVWE+FUEL+USELOD
WRITE (6,1760) B,PIHP,POHP,PTHP,WE,FUEL,PEOPLE,USELOD,NENG,WG,SIGM
1A,R,HP,W1,W2A,W2B,W3,W4
WRITE (6,1770) W5,W6A,W6B,W6C,W7,W8,W9,W10,W11,W12,W13,W14,W15,REV
1WE,REVWG
WRITE (8,1760) B,PIHP,POHP,PTHP,WE,FUEL,PEOPLE,USELOD,NENG,WG,SIGM
1A,R,HP,W1,W2A,W2B,W3,W4
WRITE (8,1770) W5,W6A,W6B,W6C,W7,W8,W9,W10,W11,W12,W13,W14,W15,REV
1WE,REVWG
C*****
C 3 VALIDATE DISC LOADING
C*****
WRITE (6,1800) WG
READ (5,*) ANS
CALL FRICMS (,CLRSCRN 6,*)
IF (ANS.NE.1.) GO TO 280
WRITE (6,1810)
CALL FRICMS (,CLRSCRN 6,*)
WG=REVWG
WE=REVWE
TRIPI=1.
TRIPI2=2.
GO TO 300
CONTINUE
C*****
C 3.4 ESTABLISH FIGURE OF MERIT AT APPROXIMATELY 0.75
C*****
M=(PI/PT)*100.
WRITE (6,1780) M
WRITE (8,1780) M
CONTINUE
WRITE (6,1790)
READ (5,*) ANS
CALL FRICMS (,CLRSCRN 6,*)
IF (ANS.NE.1.) GO TO 300
TRIPI=1.
TRIPI2=2.
WG=REVWG
WE=REVWE
OLD=REVWG
GO TO 300
IF (ANS.NE.2.) GO TO 310
WRITE (6,2270) CHORD
WRITE (6,1810)
READ (5,*) CHORD

```



```

CALL FRICMS ('CLRSCRN 6')
WG=REVWVG
WE=REVWVE
OLD=REVWVG
SIGMA=(FLOAT(BLADES)*CHORD)/(PIE*R)
TRIP1=1.
TRIP2=2.
GO TO 7C
IF (ANS.NE.2.) GO TO 320
WRITE (6,16E0)
READ (5,*) CMEGA
CALL FRICMS ('CLRSCRN 6')
TRIP1=1.
TRIP2=2.
WE=REVWVE
WG=REVWVG
OLD=REVWVG
GO TO 4C
320 CONTINUE
C*****
C3.5 REFINE GROSS WEIGHT ESTIMATE
C*****
IF (COUNT.GE.2.) GO TO 360
COUNT=CCOUNT+1.
IF (COUNT.GT.1.) GO TO 330
WRITE (6,27E0)
READ (5,*) LG
CALL FRICMS ('CLRSCRN 6')
CONTINUE
IF (BLADES.GT.2) FL=4.
IF (BLADES.LT.3) FL=2.
IF (LG.NE.1.) GO TO 350
IF (COUNT.GT.1.) GO TO 340
WRITE (6,27E0)
READ (5,*) XRLG
CALL FRICMS ('CLRSCRN 6')
WRITE (6,28E0)
READ (5,*) NW
CALL FRICMS ('CLRSCRN 6')
CONTINUE
W4=.4013*(WG**.6662)*(NW**.536)*((XRLG**.1198)
WG=REVWVG
WE=REVWVE
OLD=REVWVG
GO TO 12C
340 CONTINUE
W4=.0245*(WG**.8606)*(FL**.8046)
WG=REVWVG

```



```

WE=REVWE
OLD=REVWG
GO TO 120
C*****
C 3. 6 MAKE THIRD ESTIMATE OF POWER REQUIRED TO HOVER
C*****
C 3. 7 REPEAT THE GROSS WEIGHT ESTIMATE AND THE HOVER
C POWER ITERATIONS
C*****
360 CONTINUE
STEP=1.-(OLD/REVWG)
IF (STEP.LT.0.1) GO TO 370
WRITE (6,2740)
GO TO 250
IF (STEP.GT.-.1) GO TO 380
WRITE (6,2740)
GO TO 250
CONTINUE
WG=REVWG
IF (TRIP3.EC.3.) GO TO 390
C*****
C 3. 8 DETERMINE THE POWER REQUIRED TO HOVER IGE, SSL
C*****
WRITE (6,1820)
READ (5,*) F
CALL FRFCMS ('CLRSCRN 6')
H=H+10.
CONTINUE
390 D=2.*R
PPOGE=-.127E*(H/D)**4+.7080*(H/D)**3-1.4569*(H/D)**2+1.3432*(H/D)+
1.5147
PITLGE=PPOGE*PI
PTHOVS=PITLGE+PO
C*****
C 3. 9 DETERMINE EQUIVALENT FLAT PLATE AREA (HCRIZONTAL)
C*****
WRITE (6,16C0) WG
WRITE (6,1830)
READ (5,*) LOAD
CALL FRFCMS ('CLRSCRN 6')
EFPAFF=WG/LCAD
KNITS=0.
WRITE (6,1840)
WRITE (6,1840)
C*****
C 3. 10 DETERMINE TOTAL POWER REQUIRED AND TIP MACH
C*****
C NUMBER
C*****

```



```

NN=AIN T(MAXV/5.)+1
N=AIN T(MAXV/5.)+11
DO 400 I=1,N
VF=KNTS*1.151*5280./3600.
PPF=.5*RHQSL*(VF**3)*EPPAFF
PPF=PPF/550.
MU=VF/V TIP
POF=(1.+4.3*MU**2)*PO
POF=POF/550.
VI=SQRT(WG/(2.*RHOSL*AREAMR))
VI T=VI*SQRT((- (VF**2/(2.*VI**2))**2)+1.)
1
PI TLF=(1./B)*WG*VI T
PI TLF=PI TLF/550.
PTF=PI TLF+PCF+PPF
MACHT=(VF+V TIP)/A
PPFS(I)=PPF
POFS(I)=POF
PI TIFS(I)=PI TLF
PTFS(I)=PTF
WR ITE (6,1850) KNTS,MACHT,PI TLF,POF,PPF,PTF
WR ITE (8,1850) KNTS,MACHT,PI TLF,POF,PPF,PTF
KNTS=KNTS+5.
CONTINUE
TEMP=TEMP+460.
THETA=TEMP/518.688
CONST=6.87535E-6
PRESS=2116.22*(1.-CONST*PA)**5.2561
SIG=PRESS/2116.22
RHOALT=.0023769*SIG*THETA
AALT=SQRT(1.4*32.174*53.3*TEMP)
WR ITE (6,1860)
WR ITE (8,1860)
KNTS=0.
DO 410 I=1,N
VF=KNTS*1.151*5280./3600.
PPF=.5*RHQALT*(VF**3)*EPPAFF
PPF=PPF/550.
MU=VF/V TIP
PO=.125*SIGMA*CD0*RHOALT*AREAMR*V TIP**3
POF=(1.+4.3*MU**2)*PO
POF=POF/550.
VI=SQRT(WG/(2.*RHOALT*AREAMR))
VI T=VI*SQRT((- (VF**2/(2.*VI**2))**2)+1.)
1
PI TLF=(1./B)*WG*VI T
PI TLF=PI TLF/550.
PTF=PI TLF+PCF+PPF

```



```

MACHT=(VF+VTIP)/AALT
PPFA(I)=PPF
POFA(I)=POF
PITLFA(I)=PITLF
PTFA(I)=PTF
WRITE(6,1850) KNTS,MACHT,PITLF,POF,PPF,PTF
WRITE(8,1850) KNTS,MACHT,PITLF,POF,PPF,PTF
KNTS=KNTS+5.
CONTINUE
C*****
C4.1 MAKE PRELIMINARY SIZING OF TAIL ROTOR *****
C*****
RTR=1.3*SQR(WG/1000.)
WRITE(6,1880) RTR
WRITE(8,1880) RTR
OMEGTR=4.5*CMEGA
WRITE(6,1850) CMEGTR
WRITE(8,1850) CMEGTR
CDOTR=1.38*COO
WRITE(6,1900) CDOTR
WRITE(8,1900) CDOTR
IF (TRIP3.EC.3.) GO TO 420
WRITE(6,1910)
READ(5,*) PLADTR
CALL FRICMS (.CLRCRN 6.)
CONTINUE
LTR=R+RTR+.5
IF (TRIP3.EC.3.) GO TO 430
WRITE(6,1920)
READ(5,*) ARTR
CALL FRICMS (.CLRCRN 6.)
CONTINUE
CHORDT=RTR/ARTR
SIGTR=(FLOAT(BLADTR)*CHORDT)/(PIE*RTR)
C*****
C4.2 DETERMINE TAIL ROTOR POWER REQUIRED AT HOVER *****
C*****
AREATR=PIE*RTR**2
VTIPTR=CMEGTR*LTR
CTTR=TTTR/(AREATR*RRHOSL*VTIPTR**2)
BTR=1.-SQR(2.*CTTR)/FLOAT(BLADTR)
PITLTR=(1./BTR)*(TTTR**1.5/SQR(2.*RHOSL*AREATR))
POTR=.125*SIGTR*CDOTR*RHOSL*AREATR*(VTIPTR**3)
PTTRHP=PITLTR+POTR
PTTRHP=PITLTR+POTR
CTTA=TTTR/(AREATR*RRHOSL*VTIPTR**2)
BTA=1.-SQR(2.*CTTA)/FLOAT(BLADTR)

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PITLTA=(1./PIA)*(TTR**1.5/SQRT(2.*RHOALT*AREATR))
POTIA=.125*SIGTR*CDOTR*RHOALT*AREATR*(VTIPTR**3)
PTIAHP=PTLTR/550.
***** DETERMINE TAIL ROTOR POWER REQUIRED FOR FORWARD
***** FLIGHT
4.3
*****
4.5 DETERMINE MAXIMUM TIP MACH NUMBER FOR FORWARD
***** FLIGHT
*****
KNTS=0.0
WRITE (6,1930)
WRITE (8,1930)
DO 440 I=1,N
VF=KNTS*1.151*5280./3600.
MUTR=VF/VTIFTR
POTRF=(1.+4.3*MUTR**2)*POTR
POTRF=POTRF/550.
PTF=PTFS(I)
TTR=((PTF*550.)/(OMEGA*LTR))
CTTR=(TTF/(AREA*RHOSL*(VTIPTR**2)))
BTR=1.-SQRT(2.*CTTR)/FLOAT(BLADTR)
VTITR=SQRT(TTR/(2.*RHOSL*AREATR))
VTITR=VTITR*SQRT((- (VF**2/(2.*VTTR**2))
1+SQRT((VF**2/(2.*VTTR**2))+1.)))
PITLTF=(1./BTR)*TTR*VTITR
PITLTF=PITLTF/550.
POTRF=PITLTF+POTRF
POTFS(I)=POTRF
PITLTF=PTLTF
PITRFS(I)=PITLTF
PITRFS(I)=PITRFS(I)/A
MTTR=(VF+VTIPTR)/A
WRITE (6,1950) KNTS,MTTR,PITLTF,POTRF,PITRFS
WRITE (8,1950) KNTS,MTTR,PITLTF,POTRF,PITRFS
KNTS=KNTS+5.
CONTINUE
WRITE (6,1940)
WRITE (8,1940)
KNTS=0.0
DO 450 I=1,N
VF=KNTS*1.151*5280./3600.
MUTR=VF/VTIPTR
POTR=.125*SIGTR*CDOTR*RHOALT*AREATR*VTIPTR**3
POTRF=(1.+4.3*MUTR**2)*POTR
POTRF=POTRF/550.
PTF=PTFA(I)
TTR=((PTF*550.)/(OMEGA*LTR))

```

440


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CTTR=TTTR/(AREA*TR*(VTIPTR**2)*RHOALT)
BTTR=1.-SQRT(2.*CTTR)/FLOAT(BLADTR)
VTTR=SQRT(TTR/(2.*RHOALT*AREATR))
VTTR=VTTR*SQRT((- (VF**2/(2.*VTTR**2)))
1+SQRT(((VF**2/(2.*VTTR**2))*2)+1.))
PITLTF=(1./ETR)*TTR*VTTR
PITLTF=PITLTF/550.
POTRF=PITLTF+POTRF
POTRFA(1)=POTRF
POTRFA(1)=PITLTF
POTRFA(1)=POTRF
MTTR=(VF+VTIPTR)/AALT
WRITE(6,1950) KNTS,MTTR,PITLTF,POTRF,PITRF
WRITE(8,1950) KNTS,MTTR,PITLTF,POTRF,PITRF
KNTS=KNTS+5.
CONTINUE
450 *****
C *****
C *****
4. 4 VERTICAL STABILIZER *****
IF (TRIP3.EC.3.) GO TO 460
WRITE(6,2960)
READ(5,*) EVS
CALL FRICMS ('CLRSCRN 6')
WRITE(6,2970) SIGTR
READ(5,*) VS
CALL FRICMS ('CLRSCRN 6')
CONTINUE
VF80=80.*1.151*5280./3600.
VF160=160.*1.151*5280./3600.
ARVS=BVS**2/VS
TTTR80=(PTFS(17)*550.)/(LTR*OMEGA)
TTTR160=(PTFS(34)*550.)/(LTR*OMEGA)
CL80=(2.*TTTR80)/(RHOSL*VF80**2*VS)
CL160=(2.*TTTR160)/(RHOSL*VF160**2*VS)
CLARVS=((2.*PIE)/(2.+SQRT(ARVS**2*2.+4.)))*ARVS*PIE/180.
A80=((CL80-.4)/CLARVS)
A160=((CL160-.4)/CLARVS)
WRITE(6,2980) CL80,CL160,A80,A160
WRITE(8,2980) CL80,CL160,A80,A160
*****
C *****
C *****
C *****
5. 1 DETERMINE RETREATING BLADE STALL EFFECTS *****
*****
5. 2 DETERMINE STALL POWER INCREMENT *****
*****
5. 3 DETERMINE COMPRESSIBILITY EFFECTS *****
*****
KNT=0.
TWIST=-10.*PIE/180.

```



```

470 IF (TRIP3.EC.3.) GO TO 470
WRITE (6,2930)
READ (5,*) MCRO
CALL FRICMS (.CLRSCRN 6*)
WRITE (6,2940)
READ (5,*) CLMAX
CALL FRICMS (.CLRSCRN 6*)
CONTINUE
AMAX=CLMAX/CLA
WRITE (8,2920) R,CHORD,BLADES,WG,VTIP,EFFPAFF,NENG,H,R+OALT,AALT,TW
1IST,CLMAX,AMAX,CLA,CDO,MCRO
CT=WG/(AREA*RHODLT*(VTIP**2))
IF (H/C.GT.1.5) PPOGE=1.0
B=1.0-(SQRT(2.*CT)/FLOAT(BLADES))
WRITE (8,2910) CT,AREAMR,SIGMA,B,PPOGE
VMAX=SQRT(WG/2./RHODLT/AREAMR)*(4./(EFFPAFF/AREAMR)**.3333334
VMAXK=VMAX/1.68894
VELMAX=VMAXK
DO 630 I=1,N
WRITE (8,2860) KNT
VF=KNT*1.151*5280./3600.
MU=VF/VTIP
VL=VF**2/(2.*VI**2)
C1=(B**2+.5*MU**2)
C2=(B**2-.5*MU**2)
T1=.5*C1
T2=(B**3)/3.+(MU**2*B*.5)
T3=(B**2/4.)*(B**2+MU**2)
T4=(MU/2.)*(B**2+MU**2/4.)
A11=((B**2*MU*.5-(MU**3/8.))*4.)/(B**2*C2)
A12=(8.*MU*B)/(3.*C2)
A13=(2.*MU**2)/C2
A14=(B**2+1.5*MU**2)/C2
IF (VF.GT.0.) GO TO 480
ALPHA=0.
WRITE (8,2900) ALPHA
LAMBD1=-SQRT(CT/2.)
IF (MU.LE.0.1) GO TO 510
IF (VF.EQ.0.) DP=0.
IF (VF.EQ.0.) GO TO 490
DP=PPFA(I)*550/VF
ALPHA=-CP/WG
CONTINUE
LAMBD1=-CT/SQRT(2*(LAMBD1**2)+MU**2)+MU*ATAN(ALPHA)
DLAMB=LAMBD1-LAMBD1
LAMBD1=LAMBD1
LREF=ABS(DLAMB)
IF (LREF.GE.LERR) GO TO 500

```



```

510 LAMBDA=LAMBDA1
    E1=(2.*CT)/(SIGMA*CLA)
    E2=T1*LAMBDA
    E3=T1*TWIST/(SIGMA*CLA)-(T1*LAMBDA-TWIST*T3
D2=-((A1*LAMBDA)-(TWIST*A13)
CYCLIC=((D2*T2)-(D1*A12))/(T2*A14-T4*A12)
COLL=(D1-T4*CYCLIC)/T2
CYCD=CYCLIC*57.29578
COLLD=COLL*57.29578
THETA0=CYCLIC*57.29578
THETA2=CYCLIC*57.29578
WRITE (8,2830) A11,A12,A13,A14,T1,T2,T3,T4,LAMBDA
GAM=AMAX-COLL+CYCLIC
CS=MU*GAM+LAMBDA
BS=-MU*TWIST-GAM
RT=(BS**2-4.*TWIST*CS)
WRITE (8,2860) RT
IF (RT) 560,520,520
XS=(-BS+SQR(TRT))/(2.*TWIST)
X0=-XS-BSTWIST
IF (XS-1.) 530,560,560
IF (XS) 560,560,540
CPS=((SIGMA/(24.*PIE))*((1.-MU)**2)*(1.-XS)*SQR(T(1.-XS**2)
IF ((XS+X0)/2..GE.1.0) KS=1.0
IF ((XS+X0)/2..GT.1.0) GO TO 550
KS=-((BS/(2.*TWIST)+XS)/(1.-XS)
CPS=KS*CPS
GO TO 570
CPS=0.0
KS=0.0
PS=CPS*RHQALT*AREAMR*(VTIP**3)/550.
WRITE (8,2840) KS,CPS
A90=COLL+CYCLIC+TWIST+LAMBDA/(1.+MU)
A270=COLL-CYCLIC+TWIST+LAMBDA/(1.+MU)
A90D=A90*57.29278
A270D=A270*57.29278
WRITE (8,2850) CYCD,COLL,A90D,A270D
MTIP=(VF+VTIP)/AALT
MCRT=MCRO-CLA*A90*.113
IF (MTIP-1.) 590,580,580
WRITE (8,2850)
GO TO 610
MD=MTIP-MCRT-0.06
IF (MD) 610,610,600
CPC=SIGMA*(C.012*MD+.1*(MD**3))
GO TO 620
CPC=0.0

```



```

620 MD=0.0
      PC*RHCAIT*AREAMR*(VTIP**3)/550.
      PCMPA(1)=PMES+PS
      WRITE (8,2870) MTIP,MCRIIT,MD,CPC,PITLFA(1),POFA(1),PPFA(1),PMBS,PS
1      PCMPA(1)
      TSHP=1.13*PCMPA(1)+10.0
      VDPT=SQRT(WG/RHOAL T/AREAMR*SQRT(AREAMR/3./EFPAFF))
      VDPTK=VCPT/1.68894
      KNT=KNT+5.
      CONTINUE
630 KNT=0.
      K=MAXV+40
      WRITE (6,2430)
      WRITE (8,2430)
      DO 690 I=1,K
      VF=KNT*1.151*5280./3600.
      MU=VF/VTIP
      PP=(.5*RHOAL T*EFPAFF*(VF**3))/550.
      C1=(8**2+.5*MU**2)
      C2=(8**2-.5*MU**2)
      T1=.5*C1
      T2=(8**2)/3.+(MU**2*8*.5)
      T3=(8**2/4.)*(8**2+MU**2)
      T4=(MU/2.)*(8**2+MU**2/4.)
      A11=((8**2*MU*.5-(MU**3/8.))*4.)/((8**2*C2)
      A12=(8.*MU**2)/3.*C2
      A13=(2.*MU**2)/C2
      A14=(8**2+1.5*MU**2)/C2
      IF (VF.GT.0.) GO TO 640
      ALPHA=0.
      GO TO 650
640 ALPHA=-(PP*550.)/VF/WG
650 LAMB D1=-SQRT(C T/2.)
      IF (MU.LE.0.1) GO TO 670
      LAMBDA=-CT/SQRT(2*(LAMB D1**2)+MU**2)+MU*TAN(ALPHA)
660 DLAMB=LAMBDA-LAMB D1
      LAMB D1=LAMBDA
      LREF=ABS(DLAMB)
      IF (LREF.GE.LERR) GO TO 660
      IF (MU.LE.0.1) LAMBDA=LAMB D1
670 E1=(2.*CT)/(SIGMA*CLA)
      E2=T1*LAMBDA
      E3=T3*TWIST
      D1=((2.*CT)/(SIGMA*CLA))-T1*LAMBDA-TWIST*T3
      D2=-(A11*LAMBDA)-(TWIST*A13)
      CYCLIC=((D2*T2)-(D1*A12))/(T2*A14-T4*A12)
      COLL=(D1-T4*CYCLIC)/T2
      THETA0=CCLL*57.29578

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```

680 THETA2=CYCLIC*57.29578
    A270=CCLL-CYCLIC+TWIST+LAMBDA/(1.+MU)
    A270D=A270*57.29578
    DA270=A270-AMAX
    DREF=ABS(DA270)
    IF (A270D.LT.12.) GO TO 680
    IF (A270D.GT.13.) GO TO 680
    VSK=VF/1.68894
    WRITE (6,2440) VSK,A270D
    WRITE (8,2440) VSK,A270D
    CONTINUE
    KNT=KNT+1.
    CONTINUE
    KNT=0.
    CT=WG/(AREAMR*RHOSL*(VTIP**2))
    IF (H/D.GT.1.55) PPGC=1.0
    B=1.0-(SQRT(2.*CT)/FLOAT(BLADESI))
    VMAX=SQRT(WG/2./RHOSL/AREAMR)*(4./(EFP AFF/AREAMR))**.333334
    VMAXK=VMAX/1.68894
    DO 850 I=1,N
    VF=KNT*1.151*5280./3600.
    MU=VF/VTIP
    VL=VF**2/(2.*V I**2)
    C1=(B**2+.5*MU**2)
    C2=(B**2-.5*MU**2)
    T1=.5*C1
    T2=(B**3)/3.+(MU**2*B*.5)
    T3=(B**2/4.)*(B**2+MU**2)
    T4=(MU/2.)*(B**2+MU**2/4.)
    A11=((B**2*MU*.5-(MU**3/8.))*4.)/(B**2*C2)
    A12=(8.*MU*B)/(3.*C2)
    A13=(2.*MU*B**2)/C2
    A14=(B**2+1.5*MU**2)/C2
    IF (VF.GT.0.) GO TO 700
    ALPHA=0.
    LAMBD1=-SQRT(CT/2.)
    IF (MU.LE.0.1) GO TO 730
    IF (VF.EQ.0.) DP=0.
    IF (VF.EQ.0.) GO TO 710
    DP=PPFS(I)*550/VF
    ALPHA=-CP/WG
    CONTINUE
710 LAMBD1=-CT/SQRT(2*(LAMBD1**2)+MU**2)+MU*TAN(ALPHA)
720 DLAMB=LAMBDA-LAMBD1
    LAMBD1=LAMBDA
    LREF=ABS(DLAMB)
    IF (LREF.GE.LERR) GO TO 720
730 LAMBD=LAMBD1

```



```

E1=(2.*CT1)/(SIGMA*CLA)
E2=T1*LAMBDA
E3=T3*TWIST
D1=((2.*CT1)/(SIGMA*CLA))-T1*LAMBDA-TWIST*T3
D2=-((A11*LAMBDA)-(TWIST*A13)
CYCLIC=((D2*T2)-(D1*A12))/(T2*A14-T4*A12)
COLL=(C1-T4*CYCLIC)/T2
THETA0=COLL*57.29578
THETA2=CYCLIC*57.29578
GAM=AMAX-COLL+CYCLIC
CS=MU*GAM+LAMBDA
BS=-MU*TWIST-GAM
RT=(BS**2-4.*TWIST*CS)
IF (RT) 780,740,740
XS=(-BS+SQRT(RT))/(2.*TWIST)
X0=-XS-BSTWIST
IF (XS-1.) 750,780,780
IF (XS) 780,780,760
CPS=((SIGMA/(24.*PIE))*((1.-MU)**2)*(1.-XS)*SQRT(1.-XS**2)
IF ((XS+X0)/2.*GE.1.0) KS=1.0 GO TO 770
IF ((XS+X0)/2.*GT.1.0) GO TO 770
KS=-((BS/(2.*TWIST)+XS)/(1.-XS)
CPS=KS*CPS
GO TO 790
CPS=0.0
KS=0.0
PS=CPS*RHOSL*AREAMR*(VTIP**3)/550.
A90=COLL+CYCLIC+TWIST+LAMBDA/(1.+MU)
A270=COLL-CYCLIC+TWIST+LAMBDA/(1.+MU)
A90D=A9C*57.29278
A270D=A270*57.29278
MTIP=(VF+VTIP)/AALT
MCRIT=MCR0-CLA*A90*.113
IF (MTIP-1.) 810,800,800
CONTINUE
GO TO 830
MD=MTIP-MCRIT-0.06
IF (MD) 830,830,820
CPC=SIGMA*(C.012*MD+.1*(MD**3))
GO TO 840
CPC=0.0
MD=0.0
PMBS=CPC*RHCSL*AREAMR*(VTIP**3)/550.
PCMPSP(I)=PMBS+PS
TSHP=1.13*PCMPSP(I)+10.0
VOPT=SQRT(WG/RHCSL/AREAMR*SQRT(AREAMR/3./EFPAFF))
VOPTK=VOPT/1.68894
KNT=KNT+5.

```

740

750

760

770

780

790

800

810

820

830

840


```

850 CONTINUE
      KNT=0.
      DO 900 I=1,K
        VF=KNT*.151*5280./3600.
        MU=VF/VTIP
        PP=(.5*RRHOSL*EFPAFF*(VF**3))/550.
        C1=(B**2+.5*MU**2)
        C2=(B**2-.5*MU**2)
        T1=.5*C1
        T2=(B**3)/3.+(MU**2*B*.5)
        T3=(B**2/4.)*((B**2+MU**2)
        T4=(MU/2.)*(B**2+MU**2/4.)
        A11=((B**2*MU*.5-(MU**3/8.))*4.)/(B**2*C2)
        A12=(8.*MU**8)/(3.*C2)
        A13=(2.*MU**E**2)/C2
        A14=(B**2+1.5*MU**2)/C2
        IF (VF.GT.0.) GO TO 860
        ALPHA=0.
        GO TO 870
      ALPHA=-(PP*.550.)/VF/WG
      LAMBDA1=-SQRT(CT/2.)
      IF (MU.LE.0.1) GO TO 890
      LAMBDA=-CT/SQRT(2*(LAMBDA1**2)+MU**2)+MU*TAN(ALPHA)
      DLAMB=LAMBDA-LAMBDA1
      LAMBDA1=LAMBDA
      LREF=ABS(DLAMB)
      IF (LREF.GE.LERR) GO TO 880
      IF (MU.LE.0.1) LAMBDA=LAMBDA1
      E1=(2.*CT)/(SIGMA*CLA)
      E2=T1*LAMBDA
      E3=T3*TWIST
      D1=((2.*CT)/(SIGMA*CLA))-T1*LAMBDA-TWIST*T3
      D2=-((A11*LAMBDA)-(TWIST*A13)
      CYCLIC=((D2*T2)-(D1*A12))/(T2*A14-T4*A12)
      COLL=(D1-T4*CYCLIC)/T2
      THETA0=COLL*.5729578
      THETA2=CYCLIC*.5729578
      A270=COLL-CYCLIC+TWIST+LAMBDA/(1.+MU)
      A270D=A270*.5729278
      DA270=A270-AMAX
      DREF=ABS(DA270)
      KNT=KNT+1.
      CONTINUE
      WRITE (6,2950)
      READ (5,*) FBS
      CALL FRICMS (CLRSCRN 6')
      *****
      5.4 DETERMINE TOTAL POWER REQUIRED
      *****
C***

```



```

C*****
PTAH=PT+PTTFH
PTAH=PTAH/550.
WRITE (6,1960) PTAH
WRITE (8,1960) PTAH
KNOTS(1)=0.
WRITE (6,1970)
WRITE (8,1970)
DO 910 I=1,N
POX(I)=POFS(I)+POTRES(I)
PIX(I)=PITLFS(I)+PITRFS(I)
PPX(I)=PPFS(I)
PTX(I)=POX(I)+PPX(I)+PCMP(S(I)
WRITE (6,1980) KNOTS(I),POX(I),PPX(I),PCMP(S(I),PTX(I)
WRITE (8,1980) KNOTS(I),PIX(I),PPX(I),PCMP(S(I),PTX(I)
KNOTS(I+1)=KNOTS(I)+5.
CONTINUE
WRITE (6,1950)
WRITE (8,1950)
KNOTS(1)=0.
DO 920 I=1,N
POY(I)=POFA(I)+POTRFA(I)
PIY(I)=PITLFA(I)+PITRFA(I)
PPY(I)=PPFA(I)
PTY(I)=POY(I)+PPY(I)+PCMPA(I)
WRITE (6,1990) KNOTS(I),POY(I),PPY(I),PCMPA(I),PTY(I)
WRITE (8,1990) KNOTS(I),PIY(I),PPY(I),PCMPA(I),PTY(I)
KNOTS(I+1)=KNOTS(I)+5.
CONTINUE
*****
5.5 DETERMINE THE RSHF REQUIRED AT MAXIMUM VELOCITY
*****
PADJS=PTX(NN)+PCMP(S(NN)
PADJA=PIY(NN)+PCMPA(NN)
IF (PADJS.GT.PADJA) GO TO 930
RR SHP=PACJA
GO TO 940
RR SHP=PADJS
CONTINUE
WRITE (6,2000) RRSHP
WRITE (8,2000) RRSHP
*****
5.6 DETERMINE RSHF FOR HOVER CEILING, IGE
*****
RHO S=.0023769*(1.-CONST*HOVIGE)**4.2561
CTH=WG/(AREAMR*RHO S*VTIP**2)
BH=1.-SQRT(2.*CTH)/FLOAT(BLADES)
PTTLH=(1./BH)*(WG*1.5/SQRT(2.*RHO S*AREAMR))

```



```

PPGGEH=-.1276*(H/D)**4+.708*(H/D)**3-1.4569*(H/D)**2+1.3432*(H/D)+
1.5147
PITLGH=PPOGEH*PITLH
POH=.125*SIGMA*CDO*RHOS*AREAMR*VTIP**3
PTH=PITLGH+POH
TTR=PTH/(OMEGA*LTR)
VTIPTR=CMEGTR*RTR
CTTR=TTR/(AREA*RHOS*VTIPTR**2)
BTR=1.-SQRT(2.*CTTR)/FLOAT(BLADTR)
PITLTR=(1./BTR)*(TTR**1.5/SQRT(2.*RHOS*AREATR))
POTR=.125*SIGTR*CDOTR*RHOS*AREATR*(VTIPTR**3)
PTTRH=PITLTR+POTR
PTACH=PTH+PTTRH
PTACH=PTACH/550.
C*****
C*****
C*****
5.7 DETERMINE THE MAXIMUM RSHP REQUIRED
C*****
C*****
IF (PTACH.GT.RRSHPI) GO TO 950
RSHPM=RRSHPI
GO TO 960
950
960
RSHPM=PTACH
CONTINUE
C*****
C*****
5.8 DETERMINE THE TOTAL ESHP REQUIRED
C*****
C*****
ESHPR=(.1*RSHPM*FLOAT(NENG-1))+1.03*RSHPM+10.
WRITE (6,2010) NENG,ESHPR
WRITE (8,2010) NENG,ESHPR
C*****
C*****
6.1 SELECT TYPE AND NUMBER OF ENGINES
C*****
C*****
6.2 INSTALLATION WEIGHT
C*****
C*****
WRITE (6,2020) NENG
WRITE (6,2030)
READ (5,*) ANS
CALL FRICMS ('CLRSCRN 6')
IF (ANS.NE.1.) GO TO 970
WRITE (6,2040)
READ (5,*) NENG
CALL FRICMS ('CLRSCRN 6')
GO TO 960
970
CONTINUE
HL=(AASLY*AFHPY)
PM(1)=.025
WRITE (6,2050)
WRITE (8,2080)
DO 1100 I=1,6

```



```

YMC(I)=AFHPY*PM(I)
YOC(I)=AFHPY*OC(I)
NRPL(I)=(HL/MTBR(I))-1.)
NXRPL(I)=AINT((HL)/MTBR(I))-1.)
IF (NRPL(I).NE.1.0) GO TO 980
GO TO 1090
IF (NRPL(I).NE.2.) GO TO 990
GO TO 1090
IF (NRPL(I).NE.3.) GO TO 1000
GO TO 1090
IF (NRPL(I).NE.4.0) GO TO 1010
GO TO 1090
IF (NRPL(I).NE.5.) GO TO 1020
GO TO 1090
IF (NRPL(I).NE.6.) GO TO 1030
GO TO 1090
IF (NRPL(I).NE.7.0) GO TO 1040
GO TO 1090
IF (NRPL(I).NE.8.) GO TO 1050
GO TO 1090
IF (NRPL(I).NE.9.) GO TO 1060
GO TO 1090
IF (NRPL(I).NE.10.0) GO TO 1070
GO TO 1090
IF (NRPL(I).NE.11.) GO TO 1080
GO TO 1090
CONTINUE
NRPL(I)=NXRFL(I)+1.
CONTINUE
EIW(I)=CW(I)+IF(I)*DW(I)
RC(I)=1.35*IC(I)
SV(I)=.8*IC(I)
WQO(I)=.35*SHPM(I)
LAMFR(I)=1./MTBF(I)
RELY(I)=EXP((-LAMFR(I))*AFHPF)
AVAIL(I)=MTEMA(I)/(MTBMA(I)+MDT(I))
LCC(I)=(RDC(I)+IC(I)+HL*(YOC(I)+YMC(I))
+NRPL(I))*RC(I)-SV(I))*0.0001
1 MAINT(I)=MDT(I)/AFHPF
CONTINUE
WRITE(6,210) (DW(I),I=1,6)
WRITE(8,210) (DW(I),I=1,6)
WRITE(6,2110) (LCC(I),I=1,6)
WRITE(8,2110) (LCC(I),I=1,6)
WRITE(6,2120) (MTBR(I),I=1,6)
WRITE(8,2120) (MTBR(I),I=1,6)
WRITE(6,2130) (NRPL(I),I=1,6)
WRITE(8,2130) (NRPL(I),I=1,6)

```



```

WR ITEE (6,2140) (RDC(I),I=1,6)
WR ITEE (8,2140) (RDC(I),I=1,6)
WR ITEE (6,2150) (IC(I),I=1,6)
WR ITEE (8,2150) (IC(I),I=1,6)
WR ITEE (6,2160) (YMC(I),I=1,6)
WR ITEE (8,2160) (YMC(I),I=1,6)
WR ITEE (6,2170) (YOC(I),I=1,6)
WR ITEE (8,2170) (YOC(I),I=1,6)
WR ITEE (6,2180) (RC(I),I=1,6)
WR ITEE (8,2180) (RC(I),I=1,6)
WR ITEE (6,2190) (SV(I),I=1,6)
WR ITEE (8,2190) (SV(I),I=1,6)
WR ITEE (6,2200) (AVAIL(I),I=1,6)
WR ITEE (8,2200) (AVAIL(I),I=1,6)
WR ITEE (6,2210) (RELY(I),I=1,6)
WR ITEE (8,2210) (RELY(I),I=1,6)
WR ITEE (6,2220) (MAINT(I),I=1,6)
WR ITEE (8,2220) (MAINT(I),I=1,6)
WR ITEE (6,2230) (SHPM(I),I=1,6)
WR ITEE (8,2230) (SHPM(I),I=1,6)
WR ITEE (6,2050) NENG
WR ITEE (8,2050) NENG
DO 1230 I=1,6
DW M(I)=CW(I)*FLOAT(NENG)
ICM(I)=IC(I)*FLOAT(NENG)
SHPM(I)=SHPM(I)*FLOAT(NENG)
RDCM(I)=RDC(I)*FLOAT(NENG)
MTBRM(I)=MTBR(I)
YCM(I)=YMC(I)*FLOAT(NENG)
YOCM(I)=YOC(I)*FLOAT(NENG)
NRPLM(I)=((HL/MTBR(I))-1.)*FLOAT(NENG)
NX RPLM(I)=((AINT((HL)/MTBR(I)))-1.)*FLOAT(NENG)
IF (NRPLM(I).NE.1.0) GO TO 1110
GO TO 1220
IF (NRPLM(I).NE.2.) GO TO 1120
GO TO 1220
IF (NRPLM(I).NE.3.) GO TO 1130
GO TO 1220
IF (NRPLM(I).NE.4.0) GO TO 1140
GO TO 1220
IF (NRPLM(I).NE.5.) GO TO 1150
GO TO 1220
IF (NRPLM(I).NE.6.) GO TO 1160
GO TO 1220
IF (NRPLM(I).NE.7.0) GO TO 1170
GO TO 1220
IF (NRPLM(I).NE.8.) GO TO 1180
GO TO 1220
1110
1120
1130
1140
1150
1160
1170

```



```

1180 IF (NRPLM(I).NE.9.) GO TO 1190
1190 GO TO 1220
1200 IF (NRFLM(I).NE.10.0) GO TO 1200
1210 GO TO 1220
1220 IF (NRPLM(I).NE.11.) GO TO 1210
1230 GO TO 1220
CONTINUE
NRPLM(I)=(NXRPLM(I)+1.)
CONTINUE
EIWM(I)=EIW(I)*FLOAT(NENG)
RCM(I)=1.35*ICM(I)
SVM(I)=.8*ICM(I)
WXOM(I)=.35*SHPPMM(I)
LAMFR(I)=(1./MTBF(I))
RELYM(I)=EXP((-LAMFR(I))*AFHPF)
AVAILM(I)=(MTBMA(I)/(MTBMA(I)+MDT(I)))
LCCM(I)=(FLCAT(NENG))* (RDC(I)+IC(I)+HL*(YOC(I)
1+YMC(I))+NRPL(I)-SV(I))* .0001
MAINTM(I)=(MDT(I)/AFHPF)
CONTINUE
WRITE (6,2100) (DWM(I),I=1,6)
WRITE (8,2100) (DWM(I),I=1,6)
WRITE (6,2110) (LCCM(I),I=1,6)
WRITE (8,2110) (LCCM(I),I=1,6)
WRITE (6,2120) (MTBRM(I),I=1,6)
WRITE (8,2120) (MTBRM(I),I=1,6)
WRITE (6,2130) (NRPLM(I),I=1,6)
WRITE (8,2130) (NRPLM(I),I=1,6)
WRITE (6,2140) (RDCM(I),I=1,6)
WRITE (8,2140) (RDCM(I),I=1,6)
WRITE (6,2150) (ICM(I),I=1,6)
WRITE (8,2150) (ICM(I),I=1,6)
WRITE (6,2160) (YMCM(I),I=1,6)
WRITE (8,2160) (YMCM(I),I=1,6)
WRITE (6,2170) (YOCM(I),I=1,6)
WRITE (8,2170) (YOCM(I),I=1,6)
WRITE (6,2180) (RCM(I),I=1,6)
WRITE (8,2180) (RCM(I),I=1,6)
WRITE (6,2190) (SVM(I),I=1,6)
WRITE (8,2190) (SVM(I),I=1,6)
WRITE (6,2200) (AVAILM(I),I=1,6)
WRITE (8,2200) (AVAILM(I),I=1,6)
WRITE (6,2210) (RELYM(I),I=1,6)
WRITE (8,2210) (RELYM(I),I=1,6)
WRITE (6,2220) (MAINTM(I),I=1,6)
WRITE (8,2220) (MAINTM(I),I=1,6)
WRITE (6,2230) (SHPPMM(I),I=1,6)
WRITE (8,2230) (SHPPMM(I),I=1,6)

```



```

WRITE (6,2450) ESHPR
WRITE (8,2450) ESHPR
WRITE (6,2240)
READ (5,*) ENGSEL
CALL FRICMS (,CLRS CRN 6)
C*****
C*****
C*****
6.3 REVERSE *****
C*****
C*****
EW=W6A+W6B
EWNEW=EIWM(ENGSEL)+WXOM(ENGSEL)
WGNEW=EWNEW+REVWG-EW
WRITE (6,2300) REVWG,WGNEW
WRITE (8,2300) REVWG,WGNEW
COMPAR=1.-REVWG/WGNEW
IF (COMPAR.LE..1) GO TO 1250
WG=WGNEW
DO 1240 I=1,6
  DW(I)=0.
  LCCM(I)=0.
  MTBRM(I)=0.
  NRPLM(I)=0.
  RDCM(I)=0.
  ICM(I)=0.
  YCM(I)=0.
  YOCM(I)=0.
  RCM(I)=0.
  SVM(I)=0.
  AVAILM(I)=0.
  RELYM(I)=0.
  MAINTM(I)=0.
  SHPM(I)=0.
  NXRPLM(I)=0.
  EIWM(I)=0.
  WXOM(I)=0.
  LCCM(I)=0.
CONTINUE
TRIP3=3.
GO TO 120
1240 IF (COMPAR.GE.-.1) GO TO 1270
WG=WGNEW
DO 1260 I=1,6
  DW(I)=0.
  LCCM(I)=0.
  MTBRM(I)=0.
  NRPLM(I)=0.
  RDCM(I)=0.
  ICM(I)=0.
  YCM(I)=0.

```



```

YOCM(I)=0.
RCM(I)=0.
AVAILM(I)=0.
RELYM(I)=0.
MAINTM(I)=0.
SHPM(I)=0.
NXRPLM(I)=0.
EIWM(I)=0.
WXOM(I)=0.
LCCM(I)=0.
CONTINUE
1260 TRIP3=3.
GO TO 120
1270 CONTINUE
C *** 7. 1 DETERMINE FUEL FLOW RATES ***
C *** WR ITE (6,2250) ***
C *** WFM=SFCCM(ENGSEL) *** FLOAT(NENG) ***
C *** WFN=SFCCN(ENGSEL) *** FLOAT(NENG) ***
C *** WR ITE (6,2260) WFM,WFN,WFC ***
C *** WR ITE (8,2260) WFM,WFN,WFC ***
C *** 7. 2 DETERMINE FUEL FLOW PER HORSEPOWER ***
C *** BETA=(WFM-WFC)/((SHPM(ENGSEL)- ***
1 ALPHA=(BETA*SHPM(ENGSEL))*FLOAT(NENG)
1 SHPC(ENGSEL))*FLOAT(NENG)
C *** 7. 3 COMPUTE THE INTERCEPT AT SPECIFICATION CONDITIONS ***
C *** PRESS=2116.22*(1.-CONST*PA)**5.2561 ***
C *** TEMP=518.688*(1.-CONST*PA) ***
C *** THETA=TEMP/518.688 ***
C *** DELTA=PHASDELTA*SQRT(THETA) ***
C *** WR ITE (6,2280) TEMP,PRESS,ALPHA,THETA,DELTA,ZHI ***
C *** WR ITE (8,2280) TEMP,PRESS,ALPHA,THETA,DELTA,ZHI ***
C *** 7. 4 DETERMINE THE ZERO VELOCITY HORSEPOWER INCREMENT ***
C *** PSHP=(FLCAT(NENG)*ALPHA*DELTA*SQRT(THETA))/BETA ***
C *** WR ITE (6,2730) ***
C *** READ (5,*) TYPEM ***

```



```

IF (TYPEM.NE.1.) GO TO 1280
FSLT=45.9
GO TO 1300
1280 IF (TYPEM.NE.2.) GO TO 1290
FSLT=50.1
GO TO 1300
1290 CONTINUE
FSLT=67.2
CONTINUE
IF (TRIP5.EC.5.) GO TO 1370
CALL FRICMS (.CLRCRN 6.)
WRITE (6,2250) PSHP
WRITE (8,2250) PSHP
C***** START OF DISPLA SPECIFIC PORTION OF THE PROGRAM *****
C*****
CALL HWRGT('AUTO')
CALL HWSCL('SCREEN')
CALL PAGE (11.,8.5)
CALL NCBDR (9.,6.)
CALL AREA2D
CALL SAISSL (.02)
CALL THKCRV
CALL CRCSS
CALL LINESP (2.5)
CALL SHDCHR (90.,1.,.002,1)
CALL THKFRM (.15)
CALL INTAXS ('NOENDS')
CALL XAXEND (2)
CALL XTICKS (5)
CALL YAXANG (0.)
CALL HEIGHT (.1)
CALL MYLEGN (.1)
CALL LINES ('INDUCED POWER$',IHP,1)
CALL LINES ('PRCFIL POWER$',IHP,2)
CALL LINES ('PARASITE POWER$',IHP,3)
CALL LINES ('HISPEED EFFECTS$',IHP,4)
CALL LINES ('TOTAL POWER$',IHP,5)
CALL RESET ('HEIGHT')
CALL XNAME ('FORWARD VELOCITY(KNOTS)$',100)
CALL YNAME ('REQUIRED HORSEPOWER$',100)
CALL HEADIN ('POWER VS. VELOCITY AT ALTITUDES$',
1 IF (ENGSEL.NE.1.) GO TO 1310
CALL GRAF (0.,10.,(MAXV+50.),(-500.*FLOAT(NENG)),500.,
1 GO TO 1360

```



```

1310 IF (ENGSEL.NE.2.) GC TO 1320
      CALL GRAF (C.,10.,(MAXV+50.),(-1000.*FLCAT(NENG)),500.,
1      (1500.*FLOAT(NENG)))
      GO TO 1360
1320 IF (ENGSEL.NE.3.) GO TO 1330
      CALL GRAF (C.,10.,(MAXV+50.),(-1500.*FLOAT(NENG)),500.,
1      (2500.*FLOAT(NENG)))
      GO TO 1360
1330 IF (ENGSEL.NE.4.) GO TO 1340
      CALL GRAF (C.,10.,(MAXV+50.),(-1500.*FLCAT(NENG)),500.,
1      (2500.*FLOAT(NENG)))
      GO TO 1360
1340 IF (ENGSEL.NE.5.) GO TO 1350
      CALL GRAF (C.,10.,(MAXV+50.),(-1500.*FLOAT(NENG)),500.,
1      (3500.*FLOAT(NENG)))
      GO TO 1360
1350 CONTINUE
      CALL GRAF (C.,10.,(MAXV+50.),(-1500.*FLCAT(NENG)),
1      500.,(4500.*FLOAT(NENG)))
1360 CONTINUE
      CALL POLY3
      CALL DCT
      CALL LEGLIN (KNOTS,PIY,N,0)
      CALL CURVE (.DOT.)
      CALL RESET (.DOT.)
      CALL DASH
      CALL LEGLIN (KNOTS,POY,N,0)
      CALL CURVE (.DASH.)
      CALL RESET (.DASH.)
      CALL CHNDOT
      CALL LEGLIN (KNOTS,PPY,N,0)
      CALL CURVE (.CHNDOT.)
      CALL RESET (.CHNDOT.)
      CALL CHNDSH
      CALL LEGLIN (KNOTS,PCMPA,N,0)
      CALL CURVE (.CHNDSH.)
      CALL RESET (.CHNDSH.)
      CALL LEGLIN (KNOTS,PTY,N,0)
      CALL CURVE (IHP,5,3,7,4,25)
      CALL LEGEND (.X--PSHP$,100,0.,-PSHP)
      CALL RLMMESS (.X-MAX SHP$,100,0.,SHPMM(ENGSEL))
      CALL RLMMESS (.X-CRUISE$,100,VCR,0.)
      CALL RLMREC (3,5,4,15,2,1.55,1.)
      CALL RESET (.THKCRV.)
      CALL DCT
      CALL GRID (2,1)
      CALL RESET (.DOT.)

```



```

C*****CALL EACPL (0)*****
C*****END OF DISPLA SPECIFIC PORTION OF THE PROGRAM*****
C*****WRITE (6,2310) PSHP*****
C*****WRITE (8,1410) PSHP*****
C*****GO TO 1380*****
1370CONTINUE
C*****WRITE (6,2770)*****
1380CONTINUE
C*****7.5 DETERMINE THE MAXIMUM RANGE VELOCITY*****
C*****7.5 DETERMINE THE MAXIMUM RANGE VELOCITY*****
C*****WRITE (6,2320)*****
C*****READ (5,*) VMAXR*****
C*****CALL FRICMS ('CLRSCRN 6')*****
C*****WRITE (6,2760)*****
C*****READ (5,*) VELMAX*****
C*****CALL FRICMS ('CLRSCRN 6')*****
C*****7.6 DETERMINE THE MAXIMUM ENDURANCE VELOCITY*****
C*****7.6 DETERMINE THE MAXIMUM ENDURANCE VELOCITY*****
C*****WRITE (6,2330)*****
C*****READ (5,*) VMAXE*****
C*****CALL FRICMS ('CLRSCRN 6')*****
C*****WRITE (6,2340)*****
C*****READ (5,*) RSHPM*****
C*****RSHRME=PSHP+RSHPM*****
C*****WFME=RSHRME*BETA*****
C*****CALL FRICMS ('CLRSCRN 6')*****
C*****7.7 DETERMINE THE POWER REQUIRED AND FUEL FLOW RATE AT*****
C*****SPECIFICATION CRUISE VELOCITY*****
C*****WRITE (6,2350)*****
C*****READ (5,*) FSHPC*****
C*****RSHPRC=PSHP+RSHPC*****
C*****WFCR=RSHPRC*BETA*****
C*****CALL FRICMS ('CLRSCRN 6')*****
C*****IF (TRIP4.EQ.4.) GO TO 1390*****
1390CONTINUE
C*****7.8 DETERMINE THE TOTAL FUEL REQUIREMENTS*****
C*****7.8 DETERMINE THE TOTAL FUEL REQUIREMENTS*****
C*****FW=(.05*WFN)*2.+(WFCR*RNNGMAX/VCR)+.25*WFME*****
C*****GALIN=FW/6.5*****
C*****GALOUT=C*****
C*****WRITE (6,2360) FW*****

```



```

C*****
C*****
C*****
WR ITE (8,2380) FW
8.1 COMPUTE DESIGN GROSS AND EMPTY WEIGHT
C*****
C*****
C*****
DWG=WGNEW+FW-FUEL
WR ITE (6,2350) DWG,RE VWG
WR ITE (8,2350) DWG,WG
SIM=1-DWG/WG
IF (SIM.LT.0.1) GO TO 1400
WR ITE (6,2420)
WE=DWG-FW-USELOD
FUEL=FW
TRIP1=1.
TRIP2=2.
TRIP3=3.
TRIP4=4.
GO TO 120
CONTINUE
E VWG-DWG
EXCESS=RESE.0.0) GO TO 1430
IF (EXCESS.LE.0.0) EXCESS
WR ITE (6,2400) EXCESS
READ (5,*) ANS
CALL FRTCMS (0,CLSRCRN 6,0)
IF (ANS.FW+EXCESS
FWNEW=FW+EXCESS
RNGNMX=(FWNEW-.05*WFN-.25*WFME-.05*WFN)*VCR/WFC
NEWUSE=USELOD
DWG=DWG+EXCESS
GO TO 1440
IF (ANS.NE.2.0) GO TO 1420
NEWUSE=USELOD+EXCESS
RNGNMX=RNGMAX
DWG=DWG+EXCESS
CONTINUE
WR ITE (6,2410)
READ (5,*) FWNEW
NEWUSE=FWNEW+USELOD
RNGNMX=(FWNEW-.05*WFN-.25*WFME-.05*WFN)*VCR/WFC
DWG=DWG+EXCESS
GO TO 1440
RNGNMX=RNGMAX
NEWUSE=USELOD
CONTINUE
FW=FWNEW
8.2 DETERMINE BEST RATE OF CLIMB
C*****
C*****
C*****

```



```

CONTINUE
PAVAIL=(SHPMM(ENGSEL)-10.)/(0.1*FLOAT(NENG-1)+1.03)
WRITE (6,2460)
READ (5,*) VVERT
RCLIMB=VVERT
CALL FRTCMS (0,CLRSCRN 6)
VVERT=VVERT/60.
VFWD=VMAX*1.151*5280./3600.
VINEW=SQRT(DWG/(2.*RHOSL*AREAMR))
EFPAFF=2.*EFPAFF
VITNEW(1)=1.*VVERT
VITNEW(2)=2.*VVERT
VITNEW(3)=VFWD**2+VVERT**2
VITNEW(4)=0.
VITNEW(5)=-VINEW**4
NDEG=4
CALL ZPCLR (VITNEW,NDEG,ZCMPLX,IER)
VTNEW=ZCMPLX(3)
PC=DWG*VVERT
PC=PC/550.
MU=VFWD/VTIF
MUTR=VFWD/VTIPTR
PPC=(.5*RHOSL*EFPVF*VVERT**3)+(0.5*RHOSL*EFPAFF*VFWD**3)
PPC=PPC/550.
POC=125*RHOSL*CDO*SIGMA*AREAMR*VTIP**3*(1.+4.3*MU**2)
POC=POC/550.
PIVERT=(1./B)*DWG*VTNEW
PIVERT=PIVERT/550.
PIVERT=PC+PIVERT+PC+PPC
POTR=.125*SIGTR*CDCTR*RHOSL*AREATR*(VTIPTR**3)
POTRF=(1.+4.3*MUTR**2)*POTR
POTRF=PCTRF/550.
PPF=5*RHOSL*(VFWD**3)*EFPAFF
PPF=PPF/550.
PO=.125*SIGMA*CDO*RHOSL*AREAMR*(VTIP**3)
POF=(1.+4.3*MU**2)*PO
POF=POF/550.
VI=SQRT(DWG/(2.*RHOSL*AREAMR))
VIT=VIT*SQRT((-VFWD**2/(2.*VI**2))+1.)
1  VIT=SQRT((-VFWD**2/(2.*VI**2))+1.)
PI TLF=(1./B)*DWG*VIT
PI TLF=PI TLF/550.
PI TLF=PI TLF+PCF+PPF
TTR=((PTF*550.)/(OMEGA*LTR))
CTTR=(TTR/(AREAMR*(VTIPTR**2)*RHOSL)
BTR=1.-SQRT(2.*CTTR)/FLOAT(BLADTR)
VITR=SQRT(TTR/(2.*RHOSL*AREATR))
VITR=VITR*SQRT((-VFWD**2/(2.*VITR**2)))

```



```

1  P I T L I F = ( 1 . / B ) * T T R * V I T R
    + S Q R T ( ( ( V F W D ** 2 / ( 2 . * V I T R ** 2 ) + 1 . ) )
P I T L I F = ( 1 . / B ) * T T R * V I T R
P T T R F = P I T L I F / 550 .
P T T R F = P I T L I F + P O T R F
P T A V A L = P T T R F + P T V E R T
W R A I T E ( 6 , 2470 ) P A V A I L , P T A V A L , P I V E R T
R E A D ( 5 , * ) A N S
C A L L F R I C M S ( ' C L R S C R N 6 ' )
I F ( A N S . E Q . 1 . ) G O T O 1450
V V E R T = V V E R T * 60 .
W R A I T E ( 6 , 2480 ) R C L I M B
W R I T E ( 8 , 2480 ) R C L I M B
C ** * * * * *
8 . 3 C O M P U T E M A X I M U M H O V E R A L T I T U D E , I G E
C ** * * * * *
C O N T I N U E
W R A I T E ( 6 , 2500 )
R E A D ( 5 , * ) A L T
C A L L F R I C M S ( ' C L R S C R N 6 ' )
P A L T = 2116 . 22 * ( 1 . - C O N S T * A L T ) ** 5 . 2561
D E L T A = P A L T / 2116 . 22
T A L T A = 518 . 688 * ( 1 . - C O N S T * A L T )
T H E T A = T A L T / 518 . 688
C A L L F R I C M S ( ' C L R S C R N 6 ' )
R H O M H = . 0023769 * ( 1 . - C O N S T * A L T ) ** 4 . 2561
C T H = D W G / ( A R E A M * R H O M H * V T I P ** 2 )
B H = 1 . - S Q R T ( 2 . * C T H ) / F L O A T ( B L A D E S )
P I T L H = ( 1 . / B F ) * ( D W G ** 1 . 5 / S Q R T ( 2 . * R H O M H * A R E A M R ) )
P P O G E H = - . 1276 * ( H / D ) ** 4 + . 708 * ( H / D ) ** 3 - 1 . 4569 * ( H / D ) ** 2 + 1 . 3432 * ( H / D ) +
1 . 5147
1  P O H = . 125 * S I G M A * C D O * R H O M H * A R E A M R * V T I P ** 3
    P T H = P I T L H + P C H
    T T R = P T H / ( O M E G A * L T R )
    V T I P T R = C M E G T R * R T R
    C T T R = T T R / ( A R E A T R * R H O M H * V T I P T R ** 2 )
    B T T R = 1 . - S Q R T ( 2 . * C T T R ) / F L O A T ( B L A D T R )
    P I T L T R = ( 1 . / E T R ) * ( T T R ** 1 . 5 / S Q R T ( 2 . * R H O M H * A R E A T R ) )
    P O T R = . 125 * S I G T R * C D O T R * R H O M H * A R E A T R * ( V T I P T R ** 3 )
    P T T R H = P I T L T R + P O T R
    P T A C H = P T H + P T T R H
    P T A C H = P T A C H / 550 .
    P A V A I L = ( ( S H F M M ( E N G S E L ) - 10 . ) / ( . 1 * F L O A T ( N E N G - 1 ) + 1 . 03 ) ) * D E L T A / S Q R T ( T H
    E T A )
1  W R A I T E ( 6 , 2490 ) P A V A I L , P T A C H
    R E A D ( 5 , * ) A N S
    C A L L F R I C M S ( ' C L R S C R N 6 ' )
    I F ( A N S . E Q . 1 . ) G O T O 1460
    W R I T E ( 6 , 2530 ) A L T

```



```

1470 C*** WRITE (8,2530) ALT
C*** CONTINUE
C*** 8.4 COMPLETE SERVICE CEILING
C***
WRITE (6,2510)
READ (5,*) ALTSC
CALL FRTCMS (.1,CLRS CRN 6,.)
PALT=2116.22*(1.-CONST*ALTSC)**5.2561
DELTA=PALT/2116.22
TALT=518.688*(1.-CONST*ALTSC)
THETA=TALT/518.688
RHOSC=.0023769*(1.-CONST*ALTSC)**4.2561
PAVAIL=((SHPN(ENGSEL)*FLOAT(NENG)-10.)/(.1*FLOAT(NENG-1)+1.03))*DE
1LTA/SQRT(THETA)
VVERT=100./60.
VFWD=VMAXE*1.151*5280./3600.
VINEW=SQRT(DWG/(2.*RHOSC*AREAMR))
VITNEW(1)=1.*VVERT
VITNEW(2)=2.*VFWD**2+VVERT**2
VITNEW(3)=VFWD**2+VVERT**2
VITNEW(4)=0.
VITNEW(5)=-VINEW**4
CALL ZPCLR (VITNEW,NDEG,ZCMPLX,IER)
VTNEW=ZCMPLX(3)
PC=DWG*VVERT
PC=PC/550.
PPC=(.5*RHOSC*EFPA VF*VVERT**3)+(.5*RHOSC*EFPAFF*VFWD**3)
PPC=PPC/550.
POC=PPC/550.
POC=125*RHOSC*CD0*SIGMA*AREAMR*VTIP**3
PIVERT=(1./8)*DWG*VTNEW
PIVERT=PIVERT/550.
PTVERT=FOC+PIVERT+PC+PPC
MUTR=VFWD/VTIPTR
POTR=.125*SIGTR*CDQTR*RHOSC*AKEATR*(VTIPTR**3)
POTRF=(1.+4.3*MUTR**2)*POTR
POTRF=POTRF/550.
PPF=.5*RHOSC*(VFWD**3)*EFPAFF
PPF=PPF/550.
MU=VFWC/VTIF
PO=.125*SIGMA*CDG*RHOSC*AREAMR*(VTIP**3)
POF=(1.+4.3*MU**2)*PO
POF=POF/550.
VI=SQRT(DWG/(2.*RHOSC*AREAMR))
VIT=VI*SQRT((- (VFWD**2/(2.*VI**2))**2)+1.))
1 P1TLF=(1./8)*DWG*VIT

```



```

1530 GO TO 1530
CONTINUE
1C,R, BL ACES, 2620) SHP MM( ENGSEL), GWSPEC, DWG, WE, GALIN, GALOUT, CHORD, RSPE
1C,R, BL ACES, 2620) SHP MM( ENGSEL), GWSPEC, DWG, WE, GALIN, GALOUT, CHORD, RSPE
1C,R, BL ACES, 2630) CDO TR, OMEGTR, SIGTR, STI, FSLTS, FSLT, EFPAFF, EFPAVF
1C,R, BL ACES, 2630) CDO TR, OMEGTR, SIGTR, STI, FSLTS, FSLT, EFPAFF, EFPAVF
C***** BASES FOR COST ESTIMATING RELATIONSHIPS *****
C*****
C*****
Q=100.
C1=-12538.+101.*W1*(Q**(-.074))*IR
C2A=102.*W2A*(Q**(-.074))*IR
C2B=759.*(W2B*.848)*(Q**(-.286))*IR
C3=860.*(W3*.848)*(Q**(-.286))*IR
IF (LG.NE.2.) GO TO 1540
C4=85.*W4*(C**(-.2176))*IR
GO TO 1550
1540 CONTINUE
C4=C3*W4/W3*IR
1550 CONTINUE
C5=893.*(W5*.848)*(Q**(-.286))*IR
C6A=ICM(ENGSEL)*IR*1000.
C6B=19946.+E3.*W6B*(Q**(-.074))*IR
C6C=201.*W6C*(Q**(-.0896))*IR
C7=156.*W7*(Q**(-.0896))*IR
C8=243.*W8*(Q**(-.0896))*IR
C9=125.*W9*(Q**(-.0896))*IR
C10=91.*W10*(Q**(-.0896))*IR
C11=143.*W11*(Q**(-.0896))*IR
C12=6847.+125.*W12*(Q**(-.0896))*IR
C13=69.*W13*(Q**(-.0896))*IR
C14=213.*W14*(Q**(-.0896))*IR
C15=C3*W15/W3*IR
TOTALC=C1+C2A+C2B+C3+C4+C5+C6A+C6B+C6C+C7+C8+C9+C10+C11+C12+C13+C1
14+C15
WR ITE (6,2810) C1, C2A, C2B, C3, C4, C5, C6A, C6B, C6C, C7, C8, C9, C10, C11, C1
12, C13, C14, C15, TOTALC
WR ITE (8,2810) C1, C2A, C2B, C3, C4, C5, C6A, C6B, C6C, C7, C8, C9, C10, C11, C1
12, C13, C14, C15, TOTALC
CALL DCNEPL
STOP
C*****
1560 FORMAT (///39H WHAT TYPE OF MACHINE ARE YOU NOW USING,/,10X,22H1.
1 TEK618/DUAL SCREEN,/,10X,12H2. IBM 3278)
1570 FORMAT (45H ENTER THE SPECIFICATION MAXIMUM GROSS WEIGHT)
1580 FORMAT (47H ENTER THE MANUFACTURERS ESTIMATED EMPTY WEIGHT)

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1590 FORMAT (55H ENTER THE GROSS WEIGHT THAT YOU WANT FOR THE FIRST 80%
1591 1,9H ESTIMATE)
1600 FORMAT (30H GROSS WEIGHT ESTIMATE =,F8.2)
1610 FORMAT (54H ENTER THE VALUE OF THE DISC LOADING FOR THE ESTIMATED,
1611 1/,16H GROSS WEIGHT OF, F9.2,4H LBS)
1620 FORMAT (56H ENTER THE SPECIFICATION MAXIMUM FORWARD VELOCITY(KNOTS
1621 1))
1630 FORMAT (28H THE ADVANCE RATIO (MU) IS =,F6.4,/)
1640 FORMAT (52H ENTER THE BLADE LOADING FOR THE GIVEN ADVANCE RATIO)
1650 FORMAT (52H ENTER THE NUMBER OF MAIN ROTOR BLADES THAT YOU WANT)
1660 FORMAT (30H1GROSS WEIGHT (LBS) =,F10.2,/,30H EMPTY WEIGHT =,F10.2,
1661 1(LBS)
1662 2/,30H MAXIMUM TIP VELOCITY (FPS) =,F10.2,/,30H DISK LOADING
1663 3=,F10.2,/,30H ROTOR RADIUS (FT) =,F10.2,/,30H
1664 4ROTATIONAL VELOCITY (RPS) =,F10.2,/,30H TIP VELOCITY (FPS)
1665 5=,F10.2,/,30H COEFFICIENT OF THRUST =,F14.6,/,30H ADVANC
1666 6E RATIO (MU) =,F12.4,/,30H BLADE LOADING
1667 7F12.4,/,30H SOLIDITY =,F15.7,/,30H NUMBER OF MA
1668 8IN ROTOR BLADES =,5X,12,/,30H CHORD MAIN ROTOR BLADE (FT) =,F14.6)
1669 10X,30H
1670 FORMAT (10X,30H SPEED IS =,F11.3)
1680 1 THE ROTATIONAL SPEED DO YOU WANT NOW?)
1690 FORMAT (55H WHAT IS THE COEFFICIENT OF LIFT WITH RESPECT TO ALPHA?
1691 1,6H(/DEG))
1700 FORMAT (43H WHAT IS THE ZERO LIFT COEFFICIENT OF DRAG?)
1710 FORMAT (30H1GROSS WEIGHT (LBS) =,F10.2,/,30H EMPTY WEIGHT
1711 1(LBS)
1712 2/,30H MAXIMUM TIP VELOCITY (FPS) =,F10.2,/,30H DISK LOADING (LBS/
1713 3SF) =,F10.2,/,30H ROTOR RADIUS (FT) =,F10.2,/,30H
1714 4ROTATIONAL VELOCITY (RPS) =,F10.2,/,30H TIP VELOCITY (FPS)
1715 5=,F10.2,/,30H COEFFICIENT OF THRUST =,F14.6,/,30H ADVANC
1716 6E RATIO (MU) =,F12.4,/,30H BLADE LOADING
1717 7F12.4,/,30H SOLIDITY =,F15.7,/,30H NUMBER OF MA
1718 8IN ROTOR BLADES =,5X,12,/,30H CHORD MAIN ROTOR BLADE (FT) =,F14.6)
1719 10X,30H
1720 9/,30H ASPECT RATIO OF MAIN ROTOR =,F10.2,/,30H COEFF OF LIFT (AVG
1721 $) =,F12.4,/,30H COEFF OF LIFT W/R ALPHA =,F12.4,/,30H
1722 $COEFF OF DRAG @ 0 LIFT
1723 35H ENTER THE AMOUNT OF FUEL IN POUNDS)
1730 FORMAT (46H ENTER THE USEFUL LOAD IN PCUNDS THAT YOU WANT)
1740 FORMAT (47H ENTER THE NUMBER OF PEOPLE YOU ARE PLANNING ON)
1750 FORMAT (37H ENTER THE NUMBER OF ENGINES YOU WANT)
1760 FORMAT (30H1TIP LOSS FACTOR =,F16.7,/,30H POWER (INDUC
1761 1ED)(HP) =,F10.1,/,30H POWER (PROFILER)(HP) =,F10.1,/,30H
1762 2/,30H PCWER (TOTAL)(HP) =,F10.1,/,30H EMPTY WEIGHT (LBS)
1763 3=,F11.2,/,30H FUEL WEIGHT (LBS) =,F11.2,/,30H
1764 4NUMBER OF PEOPLE =,6X,12,/,30H USEFUL LOAD (LBS)
1765 5=,F11.2,/,30H NUMBER OF ENGINES =,6X,12,/,30H ESTIMA
1766 6TED GROSS WEIGHT(LBS) =,F11.2,/,30H SOLIDITY

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7F16.7,/,30H ROTOR RADIUS (FT)
8(HP) =,F10.1,/,30H ROTOR WEIGHT(LBS)
9/,30H TAIL: ROTOR =,F11.2,/,30H HOVER POWER
$BS) =,F11.2,/,30H BODY (LBS) STRUCTURE(L
$LANDING GEAR (LBS) =,F11.2,/,30H
FORMAT (30H NACELLE (LBS)
ENGINE (LBS) =,F11.2,/,30H PROPULSION:
2/,30H FUEL TANKS (LBS) DRIVE (LBS)
3BS) =,F11.2,/,30H AUXILIARY POWER (LBS) =,F11.2,/,30H FLIGHT CONTROLS (L
4INSTRUMENTS (LBS) =,F11.2,/,30H HYDRAULICS (LBS)
5 =,F11.2,/,30H ELECTRICAL (LBS) =,F11.2,/,30H AVIONI
6CS (LBS) =,F11.2,/,30H FURNISHINGS (LBS)
7F11.2,/,30H AIR AND ICE (LBS) =,F11.2,/,30H LOAD AND HAN
8DLING (LBS) =,F11.2,/,30H REVISED EMPTY WEIGHT (LBS) =,F11.
92,/,30H REVISED GROSS WEIGHT (LBS) =,F11.2,/,30H
FORMAT (///30H FIGURE OF MERIT (%) =,F7.3)
1780 FORMAT (//46+ LOOK AT YOUR FIGURE OF MERIT, IF NOT 70CM<80%,/,10X,5
1790 15H THEN 1. RECALCULATE THE ROTOR RADIUS WITH THE NEW DL,/,17X,20
2H2. CHANGE 1. THE CHORD,/,17X,11H3. CHANGE, 23H THE ROTATIONAL VELOC
3ITY,/,17X,15H4. CONTINUE ON)
1800 FORMAT (24H THE OLD GROSS WEIGHT IS, F11.2,/,/,40H DO YOU WANT TO C
1HANGE THE DISC LOADING?,/,10X,7H1. YES,/,10X,6H2. NO)
1810 FORMAT (56H ENTER A NEW DISK LOADING USING THE REVISED GROSS WEIGH
1T)
1820 FORMAT (37H ENTER THE HEIGHT OF THE ROTOR SYSTEM)
1830 FORMAT (50H USE THE LATEST ESTIMATE OF GROSS WEIGHT AND ENTER,/,34
1H THE EQUIVALENT FLAT PLATE LOADING)
1840 FORMAT (///43H1 @ SSL,/,55H
1 POWER PARASITE-----TOTAL,7.58H (KNOTS) TIP INDUCED-----PROF
3ICE (SHP) (SHP) (SHP) (SHP)
4 FORMAT (2X, F7.2, 1X, F9.2, 2X, F9.2, 2X, F9.2, 2X, F9.2)
1850 FORMAT (///43H1 MAIN ROTOR POWER PROFILE,/,49H
1860 AT SPECIFICATION ALTITUDE AND TEMPERATURE,/,55H AIRSPEED TIP
1 INDUCED-----PROFILE PARASITE-----TOTAL,7.58H (KNOTS) MACH
2 (SHP) (SHP) (SHP) (SHP)
3 FORMAT (34H ENTER THE NEW CHORD THAT YOU WANT)
1870 FORMAT (///1,29H TAIL ROTOR RADIUS (FT)=, F8.3)
1880 FORMAT (5X, 24H TAIL ROTOR SPEED (RPS)=, F8.3)
1890 FORMAT (5X, 24H TAIL ROTOR CDO =, 2X, F5.7)
1900 FORMAT (5X, 24H TAIL ROTOR NUMBER OF TAIL ROTOR BLADES,/,35H HELICOPT
1910 FOR A LIGHT HELICOPTER,/,36H 3-4 FOR A MEDIUM HELICOPT
2ER,/,35H
2 FORMAT (43H ENTER ASPECT RATIO OF TAIL ROTOR (4.5-8.0) )
1920 FORMAT (///39H1 TAIL ROTOR POWER PROFILE,/,27H
1930 @ SSL,/,48H
1 -----POWER-----

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1940 2--(KNOTS) /,47H AIRSPEED TIP INDUCED PROFILE TOTAL,/,47H
3--(KNOTS) MACH (SHP) (SHP))
1000 1000 TAIL ROTOR POWER PROFILE,/,47H A
1000 1000 SPECIFICATION ALTITUDE AND TEMPERATURE,/,48H
2000 2000 POWER TOTAL,7,47H (KNOTS) /,47H AIRSPEED TIP INDUCED-----PRO
3000 3000 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
4000 4000 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
1950 1950 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
1960 1960 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
1970 1970 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
1980 1980 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
1990 1990 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2000 2000 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2010 2010 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2020 2020 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2030 2030 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2040 2040 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2050 2050 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2060 2060 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2070 2070 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2080 2080 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2090 2090 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2100 2100 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2110 2110 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2120 2120 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2130 2130 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2140 2140 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2150 2150 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2160 2160 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2170 2170 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2180 2180 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2190 2190 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)
2200 2200 (2X,F7,2,1X,F5,2,1X,F9,2,2X,F9,2,2X,F9,2)

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2210 (23H RELIABILITY(ENG): ,6F8.4)
2220 (23H MAINTAINABILITY(ENG): ,6F8.3)
2230 (23H PERFORMANCE(SHP-MIL): ,6F8.1)
2240 (49H SELECT: (1.A)--(2.8)--(3.C)--(4.D)--(5.E)--(6.F))
2250 (//51H1)-----FUEL FLOW RATES-----,/
      MILITARY POWER NORMAL POWER CRUISE POWER)
2260 (3X, F10.2, 7X, F10.2, 30H ALPHA AT SSL =, F8.2)
2270 (30H THE CURRENT CHORD IS =, F10.3, /, 30H PRESSURE (PS
2280 (30H TEMPERATURE (R) =, F10.3, /, 30H DELTA AT SPEC ALTI
1F) TETA AT SPEC ALTITUDE =, F10.3, /, 30H HORSEPOWER INTERCEPT, /, 30H AT SPEC AL
3TITUDE =, F10.3)
4TITUDE =, F10.3)
2290 (//43H THE ZERO HORSEPOWER INCREMENT AT ALTITUDE=, F10.3)
2300 (//15H OLD GROSS WEIGHT =, F10.2, /, 19H NEW GROSS WEIGHT =, F1
10.2)
2310 (//32H THE PHANTOM HORSEPOWER IS =, F10.2)
2320 (41H ENTER THE MAX RANGE VELOCITY FROM GRAPHS)
2330 (49H ENTER THE MAX ENDURANCE VELOCITY FROM THE GRAPHS)
2340 (52H ENTER THE MAX REQUIRED HORSEPOWER FOR MAX ENDURANCE)
2350 (49H ENTER THE REQUIRED HORSEPOWER AT CRUISE VELOCITY)
2360 (49H ENTER THE MAX RANGE FROM THE SPECIFICATIONS (NM))
2370 (35H ENTER THE CRUISE VELOCITY IN KNOTS)
2380 (//23H THE FUEL WEIGHT IS =, F10.2, 3HUBS)
2390 (32H THE DESIGN WEIGHT IS =, F10.2, /, 32H THE ESTIMA
1TED GROSS WEIGHT IS =, F10.2)
2400 (30H ADVANTAGEOUS EXCESS WEIGHT IS, F10.1, /, 41H WHICH PARAME
1TER DO YOU WANT TO INCREASE? , /, 10X, 18H1. FUEL CAPABILITY, /, 10X, 14H
22. USEFUL LOAD, /, 10X, 7H3. BOTH)
2410 (24H ENTER THE NEW FUEL LOAD)
2420 (54H YOU ARE OVER THE ESTIMATED GROSS WEIGHT AND THEREFORE,
1/ , 15H MUST FEETERATE)
2430 (48H INOTE THE VELOCITY THAT HAS THE STALL ANGLE LESS, /, 31H
1THAN OR EQUAL TO 12.5 DEGREES , /, 21H VELOCITY
2 (KNOTS) (DEG))
2440 (1X, F9.2, 7X, F6.1)
2450 (36H THE REQUIRED SHAFT HORSEPOWER IS =, F10.2)
2460 (//53H COMPUTATION OF THE BEST RATE OF CLIMB, ENTER A GUES
1S, /, 45H FOR THE VERTICAL RATE OF CLIMB (FEET/MINUTE))
2470 (37H THE POWER AVAILABLE IS =, F10.2, /, 37H THE T
1OTAL POWER CF THE AIRCRAFT IS =, F10.2, /, 53H
2 =, F10.2, /, 53H
3 (//49H THE TOTAL POWER SHOULD EQUAL THE POWER AVAILAB
4LE, 7, 36F, /, 49H ENTER A 1, ELSE, ENTER A 2)
2480 (//26H THE BEST RATE OF CLIMB IS, F10.2, 16H FEET PER MINUT
1E)
2490 (37H THE POWER AVAILABLE IS =, F10.2, /, 37H THE T
1OTAL POWER CF THE AIRCRAFT IS =, F10.2, /, 53H)

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2 THE POWER AVAILABLE, 7, 35H IF NOT, 49H THE TOTAL POWER SHOULD EQUAL
3 FORMAT (///53H COMPUTATION OF THE MAX HOVER ALT (IGE), ENTER A 2)
1S, 25H FOR THE ALTITUDE IN FEET)
1 FORMAT (///51H COMPUTATION FOR THE SERVICE CEILING, ENTER A GUESS,
1, 25H FOR THE ALTITUDE IN FEET)
1 FORMAT (///24H THE SERVICE CEILING ALTITUDE IS =, F10.2)
2520 FORMAT (///32H THE HOVER CEILING ALTITUDE IS =, F10.2)
2530 FORMAT (37H THE POWER AVAILABLE IS
2540 TOTAL POWER CF THE AIRCRAFT IS =, F10.2, /, 53H
2 THE POWER AVAILABLE, 7, 35H IF NOT, 49H THE TOTAL POWER SHOULD EQUAL
3 FORMAT (43H1
1306, 27X, 13H FINAL SUMMARY, 28X, 11H PERFORMANCE, 7, 40X, 30H SPECIFI
2 CATION
3 8X, 12, 18X, 12, 41H CREW
4 10.1, 10X, F10.1, 41H SERVICE CEILING (FT)
5 1, 10X, F10.1, 41H HOVER IGE (FT)
6 0X, F10.1, 41H VELOCITY (KTS) CRUISE
7 F10.1, 41H MAXIMUM RATE OF CLIMB
8.1, 41H MAX ENDURANCE
9 RETREATING BLADE STALL, 20X, F10.1, 41H MAXIMUM RANGE (NMI
$ (FT/MIN)
$ 28X, 12)
$
2560 FORMAT (10X, 31H TYPE
2570 FORMAT (10X, 31H TYPE
2580 FORMAT (10X, 31H TYPE
2590 FORMAT (10X, 31H TYPE
2600 FORMAT (10X, 31H TYPE
2610 FORMAT (10X, 31H SHIP (SSL) MILITARY
2620 GEOMETRY, 41H WEIGHT (LBS) - MAX GROSS
1 F10.1, 41H
2 F10.1, 41H
3 41H FUEL CAPACITY (GAL) - INTERNAL
4 EXTERNAL
5 CHORD (FT)
6 28X, 12, 41H
7 DES
8 20X, F10.4, 41H
9 0.2, 41H
$ TAIL RADIUS (FT)
$ 28X, 12)
$ ER BLADES
$ FORMAT (14X, 27H DRAG COEFFICIENT
2630 1 IDITY
2 IDITY

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3.....:20X,F10.2,/,41H FUSELAGE LENGTH (FT),.....:FORMA
4.....:F10.2,10X,F10.2,/,41H EQUIVALENT FLAT PLAGE AREA (F1) FORMA
5RD.....:20X,F10.2,/,41H
610.2)
2640 FORMAT (50H ENTER THE SPECIFICATION PRESSURE ALTITUDE IN FEET)
2650 FORMAT (43H ENTER THE SPECIFICATION TEMPERATURE IN (F))
2660 FORMAT (53H FROM THE SPECIFICATIONS SHEET, WHAT IS THE NUMBER OF,6
1H CREW?)
2670 FORMAT (51H FROM THE SPECIFICATIONS SHEET, WHAT IS THE SERVICE,9H
1CEILING?)
2680 FORMAT (55H FROM THE SPECIFICATIONS SHEET, WHAT IS THE HOVER (IGE)
19H CEILING?)
2690 FORMAT (51H FROM THE SPECIFICATIONS SHEET, WHAT IS THE MAXIMUM,14H
1 ROTOR RADIALS?)
2700 FORMAT (51H FROM THE SPECIFICATIONS SHEET, WHAT IS THE MAXIMUM,17H
1 FUSELAGE LENGTH?)
2710 FORMAT (47H ENTER TYPE OF HELICOPTER FOR WEIGHT ESTIMATION,/,15X,8
1H1. LIGHT,/,15X,9H2. MEDIUM,/,15X,8H3. HEAVY)
2720 FORMAT (52H ENTER THE MAXIMUM RATE OF CLIMB FROM SPECIFICATIONS)
2730 FORMAT (40H WHICH TYPE HELICOPTER ARE YOU DESIGNING,/,10X,7H1. LIGH
1T,/,10X,8H2. MEDIUM,/,10X,7H3. HEAVY)
2740 FORMAT (49H YOU HAVE NOT CONVERGED TO WITH 10% OF THE WEIGHT,/,29H
1 THEREFORE YOU MUST REITERATE)
2750 FORMAT (36H ENTER THE SPECIFICATION USEFUL LOAD)
2760 FORMAT (44H ENTER THE MAXIMUM POSSIBLE FORWARD VELOCITY)
2770 FORMAT (36H ENTER IS THE TOTAL POWER VS. FORWARD,16H VELOCITY TABLE
1,/,16H NOW GRAPH A FEW,39H POINTS AND EXTRAPOLATE THE NEEDED DATA
2)
2780 FORMAT (35H ENTER TYPE OF LANDING GEAR DESIRED,/,10X,10H1. WHEEL
1S,/,10X,9H2. SKIDS)
2790 FORMAT (32H WHAT TYPE OF GEAR DO YOU DESIRE,/,10X,9H1. FIXED,/,1
10X,15H2. RETRACTABLE)
2800 FORMAT (33H ENTER THE NUMBER OF LANDING GEAR)
2810 FORMAT (55H1COST ANALYSIS PER VEHICLE (IN DOLLARS FOR 100 A/C RUN)
1,/,5X,3CH RCTOR =,F11.2,/,5X,30H
2
31.2,/,5X,30H BODY =,F11.2,/,5X,30H LANDING =
4GEAR =,F11.2,/,5X,30H NACELLE =,F11.2,/,5X,30H
5,F11.2,/,5X,30H PROPULSION: ENGINE =,F11.2,/,5X,30H
6 CRIVE =,F11.2,/,5X,30H FUEL TANKS
7 =,F11.2,/,5X,30H FLIGHT CONTROLS =,F11.2,/,5X,30H AU
8XILLARY POWER =,F11.2,/,5X,30H INSTRUMENTS =,F11.2,/,5X,30H
9 =,F11.2,/,5X,30H HYDRAULICS =,F11.2,/,5X,30H
$ ELECTRICAL =,F11.2,/,5X,3CH AVIONICS =,F11.2,/,5X,
$ =,F11.2,/,5X,30H FURNISHINGS =,F11.2,/,5X,
$30H AIR AND ICE =,F11.2,/,5X,30H LOAD AND HANDLING
$ =,F11.2,
$
2820 FORMAT (33H ENTER THE INFLATION RATE DOLLARS)

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2830      FORMAT (/27+
1      F10.6/,38H      DYNAMIC PARAMETERS,/,38H      All.....
2      F10.6/,38H      A12.....F10.6/,38H      A
3      F14.....F10.6/,38H      F1.....F10.6/,38H      A
4      F10.6/,38H      T2.....F10.6/,38H      F
5      F10.6/,38H      T3.....F10.6/,38H      F14.
6      F10.6/,38H      F10.6/,38H      INFLOW RATIO (LAMBDA
7      F10.6/),
2840      FORMAT (/5X,37HINBOARD STALL CORRECTION FACTOR.....F16.7//,5X,3
17HSTALL POWER COEFFICIENT.....F14.7)
2850      FORMAT (/5X,28HANGLE OF ATTACK CALCULATIONS//,5X,35HLONGITUDINAL
1CYCLIC ANGLE(DEG).....F10.6/,5X,35HLONGITUDINAL COLLECTIVE ANGLE(
2DEG).....F10.6/,5X,35HALPHA(90) (DEG).....F10.6/,5X,3
35HALPHA(270) (DEG).....F10.6)
2860      FORMAT (/10X,24HSTALL POWER CALCULATIONS//,5X,35HRT.....
1      F12.6)
2870      FORMAT (/10X,23HHIGH SPEED MACH EFFECTS//,5X,34HADVANCING BLADE TI
1P MACH NUMBER.....F12.6/,5X,34HCRITICAL MACH NUMBER.....F
212.6/,5X,34HDRAG DIVERGENCE MACH NUMBER.....F12.6/,5X,35HCOMPRE
3SSIBILITY PCWER COEFF.....F12.6//,38H      *****
4*****F12.6//,38H      MAIN ROTOR POWER R
5REQUIRED//,58+*****
6*****INDUCED POWER = ,6X,F12.2/,22H      PROFILE POWER
7= ,6X,F12.2/,20H      PARASITE POWER = ,5X,F12.2/,29H      COMPRES
8IBILITY SPEED EFFECTS = ,F12.2/)
9      FORMAT (54H1*****F7.2/,54H*****/
1,10X,31HFORWARD VELOCITY IN KNOTS =
2*****THAN OR EQUAL TO 1.0/)
2890      FORMAT (/5X,44HTIP MACH NUMBER GREATER
2900      FORMAT (/5X,29HDISK PLANE ANGLE OF ATTACK = ,F10.6/)
2910      FORMAT (38H      COEFFICIENT OF THRUST.....F12.6/,38H      DI
1SC AREA.....F12.6/,38H      TIP-LOSS FACTOR.....F12.6//,
2      F12.6/,38H      GROUND EFFECT RATIO.....F12.6/,38H      MA
312.6//,38H      RADIUS.....F12.6/,38H      NUMBER OF MAIN ROTO
2920      FORMAT (38H1      CHCRD.....F12.6/,38H      AICRAFT GROSS WEIGHT.....HORI
1IN ROTOR CHCRD.....F12.6/,38H      ROTOR TIP VELOCITY.....F12.6/,38H      HORI
2R BLADES.....F12.6/,38H      ROTOR TIP VELOCITY.....F12.6/,38H      IN
312.6/,38H      ROTOR TIP VELOCITY.....F12.6/,38H      NUMBER OF ENGINES IN
4ZONTAL FLAT PLATE AREA.....F12.6//,38H      MAIN ROTOR HEIGHT ABOVE GROUND.....F1
5HELICOPTER.....AIR DENSITY (RHO).....F12.6/,38H      BLADE GEOMETRIC TWIST.....F1
62.6//,35H      AIR DENSITY (RHO).....F12.6/,38H      SONIC VE
7LOCITY.....F12.6//,38H      MAXIMUM 2-D LIFT CCEFFICIENT.....F12.6/
8.....F12.6//,38H      2-D STATIC STALL ANGLE (AMAX).....F12.7//,38H      LIFT CURV
9,38H      2-D STATIC STALL ANGLE (AMAX).....F12.6//,35H      ZERO-LIFT, DRAG COEFFICIENT
$E SLOPE (/RAD).....F12.6//,35H      CRITICAL MACH OF THE CRITICAL MACH NUMBER AT ,/2
$.....F12.6//,48H      ENTER THE VALUE OF THE CRITICAL MACH NUMBER AT ,/2
2930      FORMAT (/

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2940 11H ZERC ANGLE OF ATTACK)
      FORMAT (51H ENTER THE VALUE OF THE MAXIMUM COEFFICIENT OF LIFT,/,2
16H FOR YOUR SELECTED AIRFOIL)
2950 16H FOR YOUR SELECTED AIRFOIL)
      FORMAT (53H ENTER THE VALUE OF THE VELOCITY WHERE THE RETREATING, /
1,42H BLADE STALL ANGLE IS NEAREST 12.5 DEGREES)
2960 1,42H BLADE STALL ANGLE IS NEAREST 12.5 DEGREES)
      FORMAT (///42H ENTER THE SPAN OF THE VERTICAL STABILIZER)
2970 1,42H BLADE STALL ANGLE IS NEAREST 12.5 DEGREES)
      FORMAT (29H ENTER THE ROTOR SOLIDITY IS ,F9.7,/,35H ENTER THE VER
1TICAL STABILIZER AREA)
2980 1TICAL STABILIZER AREA)
      FORMAT (///36H VERTICAL STABILIZER DATA ,//,40X,23H 8
10 KNOTS 160 KNOTS,/,37H SECTION COEFFICIENT OF LIFT ,5X,
2F8.5,5X,F8.5,/,37H ANGLE OF ATTACK TO UNLOAD TAIL ROTOR,6X,F6.3,7X
3,F6.3)
      END

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D. SAMPLE OUTPUT

GROSS WEIGHT (LBS)	14400.00	
EMPTY WEIGHT (LBS)	4320.00	
SONIC SPEED (FPS)	1116.89	
MAXIMUM TIP VELOCITY (FPS)	725.98	
DISK LOADING	7.10	
ROTOR RADIUS (FT)	25.41	
ROTATIONAL VELOCITY (RPS)	28.57	
TIP VELOCITY (FPS)	725.98	
COEFFICIENT OF THRUST	0.005668	
ADVANCE RATIO	0.3721	
BLADE LOADING	0.0960	
SOLIDITY	0.0590377	
NUMBER OF MAIN ROTOR BLADES	4	
CHORD MAIN ROTOR BLADE (FT)	1.178138	21.567
THE ASPECT RATIO IS		28.572
THE ROTATIONAL SPEED IS		

GROSS WEIGHT (LBS)	14400.00	
EMPTY WEIGHT (LBS)	4320.00	
SONIC SPEED (FPS)	1116.89	
MAXIMUM TIP VELOCITY (FPS)	725.98	
DISK LOADING	7.10	
ROTOR RADIUS (FT)	25.41	
ROTATIONAL VELOCITY (RPS)	27.00	
TIP VELOCITY (FPS)	686.03	
COEFFICIENT OF THRUST	0.006347	
ADVANCE RATIO	0.3937	
BLADE LOADING	0.0920	
SOLIDITY	0.0689887	
NUMBER OF MAIN ROTOR BLADES	4	
CHORD MAIN ROTOR BLADE (FT)	1.377	
ASPECT RATIO OF MAIN ROTOR	18.46	
COEFF OF LIFT (AVG)	0.5520	
COEFF OF LIFT W/ R ALPHA	6.3025	
COEFF OF DRAG @ 0 LIFT	0.0100	

TIP LOSS FACTOR	=	0.9721020
POWER (INDUCED)(HP)	=	1310.3
POWER (PROFILE)(HP)	=	353.6
POWER (TOTAL)(HP)	=	1663.9
EMPTY WEIGHT (LBS)	=	8867.39
FUEL WEIGHT (LBS)	=	4000.00
NUMBER OF PEOPLE	=	14
USEFUL LOAD (LBS)	=	4500.00
NUMBER OF ENGINE	=	2
ESTIMATED GROSS WEIGHT(LBS)	=	17367.39
SOLIDITY	=	0.0762025
ROTOR RADIUS (FT)	=	26.734
HOVER POWER (HP)	=	1663.9
ROTOR WEIGHT(LBS)	=	1725.18
TAIL: ROTOR (LBS)	=	88.54
STRUCTURE (LBS)	=	111.77
BODY (LBS)	=	1323.89
LANDING GEAR (LBS)	=	624.21
NACELLE (LBS)	=	178.53
PROPULSION: ENGINE (LBS)	=	1215.64
ERIVE (LBS)	=	957.32
FUEL TANKS (LBS)	=	676.30
FLIGHT CONTRCLS (LBS)	=	587.49
AUXILIARY POWER (LBS)	=	190.00
INSTRUMENTS (LBS)	=	103.83
HYDRAULICS (LBS)	=	74.42
ELECTRICAL (LBS)	=	407.26
AVIONICS (LBS)	=	309.11
FURNISHINGS (LBS)	=	432.75
AIR AND ICE (LBS)	=	83.72
LOAD AND HANDLING (LBS)	=	84.50
REVISED EMPTY WEIGHT (LBS)	=	9174.45
REVISED GROSS WEIGHT (LBS)	=	17674.45

FIGURE OF MERIT (%) = 78.747

MAIN ROTOR POWER PROFILE

AIR SPEED (KNOTS)	TIP MACH	INDUCED (SHP)	SSL POWER PROFILE (SHP)	PARASITE (SHP)	TOTAL (SHP)
0.0	0.0	1335.0	1	0.0	1688.6
5.0	0.065	1320.6	1	0.04	1674.5
10.0	0.067	1278.5	3	0.30	1633.3
15.0	0.067	1211.9	5	1.03	1568.4
20.0	0.068	1136.6	5	2.44	1486.0
25.0	0.069	1030.3	5	4.76	1394.3
30.0	0.070	931.5	6	8.23	1302.6
35.0	0.071	845.9	6	13.06	1218.3
40.0	0.071	768.7	6	19.50	1145.6
45.0	0.072	687.2	7	27.08	1085.3
50.0	0.073	623.5	7	38.69	1038.5
55.0	0.073	552.8	8	50.81	1002.8
60.0	0.074	489.3	8	65.67	977.4
65.0	0.075	425.7	9	83.50	961.8
70.0	0.076	399.9	9	104.53	954.2
75.0	0.077	376.4	10	128.99	961.8
80.0	0.078	355.2	11	155.11	976.6
85.0	0.079	337.0	12	187.10	998.1
90.0	0.080	320.5	13	222.22	1026.1
95.0	0.081	305.2	14	261.67	1061.0
100.0	0.082	291.4	15	304.69	1102.2
105.0	0.083	278.2	16	352.52	1150.1
110.0	0.084	267.6	17	405.37	1204.6
115.0	0.085	254.6	18	463.47	1265.8
120.0	0.086	246.6	19	526.06	1333.8
125.0	0.087	237.6	20	595.36	1408.7
130.0	0.088	229.1	21	669.60	1490.7
135.0	0.089	221.3	22	749.02	1579.9
140.0	0.090	213.0	23	836.83	1676.6
145.0	0.091	204.5	24	928.26	1780.7
150.0	0.092	197.0	25	1028.55	1892.7
155.0	0.093	188.4	26	1134.93	2012.6
160.0	0.094	183.3	27	1247.62	2140.6
165.0	0.095	178.8	28	1368.84	2276.1
170.0	0.096	173.4	29	1496.84	2421.7
175.0	0.097	168.3	30	1632.84	2575.5
180.0	0.098	163.8	31	1776.06	2737.1
185.0	0.099	159.0	32	1929.73	2909.1
190.0	0.100	154.9	33	2089.06	3111.1

AT SPECIFICATION		MAIN ROTOR ALTITUDE		POWER PROFILE		PARASITE		TOTAL	
AIR SPEED (KNOTS)	TIP MACH	INDUCED (SHP)	POWER (SHP)	PARASITE (SHP)	TOTAL (SHP)	PARASITE (SHP)	TOTAL (SHP)		
0.0	0.63	1387.4	326.8	0.0	1715.2	0.0	1715.2		
5.0	0.64	1374.9	327.0	0.04	1701.9	0.08	1702.0		
10.0	0.65	1334.3	327.5	0.28	1662.4	0.95	1663.4		
15.0	0.66	1269.9	328.5	0.25	1599.7	0.95	1600.7		
20.0	0.67	1186.6	329.8	2.40	1518.8	4.77	1523.6		
25.0	0.67	1091.2	333.6	4.60	1427.0	7.95	1434.9		
30.0	0.69	994.4	336.1	7.07	1335.5	12.45	1348.0		
35.0	0.69	900.0	338.9	12.02	1248.1	18.65	1266.7		
40.0	0.69	815.1	342.0	18.66	1172.7	25.18	1197.9		
45.0	0.70	745.0	345.8	35.19	1107.9	46.84	1154.7		
50.0	0.71	675.0	349.8	46.84	1056.0	60.82	1116.8		
55.0	0.72	618.9	354.4	60.82	1015.6	77.37	1093.0		
60.0	0.72	570.6	358.0	77.37	985.9	96.49	1082.4		
65.0	0.73	528.2	369.5	96.49	952.8	114.16	1066.9		
70.0	0.74	492.3	375.4	114.16	948.7	144.91	1051.6		
75.0	0.75	460.0	381.7	144.91	951.7	172.25	1043.9		
80.0	0.76	432.1	385.3	172.25	961.4	201.40	1032.8		
85.0	0.77	407.7	390.2	201.40	978.5	241.55	1020.0		
90.0	0.78	384.8	402.5	241.55	1001.0	281.93	1031.9		
95.0	0.78	364.6	410.5	281.93	1031.0	325.75	1066.8		
100.0	0.80	330.5	418.7	325.75	1108.8	374.21	1157.0		
105.0	0.81	315.7	423.6	374.21	1157.0	428.91	1211.9		
110.0	0.82	308.9	436.5	428.91	1211.9	486.57	1273.5		
115.0	0.83	289.1	445.5	486.57	1273.5	549.57	1340.1		
120.0	0.84	277.0	455.2	549.57	1340.1	618.73	1415.3		
125.0	0.85	267.7	465.5	618.73	1415.3	692.58	1496.9		
130.0	0.86	257.4	475.7	692.58	1496.9	772.35	1584.3		
135.0	0.87	243.9	486.6	772.35	1584.3	858.24	1679.6		
140.0	0.88	231.4	497.3	858.24	1679.6	950.47	1781.1		
145.0	0.89	222.4	509.3	950.47	1781.1	1048.24	1891.7		
150.0	0.90	217.0	523.3	1048.24	1891.7	1153.77	2008.5		
155.0	0.91	210.4	534.6	1153.77	2008.5	1264.27	2133.0		
160.0	0.92	204.2	546.5	1264.27	2133.0	1383.95	2266.0		
165.0	0.93	198.2	559.3	1383.95	2266.0	1508.02	2407.0		
170.0	0.94	192.7	573.6	1508.02	2407.0	1642.69	2557.7		
175.0	0.95	187.6	586.1	1642.69	2557.7	1781.17	2715.9		
180.0	0.96	182.2	601.2	1781.17	2715.9				

TAIL ROTOR RADIUS (FT)= 5.451
 TAIL ROTOR SPEED (RPS)= 122.201
 TAIL ROTCR CDO = 0.0138000

TAIL ROTOR POWER PROFILE

AIR SPEED (KNOTS)	TIP MACH	INDUCED (SHP)	SSL POWER (SHP)	PROFILE (SHP)	TOTAL (SHP)
0.00	0.60	95.87	43.67	139.54	139.54
5.00	0.60	93.94	43.70	137.63	137.63
10.00	0.61	88.34	43.79	132.13	132.13
15.00	0.62	79.67	43.94	123.61	123.61
20.00	0.63	68.94	44.15	113.09	113.09
25.00	0.63	57.45	44.42	101.87	101.87
30.00	0.64	46.56	44.75	91.31	91.31
35.00	0.65	37.26	45.14	82.40	82.40
40.00	0.66	29.91	45.60	75.50	75.50
45.00	0.66	24.37	46.11	70.48	70.48
50.00	0.67	20.22	46.68	66.97	66.97
55.00	0.68	17.31	47.31	64.62	64.62
60.00	0.69	15.13	48.01	63.14	63.14
65.00	0.69	13.54	48.76	62.30	62.30
70.00	0.70	12.40	49.57	61.97	61.97
75.00	0.71	11.59	50.45	62.04	62.04
80.00	0.72	11.05	51.38	62.43	62.43
85.00	0.72	10.73	52.38	63.11	63.11
90.00	0.73	10.55	53.43	64.02	64.02
95.00	0.74	10.62	54.55	65.16	65.16
100.00	0.75	10.79	55.72	66.51	66.51
105.00	0.76	11.10	56.96	68.06	68.06
110.00	0.76	11.51	58.26	69.80	69.80
115.00	0.77	12.18	59.61	71.73	71.73
120.00	0.78	13.69	61.03	73.86	73.86
125.00	0.79	14.70	62.51	76.20	76.20
130.00	0.79	15.87	64.04	78.74	78.74
135.00	0.80	17.70	65.64	81.51	81.51
140.00	0.81	18.73	67.30	84.51	84.51
145.00	0.82	20.43	69.02	87.75	87.75
150.00	0.83	22.45	70.80	91.25	91.25
155.00	0.83	24.35	72.63	95.08	95.08
160.00	0.84	26.96	74.49	99.46	99.46
165.00	0.85	29.66	76.51	103.16	103.16
170.00	0.86	32.55	78.59	108.16	108.16
175.00	0.87	35.95	80.59	113.22	113.22
180.00	0.88	39.55	82.73	118.45	118.45
190.00	0.88	43.33	87.19	124.48	124.48
195.00	0.88	47.55	87.19	130.75	130.75

AT SPEED		TAIL ROTOR ALTITUDE AND TEMPERATURE		PROFILE		TOTAL	
AIR SPEEDS (KNOTS)		TIP MACH		INDUCED (SHP)		(SHP)	
0.0	0.0	0.58	102.3	1	40.35	142.66	
5.0	0.58	0.58	100.3	1	40.38	140.76	
10.0	0.59	0.59	94.7	9	40.46	135.25	
15.0	0.60	0.60	86.0	8	40.60	126.69	
20.0	0.61	0.61	75.1	8	40.80	115.98	
25.0	0.62	0.62	63.3	3	41.05	104.38	
30.0	0.63	0.63	51.7	6	41.72	93.19	
35.0	0.64	0.64	41.7	3	42.14	83.48	
40.0	0.64	0.64	33.6	0	42.61	75.73	
45.0	0.65	0.65	27.3	3	43.14	69.94	
50.0	0.66	0.66	22.6	5	43.72	65.79	
55.0	0.66	0.66	19.1	9	44.36	62.91	
60.0	0.67	0.67	16.6	4	45.06	61.00	
65.0	0.68	0.68	14.7	6	45.81	59.82	
70.0	0.69	0.69	12.3	9	46.62	59.20	
75.0	0.69	0.69	11.7	1	47.48	59.20	
80.0	0.70	0.70	11.2	7	48.38	59.67	
85.0	0.71	0.71	11.0	2	49.31	60.40	
90.0	0.72	0.72	10.9	5	50.41	61.52	
95.0	0.73	0.73	11.0	3	51.50	62.89	
100.0	0.74	0.74	11.6	1	52.64	63.45	
110.0	0.75	0.75	11.1	6	53.84	65.20	
120.0	0.75	0.75	12.7	1	55.09	67.14	
130.0	0.77	0.77	13.5	4	56.76	69.27	
140.0	0.77	0.77	14.4	1	57.18	71.60	
150.0	0.78	0.78	15.4	2	59.66	73.14	
160.0	0.79	0.79	16.7	1	60.19	76.90	
170.0	0.80	0.80	18.1	1	62.18	81.89	
180.0	0.80	0.80	19.6	1	63.42	85.11	
190.0	0.81	0.81	21.4	7	65.42	88.60	
200.0	0.82	0.82	23.7	0	67.18	92.35	
210.0	0.83	0.83	25.8	1	70.69	96.39	
220.0	0.84	0.84	28.9	4	72.55	100.74	
230.0	0.85	0.85	30.9	9	74.45	105.42	
240.0	0.85	0.85	33.6	6	76.45	110.45	
250.0	0.85	0.85	37.0	1	80.58	115.84	
260.0	0.85	0.85	41.0	6		121.64	

VERTICAL STABILIZER DATA

SECTION COEFFICIENT OF LIFT
ANGLE OF ATTACK TO UNLOAD TAIL ROTOR

80 KNOTS 160 KNOTS
0.83326 0.46359
22.263 3.268

RADI US.....
MAIN ROTOR CHCRD.....
NUMBER OF MAIN ROTOR BLADES.....
AIRCRAFT GRCS WEIGHT.....
ROTOR TIP VELCCITY.....
HORIZONTAL FLAT PLATE AREA.....
NUMBER OF ENGINES IN HELICOPTER..

26.733826
1.600000
0.000000
17585.0703
725.978027
29.308441
0.000000

MAIN ROTOR HEIGHT ABOVE GROUND...
AIR DENSITY (RHO).....
SONIC VELCCITY.....
BLADE GEOMETRIC TWIST.....

23.000000
0.002197
1154.32056
-0.174533

MAXIMUM 2-D LIFT COEFFICIENT.....
2-D STATIC STALL ANGLE (AMAX).....
LIFT CURVE SLCPE (/RAD).....
ZERO-LIFT CRAG COEFFICIENT.....
CRITICAL MACH NO (FOR CL = 0)..
COEFFICIENT OF THRUST.....
DISC AREA.....
SOLIDITY.....
TIP-LOSS FACTOR.....
GROUND EFFECT RATIO.....

1.250000
0.1983330
6.302530
0.010000
0.720000
0.006765
2245.28784
0.076202
0.970920
0.874897


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*****
** FORWARD VELOCITY IN KNOTS = 0.0 *****
** DISK PLANE ANGLE OF ATTACK = 0.0 *****

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DYNAMIC PARAMETERS

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A11..... 0.0
A12..... 0.0
A13..... 0.0
A14..... 1.000000
T1..... 0.471343
T2..... 0.305091
T3..... 0.222164
T4..... 0.0
INFLOW RATIO (LAMBDA)..... -0.058160

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STALL PCWER CALCULATIONS

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RT..... -0.028292
INBOARD STALL CORRECTION FACTOR..... 0.0
STALL POWER COEFFICIENT..... 0.0

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ANGLE OF ATTACK CALCULATIONS

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LONGITUDINAL CYCLIC ANGLE(DEG)..... 0.0
LONGITUDINAL COLLECTIVE ANGLE(DEG)..... 17.720932
ALPHA(90) (DEG)..... 4.388375
ALPHA(270) (DEG)..... 4.388375

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HIGH SPEED MACH EFFECTS

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ADVANCING BLADE TIP MACH NUMBER..... 0.628922
CRITICAL MACH NUMBER..... 0.665450
DRAG DIVERGENCE MACH NUMBER..... 0.0
COMPRESSIBILITY POWER COEFF..... 0.0

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MAIN ROTOR POWER REQUIRED

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INDUCED POWER = 1388.74
PROFILE POWER = 326.81
PARASITE POWER = 0.0
COMPRESSIBILITY POWER = 0.0
STALL POWER = 0.0
HIGH SPEED EFFECTS = 0.0

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 FORWARD VELOCITY IN KNOTS = 140.00

DYNAMIC PARAMETERS

A11	0.711244
A12	0.947375
A13	0.689869
A14	1.238236
T1	0.497838
T2	0.356539
T3	0.247140
T4	0.157756
INFLW RATIO (LAMBDA)	-0.053642

STALL POWER CALCULATIONS

RT	0.002215
INBOARD STALL CORRECTION FACTOR	0.5647528
STALL POWER COEFFICIENT	0.0000402

ANGLE OF ATTACK CALCULATIONS

LONGITUDINAL CYCLIC ANGLE(DEG)	-7.126393
LONGITUDINAL COLLECTIVE ANGLE(DEG)	18.903610
ALPHA(90) (DEG)	-0.541373
ALPHA(270) (DEG)	13.710670

HIGH SPEED MACH EFFECTS

ADVANCING BLADE TIP MACH NUMBER	0.8333665
CRITICAL MACH NUMBER	0.726730
DRAW DIVERGENCE MACH NUMBER	0.046935
COMPRESSIBILITY POWER COEFF	0.000044

MAIN ROTOR POWER REQUIRED

INDUCED POWER =	247.98
PROFILE POWER =	475.75
PARASITE POWER =	772.58
COMPRESSIBILITY POWER =	149.96
STALL PCWER =	137.91

HIGH SPEED EFFECTS =	287.86
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NOTE THE VELOCITY THAT HAS THE STALL ANGLE LESS
THAN OR EQUAL TO 12.5 DEGREES

VELOCITY (KNOTS)	ANGLE (DEG)
126.94	12.1
127.94	12.2
128.94	12.3
129.94	12.4
130.94	12.6
131.94	12.7
132.94	12.8
133.94	12.9

TOTAL POWER FOR THE AIRCRAFT TO HOVER IS= 1829.48

TOTAL ROTOR POWER PROFILE

AIR SPEED (KNOTS)	INDUCED (SHP)	PROFILE (SHP)	PARASITE (SHP)	COMP (SHP)	TOTAL (SHP)
0.0	1430.88	397.31	0.0	0.0	1828.19
5.0	1416.52	397.55	0.0	0.0	1812.07
10.0	1366.64	398.26	0.30	0.0	1765.48
15.0	1291.58	399.43	1.03	0.0	1692.10
20.0	1155.26	401.08	2.47	0.0	1599.81
25.0	1088.57	403.20	4.76	0.0	1496.23
30.0	978.84	405.86	8.23	0.0	1393.99
35.0	878.23	408.40	13.06	0.0	1300.77
40.0	789.11	412.40	19.50	0.0	1221.13
45.0	712.54	416.40	27.76	0.0	1156.50
50.0	646.50	420.88	38.09	0.0	1105.42
55.0	590.51	425.55	50.61	0.0	1067.57
60.0	543.50	431.25	65.81	0.0	1040.57
65.0	502.54	437.15	83.67	0.0	1023.71
70.0	467.36	443.55	104.50	0.0	1015.85
75.0	437.17	450.35	128.99	0.0	1016.32
80.0	410.68	457.65	155.99	0.0	1039.71
85.0	387.35	465.43	187.11	0.0	1062.13
90.0	366.66	473.49	226.22	0.0	1091.43
95.0	347.15	482.49	261.69	0.0	1127.76
100.0	331.23	491.52	304.69	4.39	1181.32
105.0	316.03	501.39	352.53	11.36	1251.32
110.0	303.57	511.30	403.37	12.18	1327.98
115.0	290.11	523.08	465.06	14.40	1411.04
120.0	277.01	534.66	529.36	20.44	1503.73
125.0	261.33	545.69	599.60	28.74	1601.73
130.0	246.53	558.25	674.90	37.09	1708.23
135.0	233.49	569.14	736.02	45.80	1822.50
140.0	224.05	582.54	828.55	57.13	1944.83
145.0	217.39	599.83	923.77	70.93	2172.91
150.0	212.41	623.67	1034.93	87.13	2397.63
155.0	208.59	638.99	1124.75	105.91	2562.63
160.0	204.10	653.79	1234.68	129.78	2723.98
165.0	200.39	669.05	1368.84	150.22	2887.80
170.0	196.04	686.05	1493.22	172.78	3057.15
175.0	192.12	702.79	1677.90	222.41	3233.62
180.0	188.55	719.67	1928.90	256.74	3418.44
185.0	185.45	737.67	2089.73	272.74	3612.59

AIRSPEED (KNOTS)	AT SPEED	TOTAL ROTOR POWER PROFILE AND TEMPERATURE			
		INDUCED (SHP)	PROFILE (SHP)	PARASITE (SHP)	TOTAL (SHP)
0.00	0.00	1491.04	367.17	0.00	1858.21
5.00	0.00	1479.18	367.38	0.00	1842.73
10.00	0.00	1429.00	368.04	0.00	1797.50
15.00	0.00	1356.00	369.13	0.00	1726.08
20.00	0.00	1261.31	370.61	0.00	1634.75
25.00	0.00	1155.03	372.01	0.00	1532.32
30.00	0.00	1046.03	375.84	0.00	1428.64
35.00	0.00	942.21	377.84	0.00	1332.12
40.00	0.00	848.43	381.11	0.00	1247.91
45.00	0.00	767.43	384.95	0.00	1177.89
50.00	0.00	697.67	388.52	0.00	1121.81
55.00	0.00	638.14	393.53	0.00	1078.51
60.00	0.00	587.25	398.58	0.00	1046.59
65.00	0.00	543.67	403.86	0.00	1024.80
70.00	0.00	505.73	409.18	0.00	1012.10
75.00	0.00	472.86	416.93	0.00	1007.68
80.00	0.00	443.86	422.12	0.00	1010.94
85.00	0.00	418.40	437.74	0.00	1021.42
90.00	0.00	395.70	445.80	0.00	1038.90
95.00	0.00	375.53	454.29	0.00	1062.04
100.00	0.00	357.53	463.59	0.49	1094.82
105.00	0.00	341.56	472.59	1.14	1148.36
110.00	0.00	326.81	482.39	1.06	1210.67
115.00	0.00	313.51	492.63	2.75	1278.82
120.00	0.00	301.16	503.30	5.57	1353.52
125.00	0.00	291.43	514.41	9.10	1435.58
130.00	0.00	281.62	525.96	11.63	1525.08
135.00	0.00	272.63	537.94	13.86	1621.47
140.00	0.00	264.53	550.35	18.57	1863.80
145.00	0.00	257.18	563.20	20.46	2046.22
150.00	0.00	250.45	576.49	23.59	2235.12
155.00	0.00	243.40	590.27	28.69	2482.30
160.00	0.00	236.22	604.97	33.39	2614.83
165.00	0.00	229.29	618.00	39.13	2753.63
170.00	0.00	222.66	634.06	45.28	2900.56
175.00	0.00	216.33	649.36	51.87	3055.96
180.00	0.00	210.22	665.70	54.71	3220.03
185.00	0.00	204.32	681.17	55.55	3394.03

-----FUEL FLOW RATES-----
 MILITARY POWER 2142.00 NORMAL POWER 1854.36 CRUISE POWER 1517.66

TEMPERATURE (R) = 504.423
 PRESSURE (PSF) = 1827.697
 ALPHA AT SSL = 624.344
 THETA AT SPEC ALTITUDE = 0.972
 DELTA AT SPEC ALTITUDE = 0.864
 ZERC HORSEPOWER INTERCEPT = 531.755
 AT SPEC ALTITUDE

THE ZERO HORSEPOWER INCREMENT AT ALTITUDE= 2221.240

THE FUEL WEIGHT IS = 3959.12LBS
 THE DESIGN GROSS WEIGHT IS = 18368.34
 THE ESTIMATED GROSS WEIGHT IS = 17585.07

THE BEST RATE OF CLIMB IS 3800.00 FEET PER MINUTE

THE HOVER CEILING ALTITUDE IS = 12000.00

THE SERVICE CEILING ALTITUDE IS = 21000.00

HELICOPTER DESIGN AE4306 FINAL SUMMARY

PERFORMANCE

	SPECIFICATION	DESIGN
CREW.....	3	14
INTERNAL LOAD(LBS).....	3750.0	4500.0
SERVICE CEILING(FT).....	17500.0	21000.0
HOVER ICE (FT).....	12000.0	12000.0
VELOCITY (KTS).....	135.0	170.0
CRUISE.....	160.0	196.0
MAXIMUM.....		170.0
MAX ENDURANCE.....		170.0
MAX RANGE.....		130.0
RETRACTING BLADE STALL.....		250.0
MAXIMUM RANGE (NMI).....	250.0	3800.0
MAXIMUM RATE OF CLIMB (FT/MIN).....	2500.0	2
ENGINE - NUMBER.....		D
TYPE.....		3600.0
SHP (SSL) MILITARY.....		

GEOMETRY

WEIGHT (LBS) - MAX GROSS.....	18000.0	18368.3
EMPTY.....		9095.5
FUEL CAPACITY (GAL) - INTERNAL.....		609.1
EXTERNAL.....		0.0
MAIN ROTOR - CHORD (FT).....		1.60
RADIUS (FT).....		26.73
NUMBER OF BLADES.....		4
DRAW COEFFICIENT.....		0.0100
ROTATIONAL VELOCITY.....		27.16
SOLIDITY.....		0.076202
TAIL ROTOR - CHORD (FT).....		0.91
RADIUS (FT).....		5.45
NUMBER BLADES.....		4
DRAW COEFFICIENT.....		0.0138
ROTATIONAL VELOCITY.....		122.20
SOLIDITY.....		0.212207
VERTICAL TAIL AREA (FT).....		55.43
FUSELAGE LENGTH (FT).....		50.10
EQUIVALENT FLAT PLAGE AREA (FT) FORWARD	56.00	29.31
VERTICAL		58.62

COST ANALYSIS PER VEHICLE (IN DOLLARS FOR 100 A/C RUN)

ROTOR		207647.31
TAIL:		11561.87
STRUCTURE		20104.41
BODY		182568.06
LANDING GEAR		119506.94
NACELLE		34988.90
PROPULSION:	ENGINE	1281599.00
	DRIVE	121739.87
	FUEL TANKS	160159.44
FLIGHT CCNTFOLS		109443.50
AUXILLARY PCWER		54357.60
INSTRUMENTS		15419.93
HYDRAULICS		8067.89
ELECTRICAL		68819.65
AVIONICS		52901.66
FURNISHINGS		35208.07
AIR AND ICE		21086.03
LOAD AND HANDLING		20675.80
TOTAL CCST PER VEHICLE	=	2525889.00

APPENDIX C

TABLE III

AH-64 Data

<u>Parameter</u>	<u>Value</u>	
Main rotor radius	24.0	feet
Tail rotor radius	4.6	feet
Number of main rotor blades	4	
Number of tail rotor blades	4	
Height of the main rotor system	12.6	feet
Speed of the main rotor	30.3	rads/sec
Speed of the tail rotor	147.0	rads/sec
Chord of the main rotor	1.75	feet
Chord of the tail rotor	0.83	feet
Span of the main rotor	18.8	feet
Span of the tail rotor	3.1	feet
Twist of the main rotor blade	-9.0	degrees
Twist of the tail rotor blade	-8.8	degrees
Profile drag of the main rotor blade	0.009	
Profile drag of the tail rotor blade	0.009	
Disc loading of the main rotor system	8.1	
Width of the fuselage	3.96	feet
Length of the fuselage	49.1	feet
Frontal equivalent flat plate area	34.7	sq ft
Vertical equivalent flat plate area	45.8	sq ft
Maximum forward velocity	154	knots
Maximum range	246	nmi
Rate of climb	2490	ft/min
Hover ceiling (IGE)	14,200	feet
Hover ceiling (OGE)	11,000	feet
Length of the tail	29.7	feet
Operating weight	11,010	pounds
Load weight	2,020	pounds
Fuel weight	1,620	pounds
Maximum gross weight	14,650	pounds

TABLE IV

OH-6A Data

<u>Parameter</u>	<u>Value</u>	
Main rotor radius	16.3	feet
Tail rotor radius	4.3	feet
Number of main rotor blades	4	
Number of tail rotor blades	2	
Height of the main rotor system	7.0	feet
Speed of the main rotor	49.2	rads/sec
Speed of the tail rotor	315.0	rads/sec
Chord of the main rotor	0.57	feet
Chord of the tail rotor	0.40	feet
Span of the main rotor	11.5	feet
Span of the tail rotor	1.4	feet
Twist of the main rotor blade	-9.0	degrees
Twist of the tail rotor blade	-8.0	degrees
Profile drag of the main rotor blade	0.009	
Profile drag of the tail rotor blade	0.009	
Disc loading of the main rotor system	8.1	
Width of the fuselage	4.57	feet
Length of the fuselage	23.0	feet
Frontal equivalent flat plate area	5.0	sq ft
Vertical equivalent flat plate area	10.8	sq ft
Maximum forward velocity	116	knots
Maximum range	330	nmi
Rate of climb	500	ft/min
Hover ceiling (IGE)	7,100	feet
Hover ceiling (OGE)	4,200	feet
Length of the tail	15.2	feet
Operating weight	1,160	pounds
Load weight	960	pounds
Fuel weight	400	pounds
Maximum gross weight	2,520	pounds

TABLE V
SH-3H Data

<u>Parameter</u>	<u>Value</u>	
Main rotor radius	31.0	feet
Tail rotor radius	5.3	feet
Number of main rotor blades	5	
Number of tail rotor blades	5	
Height of the main rotor system	14.3	feet
Speed of the main rotor	21.3	rads/sec
Speed of the tail rotor	130.0	rads/sec
Chord of the main rotor	1.52	feet
Chord of the tail rotor	0.61	feet
Span of the main rotor	29.3	feet
Span of the tail rotor	4.0	feet
Twist of the main rotor blade	-8.0	degrees
Twist of the tail rotor blade	0.0	degrees
Profile drag of the main rotor blade	0.0095	
Profile drag of the tail rotor blade	0.0105	
Disc loading of the main rotor system	6.96	
Width of the fuselage	7.08	feet
Length of the fuselage	31.3	feet
Frontal equivalent flat plate area	31.3	sq ft
Vertical equivalent flat plate area	36.0	sq ft
Maximum forward velocity	120	knots
Maximum range	505	nmi
Rate of climb	500	ft/min
Hover ceiling (IGE)	3,700	feet
Hover ceiling (OGE)	4,000	feet
Length of the tail	36.6	feet
Operating weight	13,600	pounds
Load weight	1,760	pounds
Fuel weight	5,640	pounds
Maximum gross weight	21,000	pounds

TABLE VI

S-76 Data

<u>Parameter</u>	<u>Value</u>	
Main rotor radius	22.0	feet
Tail rotor radius	4.0	feet
Number of main rotor blades	4	
Number of tail rotor blades	4	
Height of the main rotor system	10.0	feet
Speed of the main rotor	30.7	rads/sec
Speed of the tail rotor	168.0	rads/sec
Chord of the main rotor	1.29	feet
Chord of the tail rotor	0.54	feet
Span of the main rotor	17.0	feet
Span of the tail rotor	3.3	feet
Twist of the main rotor blade	-10.0	degrees
Twist of the tail rotor blade	-8.0	degrees
Profile drag of the main rotor blade	0.009	
Profile drag of the tail rotor blade	0.015	
Disc loading of the main rotor system	8.1	
Width of the fuselage	7.00	feet
Length of the fuselage	43.4	feet
Frontal equivalent flat plate area	11.6	sq ft
Vertical equivalent flat plate area	30.0	sq ft
Maximum forward velocity	155	knots
Maximum range	404	nmi
Rate of climb	425	ft/min
Hover ceiling (IGE)	6,200	feet
Hover ceiling (OGE)	2,800	feet
Length of the tail	26.5	feet
Operating weight	5,600	pounds
Load weight	2,520	pounds
Fuel weight	1,880	pounds
Maximum gross weight	10,000	pounds

TABLE VII

UH-60A Data

<u>Parameter</u>	<u>Value</u>	
Main rotor radius	26.8	feet
Tail rotor radius	4.0	feet
Number of main rotor blades	4	
Number of tail rotor blades	4	
Height of the main rotor system	11.2	feet
Speed of the main rotor	27.2	rads/sec
Speed of the tail rotor	125.0	rads/sec
Chord of the main rotor	1.75	feet
Chord of the tail rotor	0.81	feet
Span of the main rotor	29.3	feet
Span of the tail rotor	4.25	feet
Twist of the main rotor blade	-18.0	degrees
Twist of the tail rotor blade	-18.0	degrees
Profile drag of the main rotor blade	0.008	
Profile drag of the tail rotor blade	0.008	
Disc loading of the main rotor system	8.95	
Width of the fuselage	7.75	feet
Length of the fuselage	50.1	feet
Frontal equivalent flat plate area	25.7	sq ft
Vertical equivalent flat plate area	30.8	sq ft
Maximum forward velocity	156	knots
Maximum range	275	nmi
Rate of climb	200	ft/min
Hover ceiling (IGE)	7,800	feet
Hover ceiling (OGE)	3,900	feet
Length of the tail	31.5	feet
Operating weight	10,680	pounds
Load weight	7,270	pounds
Fuel weight	2,350	pounds
Maximum gross weight	20,250	pounds

TABLE VIII

CH-54B Data

<u>Parameter</u>	<u>Value</u>	
Main rotor radius	36.0	feet
Tail rotor radius	8.0	feet
Number of main rotor blades	6	
Number of tail rotor blades	4	
Height of the main rotor system	17.6	feet
Speed of the main rotor	19.4	rads/sec
Speed of the tail rotor	66.0	rads/sec
Chord of the main rotor	1.97	feet
Chord of the tail rotor	1.28	feet
Span of the main rotor	29.8	feet
Span of the tail rotor	6.45	feet
Twist of the main rotor blade	-8.0	degrees
Twist of the tail rotor blade	-8.0	degrees
Profile drag of the main rotor blade	0.0095	
Profile drag of the tail rotor blade	0.0105	
Disc loading of the main rotor system	10.3	
Width of the fuselage	7.08	feet
Length of the fuselage	70.2	feet
Frontal equivalent flat plate area	65.0	sq ft
Vertical equivalent flat plate area	99.4	sq ft
Maximum forward velocity	110	knots
Maximum range	200	nmi
Rate of climb	189	ft/min
Hover ceiling (IGE)	6,400	feet
Hover ceiling (OGE)	2,400	feet
Length of the tail	44.5	feet
Operating weight	19,230	pounds
Load weight	14,190	pounds
Fuel weight	8,580	pounds
Maximum gross weight	42,000	pounds

TABLE IX

CH-53D Data

<u>Parameter</u>	<u>Value</u>	
Main rotor radius	36.1	feet
Tail rotor radius	8.0	feet
Number of main rotor blades	6	
Number of tail rotor blades	4	
Height of the main rotor system	15.8	feet
Speed of the main rotor	19.4	rads/sec
Speed of the tail rotor	83.0	rads/sec
Chord of the main rotor	2.17	feet
Chord of the tail rotor	1.28	feet
Span of the main rotor	28.9	feet
Span of the tail rotor	6.45	feet
Twist of the main rotor blade	-6.0	degrees
Twist of the tail rotor blade	-8.0	degrees
Profile drag of the main rotor blade	0.0095	
Profile drag of the tail rotor blade	0.0095	
Disc loading of the main rotor system	10.3	
Width of the fuselage	8.83	feet
Length of the fuselage	67.2	feet
Frontal equivalent flat plate area	47.3	sq ft
Vertical equivalent flat plate area	90.0	sq ft
Maximum forward velocity	164	knots
Maximum range	242	nm
Rate of climb	625	ft/min
Hover ceiling (IGE)	14,000	feet
Hover ceiling (OGE)	8,000	feet
Length of the tail	44.5	feet
Operating weight	23,630	pounds
Load weight	14,030	pounds
Fuel weight	4,340	pounds
Maximum gross weight	42,000	pounds

TABLE X

CH-53E Data

<u>Parameter</u>	<u>Value</u>	
Main rotor radius	38.5	feet
Tail rotor radius	10.0	feet
Number of main rotor blades	7	
Number of tail rotor blades	4	
Height of the main rotor system	16.0	feet
Speed of the main rotor	18.7	rads/sec
Speed of the tail rotor	73.0	rads/sec
Chord of the main rotor	2.44	feet
Chord of the tail rotor	1.28	feet
Span of the main rotor	28.6	feet
Span of the tail rotor	8.53	feet
Twist of the main rotor blade	-13.6	degrees
Twist of the tail rotor blade	-8.0	degrees
Profile drag of the main rotor blade	0.009	
Profile drag of the tail rotor blade	0.0095	
Disc loading of the main rotor system	15.0	
Width of the fuselage	8.83	feet
Length of the fuselage	99.0	feet
Frontal equivalent flat plate area	120.0	sq ft
Vertical equivalent flat plate area	63.6	sq ft
Maximum forward velocity	146	knots
Maximum range	400	nmi
Rate of climb	325	ft/min
Hover ceiling (IGE)	6,000	feet
Hover ceiling (OGE)	1,400	feet
Length of the tail	48.0	feet
Operating weight	24,790	pounds
Load weight	15,480	pounds
Fuel weight	25,480	pounds
Maximum gross weight	73,500	pounds

HELICOPTER DESIGN

AE 4306/4900

- | | |
|----------|-----------|
| 1. AH-64 | 8. UH-60A |
| 2. OH-6A | 9. CH-54B |
| 3. BH-3H | 7. CH-53D |
| 4. S-76 | 6. CH-54E |

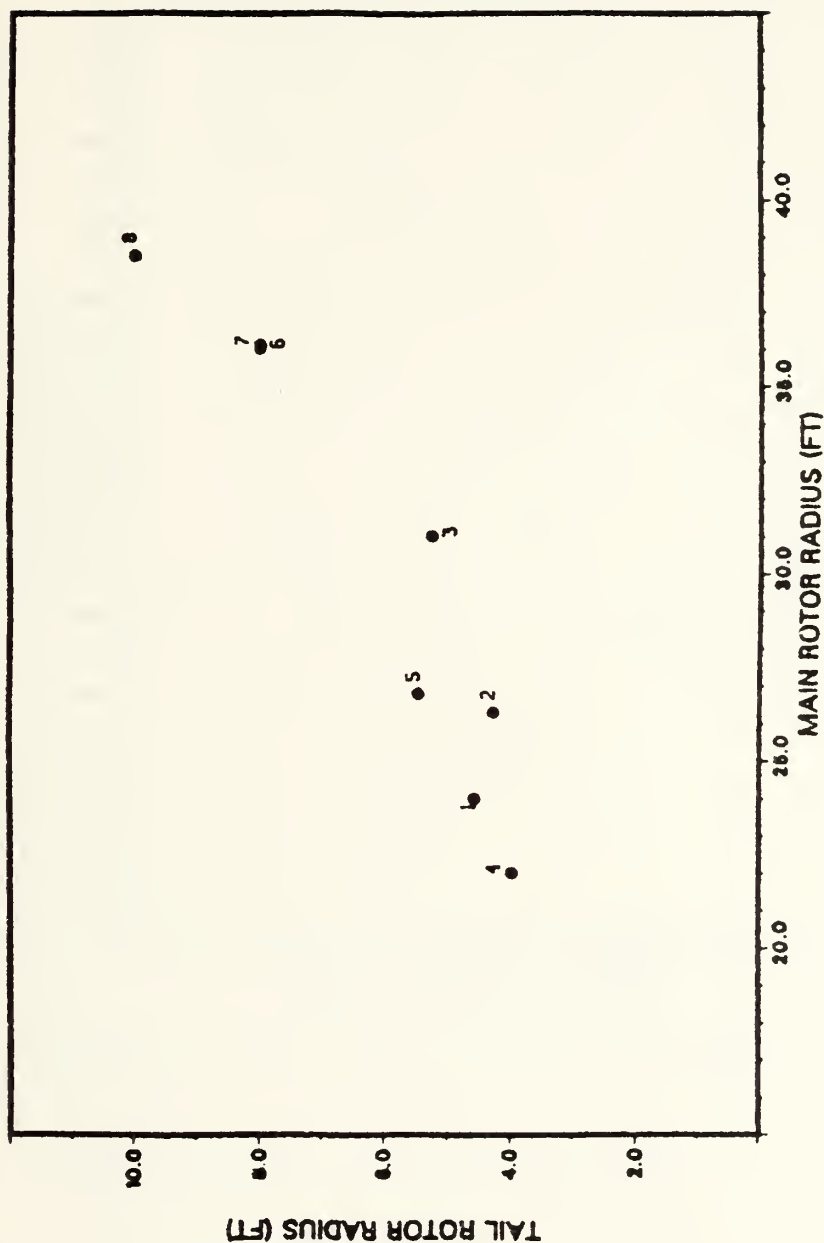


Figure 3.1. X-Y Plot (horizontal page format)

HELICOPTER DESIGN

AE 4306/4800

1. AH-64	8. UH-60A
2. OH-6A	9. CH-54B
3. BH-3H	7. CH-53D
4. S-70	6. CH-54E

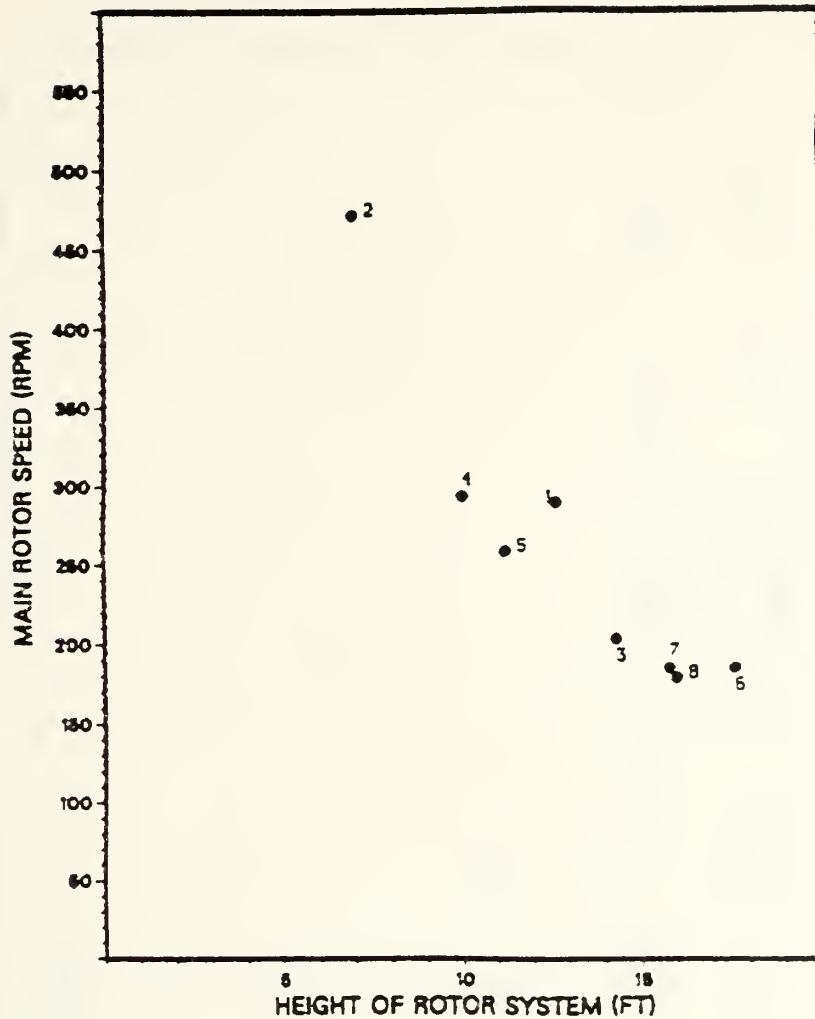


Figure 3.2. X-Y Plot (vertical page format)

HELICOPTER DESIGN

AE 4306/4900

- | | |
|----------|-----------|
| 1. AH-64 | 6. UH-60A |
| 2. OH-6A | 7. CH-54B |
| 3. SH-3H | 8. CH-53D |
| 4. S-76 | 9. CH-54E |

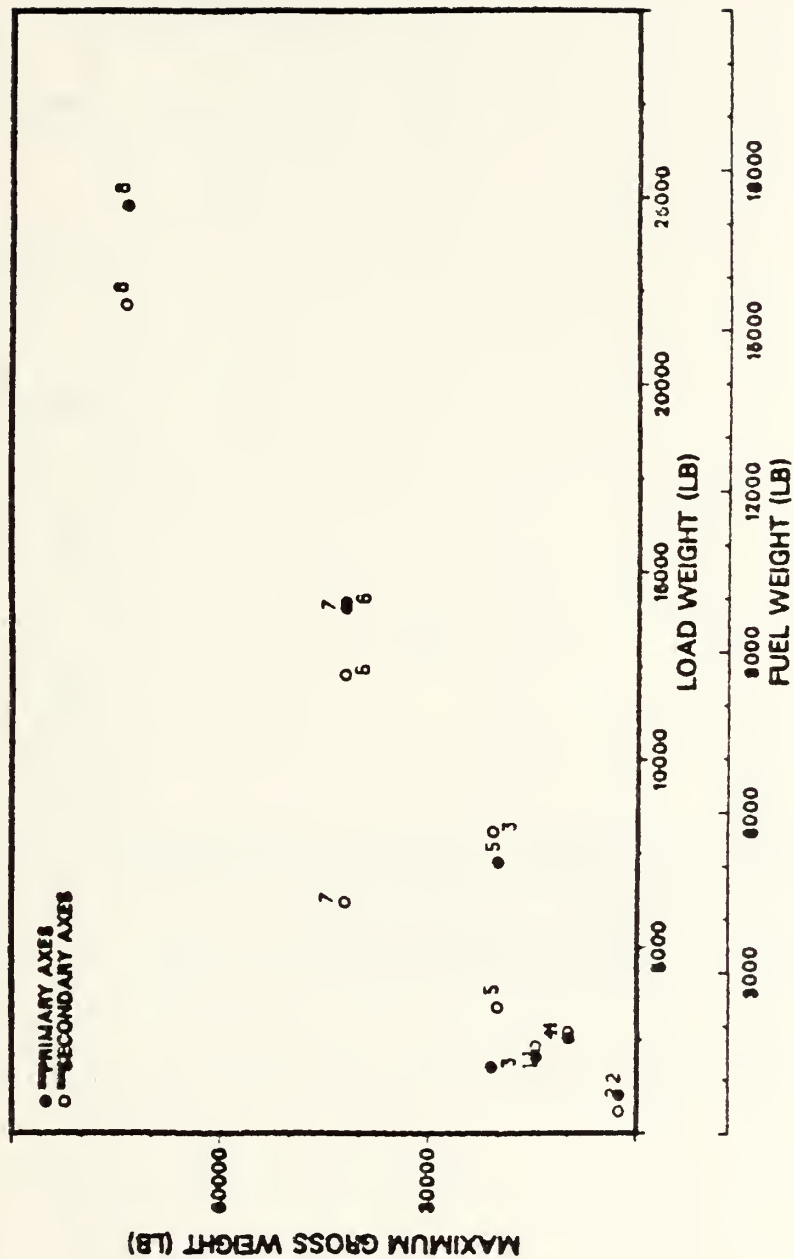


Figure 3.3. Multiple X Axes Plot (horizontal page format)

HELICOPTER DESIGN

AE 4306/4900

1. AH-64	5. UH-60A
2. OH-6A	6. CH-54B
3. SH-3H	7. CH-53D
4. S-76	8. CH-54E

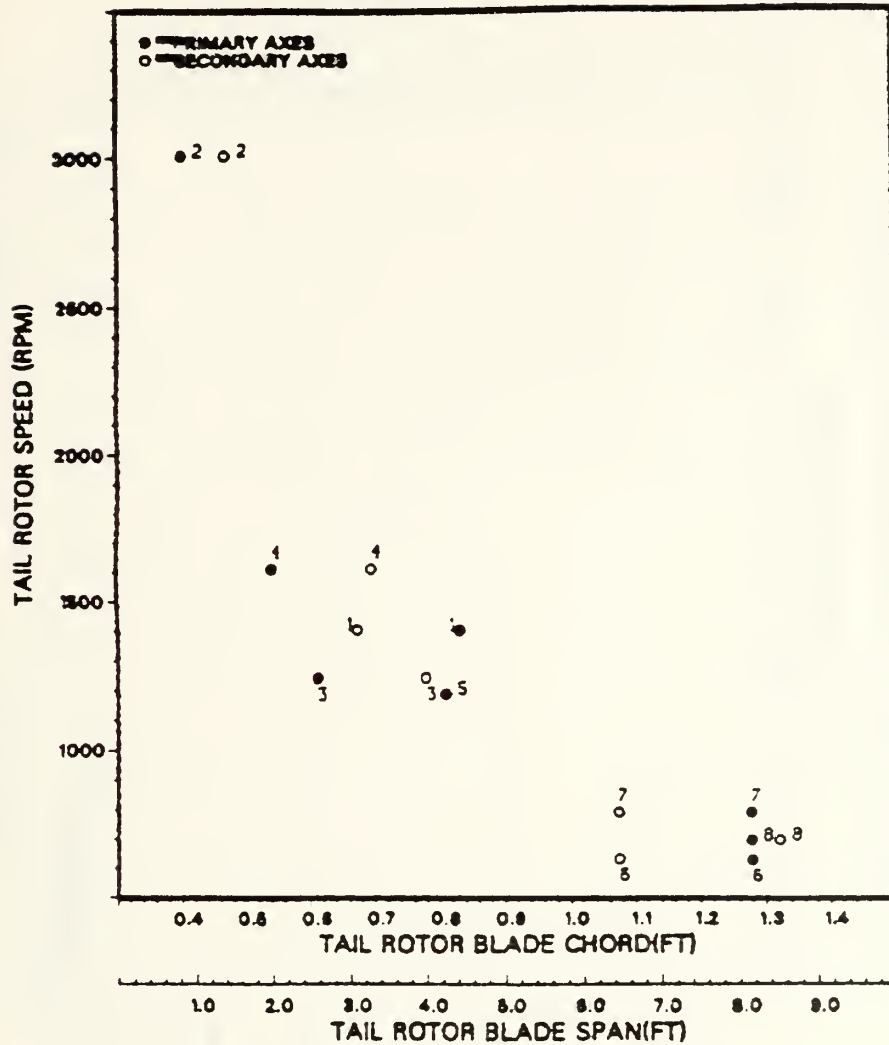


Figure 3.4. Multiple X Axes Plot (vertical page format)

HELICOPTER DESIGN

AE 4306/4800

1. AH-64 8. UH-60A
2. CH-53A 9. CH-53B
3. SH-60 7. CH-53D
4. S-70 6. CH-53E

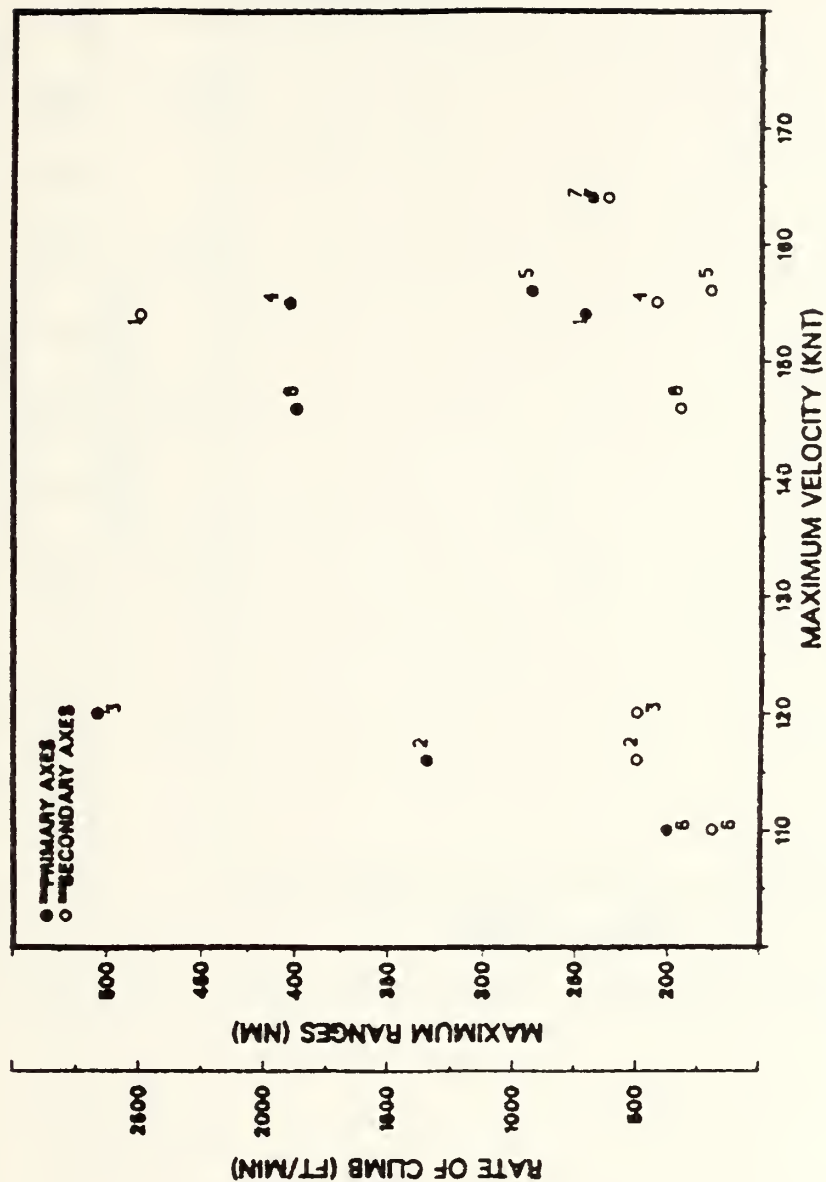


Figure 3.5. Multiple Y Axes Plot (horizontal page format)

HELICOPTER DESIGN

AE 4306/4900

1. AH-64	5. UH-60A
2. OH-6A	6. CH-54B
3. SH-3H	7. CH-53D
4. S-70	8. CH-54E

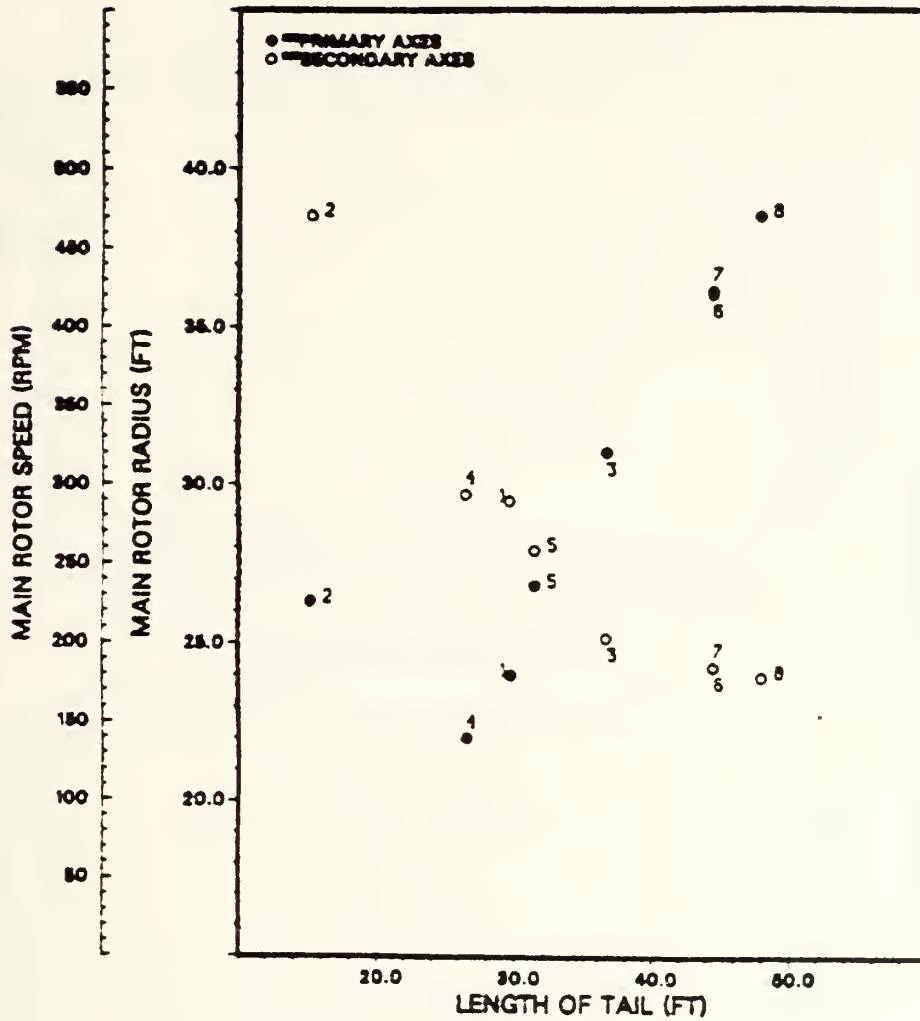


Figure 3.6. Multiple Y Axes Plot (vertical page format)

HELICOPTER DESIGN

AE 4306/4900

- 1. AH-64
- 2. OH-6A
- 3. EH-60
- 4. S-76
- 5. UH-60A
- 6. CH-54E
- 7. CH-53D
- 8. CH-54E

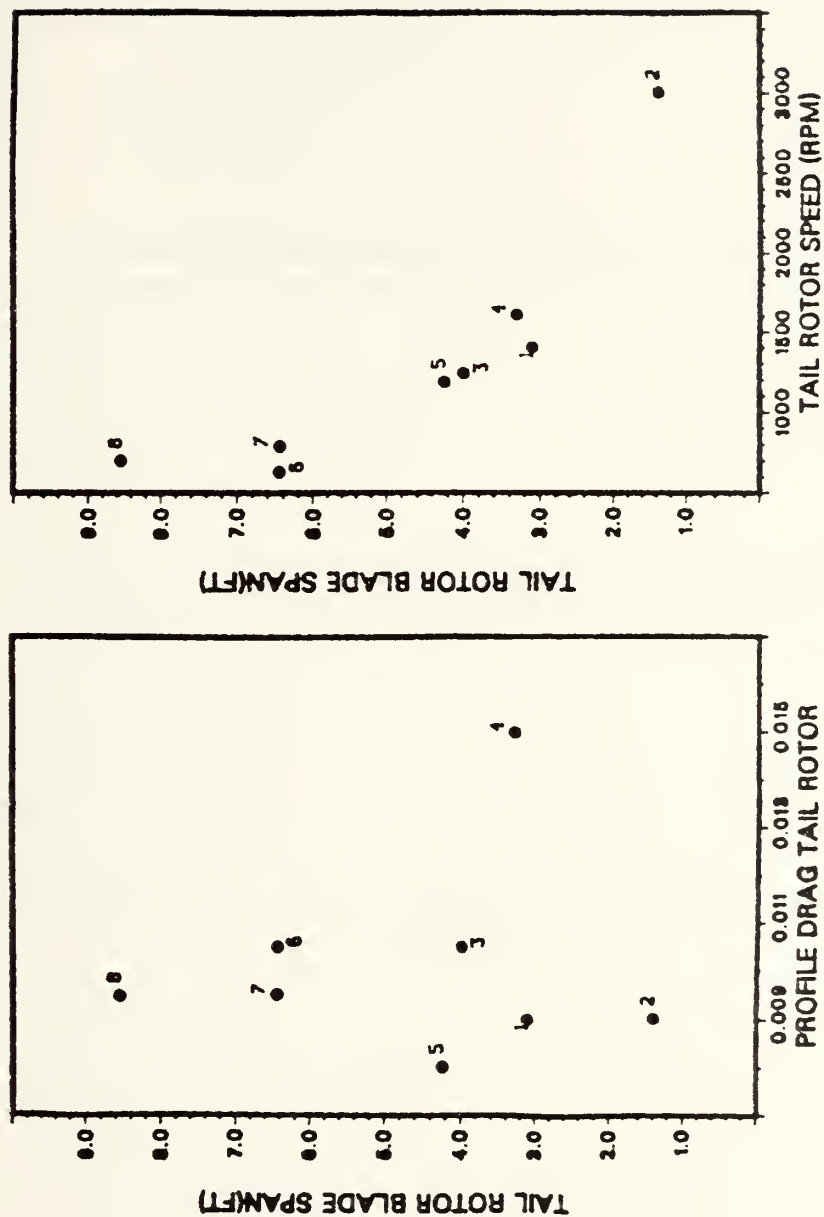


Figure 3.7. Two Plot Option

HELICOPTER DESIGN

AE 4306/4900

1. AH-64	8. UH-60A
2. OH-6A	9. CH-53E
3. SH-3H	7. CH-53D
4. S-70	6. CH-54E

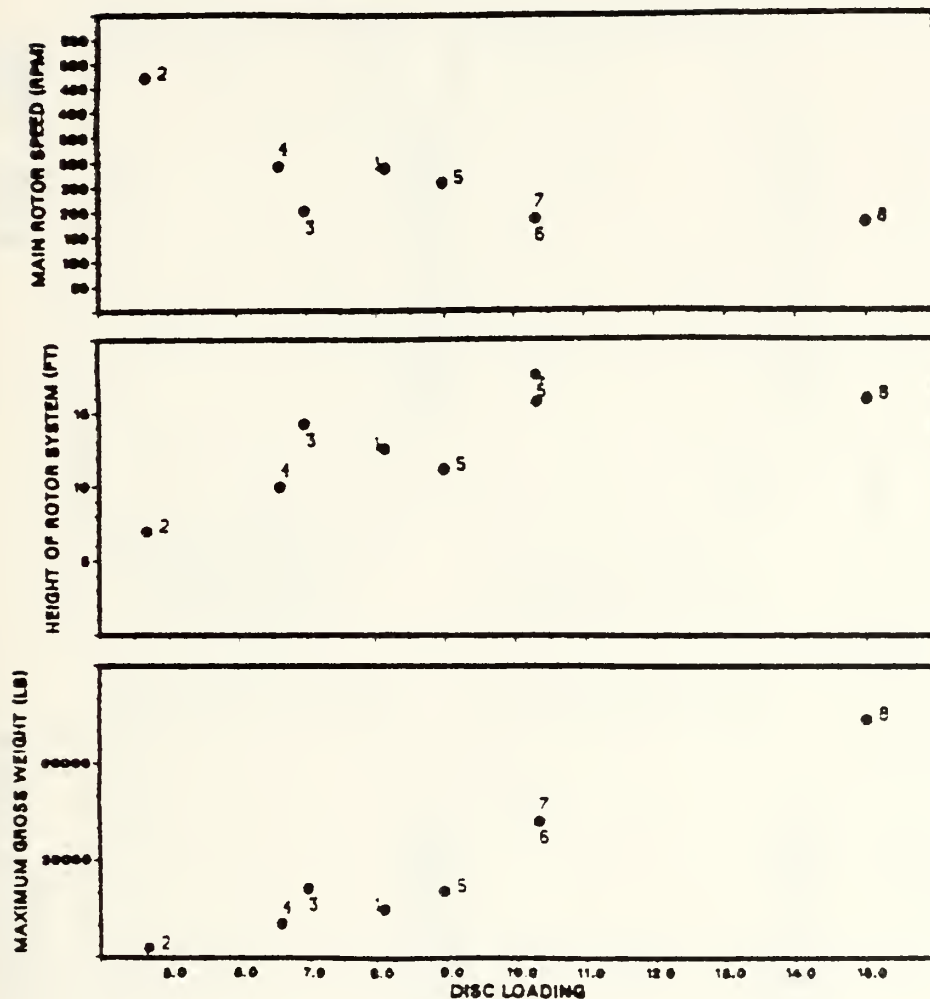


Figure 3.8. Three Plot Option

HELICOPTER DESIGN

AE 4306/4900

1. AH-64 8. UH-60A
2. OH-6A 9. CH-54E
3. EH-60 7. CH-53D
4. S-76 6. CH-54E

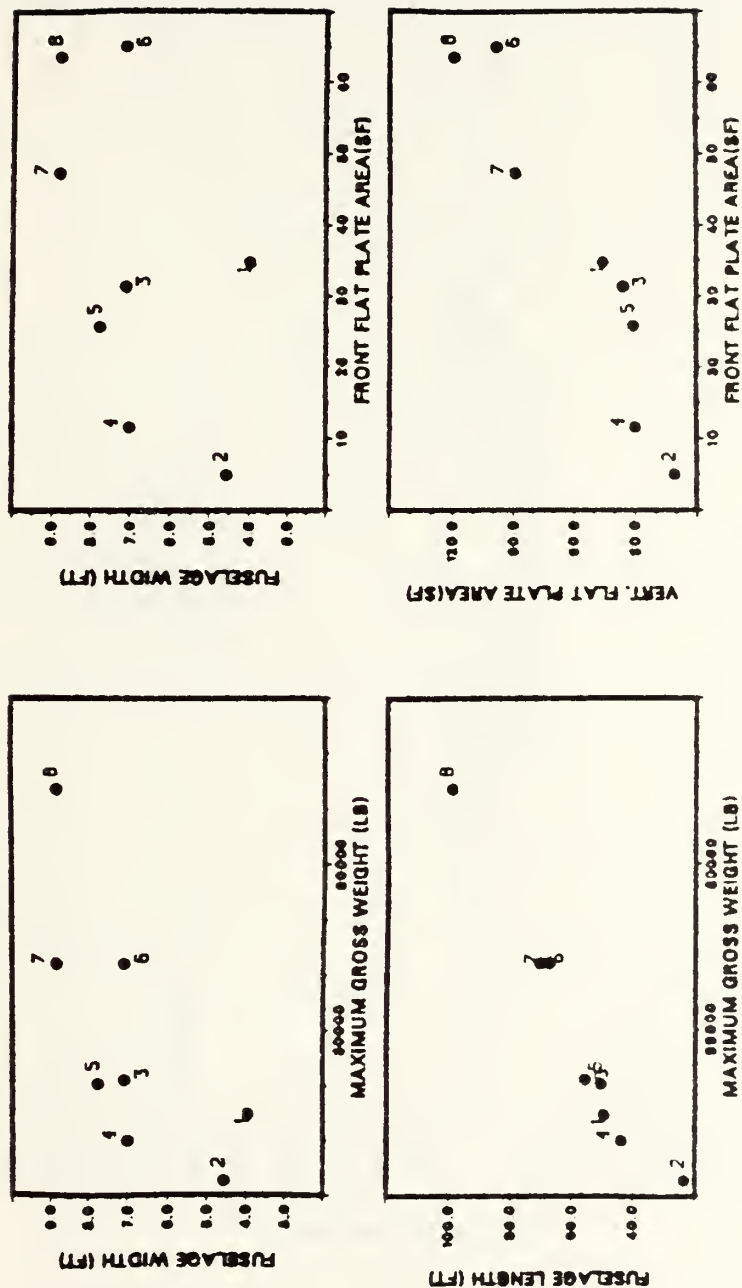


Figure 3.9. Four Plot Option

POWER VS. VELOCITY AT ALTITUDE

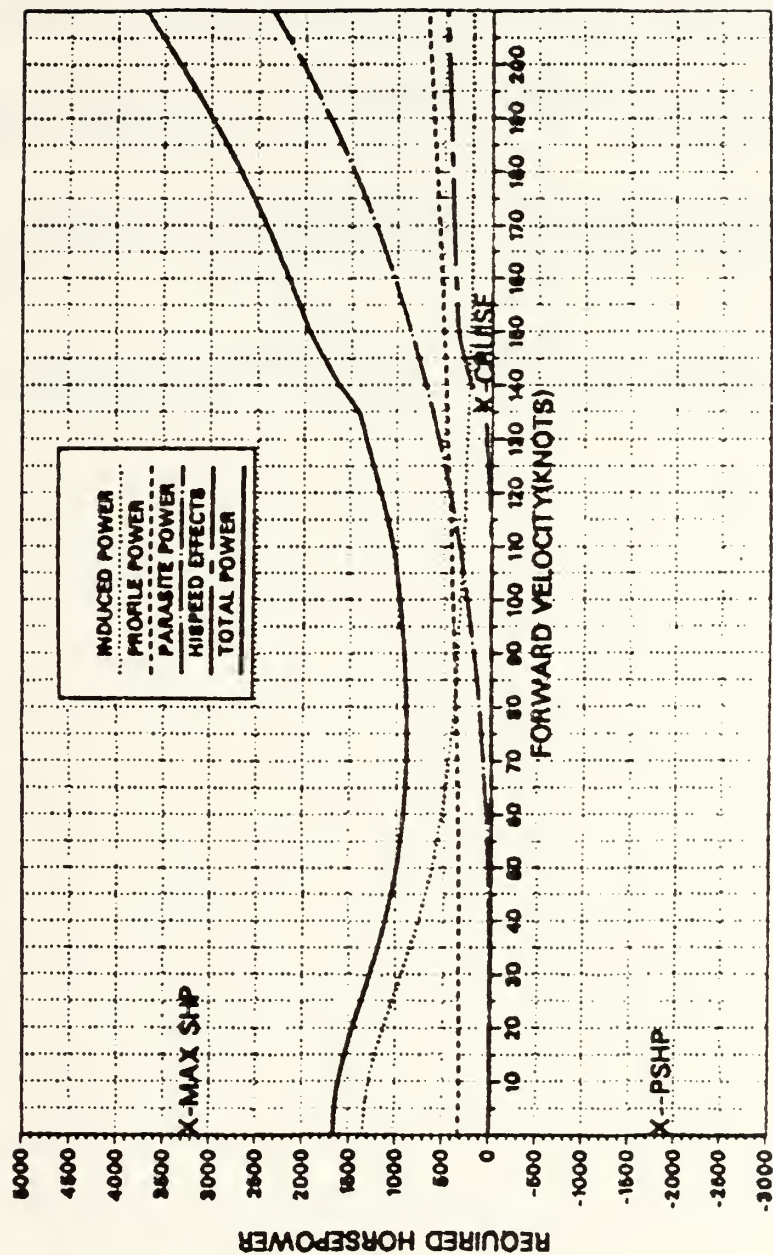


Figure 3.10. Sample Total Power Curve

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